

Implementing an Ultralow-Power Keypad Interface With the MSP430

Mike Mitchell

MSP430

ABSTRACT

Often in applications with keypads, the condition can occur where a key can be held or stuck down, causing excess current consumption and reducing the battery life of a battery-operated product. This application report shows a solution. The keypad interface in this report, based on the MSP430, draws 0.1 μ A while waiting for a key press, is completely interrupt driven, requiring no polling, and consumes a maximum of only 2 μ A at 3 V if all keys are pressed and held simultaneously.

Introduction

The keypad interface described in this report (shown schematically in Figure 1) is based on the MSP430F12x device. Its beneficial features include:

- 100 nA typical current consumption while waiting for key press
- 2 µA maximum current consumption if all keys are held simultaneously
- No polling required
- No crystal required
- Minimum external components
- Suitable for any MSP430 device

Implementation

The rows of the keypad are connected to port pins P3.0 - P3.3. The columns are connected to pins P1.0 - P1.2. Connecting the rows to port 3 pins, instead of port 1 pins, leaves the other port 1 pins for other interrupt sources, because the P1 pins have interrupt capability, but the P3 pins do not.

In normal mode, while the circuit is awaiting a key press (wait-for-press mode), the rows are driven high, and the P1.x column pins are configured as inputs, with interrupts enabled and set to interrupt on a rising edge. The 4.7 M Ω pulldown resistors hold the inputs low in this state. The MSP430 is then put into low-power mode 4, where the MSP430 current consumption is about 100 nA. This state is maintained indefinitely until a key is pressed. The circuit is completely interrupt-driven with no need for polling.

Note: Patent Pending

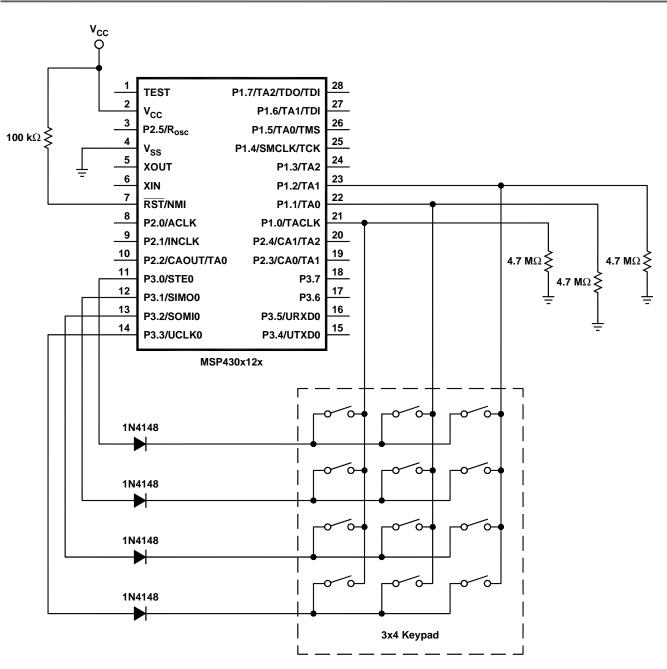


Figure 1. Keypad Schematic Diagram

When a key is pressed, the column associated with that key gets a rising edge, waking the MSP430. At that point, Timer_A is configured to perform a debounce delay of about 40 ms. The timer for the delay uses the internal digitally controlled oscillator (DCO) of the MSP430 – an RC-type oscillator. The DCO is subject to tolerances, so a debounce delay was chosen to give a worst-case-minimum delay of 25 ms. That translates to a worst-case-maximum delay of about 86 ms and a typical delay of about 40 ms. This is a useable range for keypad debounce.

After a key has been pressed, the MSP430 goes into a wait-for-release mode in which it drives high only the necessary row for the key being pressed (other rows are driven low). It reconfigures the P1.x I/O lines to interrupt on a falling edge, and it goes back into low power mode 4, waiting for the release of the key. Again, there is no polling necessary at this point. The detection of the key release is completely interrupt driven allowing the microcontroller to stay asleep while the key is held, thus reducing current consumption. Once the key is released, the debounce delay is again executed. After the debounce delay, the keypad is scanned again to determine if any other keys are being held. If so, the wait-for-release mode continues, waiting for all keys to be released. When all keys are released the MSP430 goes back to the wait-for-press mode again.

During the wait-for-release mode, only one row of the keypad is driven high, therefore limiting the maximum amount of current consumption to the condition where all three keys on a single row are pressed and held. For a 3-V system, that equates to about 2 μ A. Any other key press does not result in increased current consumption because the corresponding row is not driven high.

In this 3×4 keypad example, the rows are driven rather than the columns to limit the maximum current consumption by the circuit when all keys are pressed and held simultaneously. Had the columns been driven instead, the rows would have had the pulldown resistors, therefore increasing the number of paths to ground when all the keys are held and increasing the possible current consumption.

The Software

The software flow is shown in Figure 2. The complete code listing follows. The complete code is also available for download through the same link as this report.

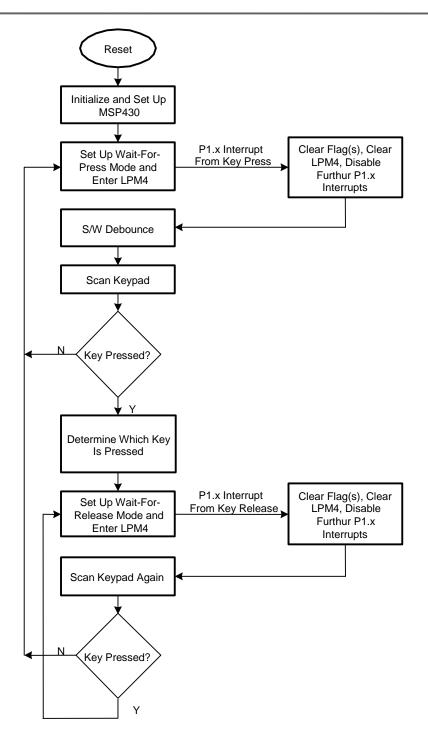


Figure 2. Software Flow

; THIS PROGRAM IS PROVIDED "AS IS". TI MAKES NO WARRANTIES OR ; REPRESENTATIONS, EITHER EXPRESS, IMPLIED OR STATUTORY, ; INCLUDING ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS ; FOR A PARTICULAR PURPOSE, LACK OF VIRUSES, ACCURACY OR ; COMPLETENESS OF RESPONSES, RESULTS AND LACK OF NEGLIGENCE. ; TI DISCLAIMS ANY WARRANTY OF TITLE, QUIET ENJOYMENT, QUIET ; POSSESSION, AND NON-INFRINGEMENT OF ANY THIRD PARTY ; INTELLECTUAL PROPERTY RIGHTS WITH REGARD TO THE PROGRAM OR ; YOUR USE OF THE PROGRAM. ; IN NO EVENT SHALL TI BE LIABLE FOR ANY SPECIAL, INCIDENTAL, ; CONSEQUENTIAL OR INDIRECT DAMAGES, HOWEVER CAUSED, ON ANY ; THEORY OF LIABILITY AND WHETHER OR NOT TI HAS BEEN ADVISED ; OF THE POSSIBILITY OF SUCH DAMAGES, ARISING IN ANY WAY OUT ; OF THIS AGREEMENT, THE PROGRAM, OR YOUR USE OF THE PROGRAM. ; EXCLUDED DAMAGES INCLUDE, BUT ARE NOT LIMITED TO, COST OF ; REMOVAL OR REINSTALLATION, COMPUTER TIME, LABOR COSTS, LOSS ; OF GOODWILL, LOSS OF PROFITS, LOSS OF SAVINGS, OR LOSS OF ; USE OR INTERRUPTION OF BUSINESS. IN NO EVENT WILL TI'S ; AGGREGATE LIABILITY UNDER THIS AGREEMENT OR ARISING OUT OF ; YOUR USE OF THE PROGRAM EXCEED FIVE HUNDRED DOLLARS ; (U.S.\$500). ; Unless otherwise stated, the Program written and copyrighted ; by Texas Instruments is distributed as "freeware". You may, ; only under TI's copyright in the Program, use and modify the ; Program without any charge or restriction. You may ; distribute to third parties, provided that you transfer a ; copy of this license to the third party and the third party ; agrees to these terms by its first use of the Program. You ; must reproduce the copyright notice and any other legend of ; ownership on each copy or partial copy, of the Program. ; You acknowledge and agree that the Program contains ; copyrighted material, trade secrets and other TI proprietary ; information and is protected by copyright laws, ; international copyright treaties, and trade secret laws, as ; well as other intellectual property laws. To protect TI's ; rights in the Program, you agree not to decompile, reverse ; engineer, disassemble or otherwise translate any object code ; versions of the Program to a human-readable form. You agree ; that in no event will you alter, remove or destroy any ; copyright notice included in the Program. TI reserves all ; rights not specifically granted under this license. Except ; as specifically provided herein, nothing in this agreement ; shall be construed as conferring by implication, estoppel, ; or otherwise, upon you, any license or other right under any ; TI patents, copyrights or trade secrets. ; You may not use the Program in non-TI devices. #include "msp430x12x.h" ; Ultralow-Power Keypad Interface ; Description: This program implements and ultralow-power keypad interface ; on the MSP430F12x. The circuit consumes .1uA in normal mode while waiting ; for a key press. After a key press, a s/w debounce is performed and the ; uC then waits for the key to be released. The ciruict consumes a maximum ; of 2uA in the even the keys are accidentally pressed and held. The circuit



; is completely interrupt driven, requires no polling, and requires no external crystal. ; ; ; ; Mike Mitchell
; MSP430 Applications ; Texas Instruments, Inc ; January, 2002 RSEG CSTACK ; System stack DS 0 RSEG UDATAO ; RAM Locations EQU 01h NoKey EQU 02h NoMatch Error_Flags DS 1 ; Error Flags ; xxxx xxxx ; ||-- No Key being depressed ; ----- No key match found ; RSEG CODE ; Program code mov #SFE(CSTACK),SP Reset ; Initialize stackpointer SetupWDT SetupWDT mov #WDTPW+WDTHOLD,&WDTCTL ; Stop WDT SetupPorts mov.b #0F8h,&P1DIR ; Unused P1.x as Outputs mov.b #0FFh,&P2DIR
mov.b #0FFh,&P3DIR ; Unused P2.x as outputs ; All P3.x as outputs eint ; Enable Interrupts ; Set Rsel=0, leave DCO=3 mov.b #0,&BCSCTL1 SetupDCO ; This gives nom MCLK of ; 130KHz at 3V, 25C. Mainloop call #Set_For_Press ; Setup to wait for key press bis #LPM4,SR call #Debounce call #KeyScan ; Wait for key press ; Call debounce delay call #KeyScan ; Scan Keypad bit.b #NoKey,Error_Flags ; Test if no key was depressed jnz Mainloop ; False interrupt, no key pressed call #KeyLookup ; Lookup Key value call #Wait_For_Release ; Wait for key(s) to be released ; False interrupt, no key pressed jmp Mainloop _____ Set_For_Press ; Setup to wait for key press ;_____ bis.b #BIT0+BIT1+BIT2+BIT3,&P3OUT ; Enable keypad bic.b #BIT0+BIT1+BIT2,&P1IES ; L-to-H interrupts clr.b &P1IFG ; Clear any pending flags mov.b #BIT0+BIT1+BIT2,&P1IE ; Enable interrupts clr.b Error_Flags ; Clear error flags ret

		Delay Routine	
SetupTA		#TASSEL1+TACLR,&TACTL	
	mov	#CCIE,&TACCTL0	; Enable CCR0 interrupt
	mov	#5125,&TACCR0	; Value for typ delay of ~40mS
	bis	#MC0,&TACTL	; Start TA in up mode
		#LPM0,SR	; Sleep during debounce delay
	ret		; Return
	; Keypad	Routine	
-			
#define	KeyMask LoopCount	R14	
#define	KeyHex	R13	
#define	KeyVal	R5	
	mov	#1,KeyMask	; Initialize scan mask
	mov	#4,LoopCount	; Initialize loop counter
	clr	KeyHex	; Clear register
	bic.b	#07h,&P1OUT	; Clear column bits in P10UT req
Scan 1	bic.b	-	; Stop driving rows
SCall_1	bis.b		; Set column pins to output and low
	bic.b	#07h,&P1OUT	; To bleed off charge and avoid ; erroneous reads
	het er he		
	bic.b		; Set column pins back to input
	Mov.b	KeyMask, &P3OUT	; Drive row
	bit.b		; Test if any key pressed
	jz	Scan_2	; No key pressed
	bis.b	KeyMask,KeyHex	; If yes, set bit for row
	mov.b	&P1IN,R12	; Read column inputs
	and.b	#07h,R12	; Clear unused bits
	rla.b	R12	i
	rla.b	R12	; Rotate column bit
	rla.b	R12	;
	rla.b	R12	;
	bis.b	R12,KeyHex	; Set column bit in KeyHex
Scan_2	rla.b	KeyMask	; Rotate mask
—	dec	LoopCount	; Decrement counter
	jnz	Scan_1	; Continue scanning if not done
; Check t	o see if an	v kev is being pressed.	If not, set flag and return.
	tst.b	KeyHex	; Test KeyHex
	jnz	EndScan	; If not 0 return
	bis.b	#NoKey,Error_Flags	
EndScan	bis.b	#0Fh,&P3OUT	; Drive rows again
	ret		
		look-up to determine wh	nat key was pressed.
;			
	mov	#10,KeyVal	; Initial key value
LookLoop	cmp.b	Key_Tab(R5),KeyHex	
	jeq	EndLU	; If equal end look-up
	dec	KeyVal	; decrement pointer/counter
	jnz	LookLoop	; Continue until find key or
			; count to zero.

TEXAS INSTRUMENTS

; return error condition bis.b #NoMatch,Error_Flags ; Set Error Flag ret ; Return EndLU ; Done with Key look-up - found key successfully. KeyVal ; Adjust because using same dec ; register for key counter ; and table pointer ; --> The key that was pressed is now in R5. The applicaion ; can now move it for furthur handling, display, etc. ; This example doesn't actually do anything with the key information. ret ;------Wait_For_Release ; Setup to wait for key release ;------; Isolate one row that is in use #1,R11 ; row counter #0Fh,KeyHex ; And off column info in KeyHex KeyHex ; Rotate row info through C proceed ; Looking for a '1' mov.b L\$1 and.b rrc proceed R11 jc rla ; Shift to next bit and L\$1 ; continue looking jmp ; Invert inv.b R11 and #0Fh,R11 bic.b R11,&P30UT proceed ; Clear upper bits ; Turn off all but one row ; Setup for interrupt on key release bis.b #07h,&P1DIR ; Set column pins to output and low ; To bleed off charge and avoid bic.b #07h,&P1OUT ; erroneous reads ; Set column pins back to input bic.b #07H,&P1DIR bis.b #07h,&P1IES clr.b &P1IFG ; H-L Interrupts ; Clear any pending flags ; Enable Interrupts #UPM4,SR ; Sleep waiting for release #UPM4,SR ; Sleep waiting for release #KeyScan ; Soor ; #NoKey Free bis.b #LPM4,SR bis Call call bit.b #NoKey,Error_Flags ; Test if any key pressed ; If so, repeat jz Wait_For_Release End_Wait bic.b #NoKey,Error_Flags ; Clear flag ret ; Return P1ISR ; P1.x Interrupt service Routine bic#LPM4,0(SP); Return activeclr.b&P1IFG; Clear interrupt flagclr.b&P1IE; Disable furthur P1 interrupts reti CCR0_ISR ; CCR0 Interrupt Service Routine ;----bic #LPM0,0(SP) ; Return Active mov #TACLR, &TACTL ; Stop and clear TA clr &TACCTL0 ; Clear CCTL0 register reti ;------Key_Tab ; Key look-up table

DB	00h	; Dummy value. Allows use of same register for ; both table pointer and key counter
DB	028h	; '0' key
DB	011h	; '1' key
DB	021h	; '2' key
DB	041h	; '3' key
DB	012h	; '4' key
DB	022h	; '5' key
DB	042h	; '6' key
DB	014h	; '7' key
DB	024h	; '8' key
DB	044h	; '9' key
COMMON	INTVE	C ; Interrupt vectors
0PC	סדפדי	
		_VECTOR
		A0_VECTOR
		—
ORG	_	VECTOR
	DB DB DB DB DB DB DB DB COMMON ORG DW ORG DW	DB 028h DB 011h DB 021h DB 041h DB 012h DB 022h DB 042h DB 042h DB 014h DB 024h DB 044h COMMON INTVECTOR ORG RESET DW Reset ORG TIMERA DW CCR0_D

TEXAS INSTRUMENTS

Г

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third–party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Mailing Address:

Texas Instruments Post Office Box 655303 Dallas, Texas 75265

Copyright © 2003, Texas Instruments Incorporated