

ECSE 425 - Topic 4

**Advanced Pipelining:
Instruction Level Parallelism
and Its Exploitation**

(Chapter 2 and Appendix G)

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Instruction Level Parallelism

- Pipelining overlaps the execution of instructions
- This potential overlap among instructions is called Instruction Level Parallelism (ILP)
- In this topic we look at techniques to increase the amount of ILP
- First, we will look at what limits ILP and how much we can actually expect to extract
- Then we will exploit the available ILP
- Two main techniques:
 - Hardware (market winner: Intel Pentium series)
 - Software (special niche markets, Intel Itanium, DSPs)

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Recall from Pipelining Review

- **Pipeline CPI = Ideal pipeline CPI + Structural Stalls + Data Hazard Stalls + Control Stalls**
 - **Ideal pipeline CPI**: measure of the maximum performance attainable by the implementation
 - **Structural hazards**: HW cannot support this combination of instructions
 - **Data hazards**: Instruction depends on result of prior instruction still in the pipeline
 - **Control hazards**: Caused by delay between the fetching of instructions and decisions about changes in control flow (branches and jumps)

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Technique	Reduces
Forwarding	Potential data hazard stalls
Delayed branches and simple branch scheduling	Control hazard stalls
Dynamic scheduling	Data hazard stalls
Branch prediction	Control stalls
Issuing multiple instructions per cycle	Ideal CPI
Speculation	Data and control stalls
Dynamic memory disambiguation	Data hazard stalls involving memory
Loop unrolling	Control hazard stalls
Basic compiler pipeline scheduling	Data hazard stalls
Compiler dependence analysis and software pipelining	Ideal CPI and data hazard stalls

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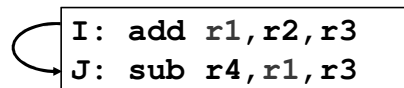
Instruction-Level Parallelism (ILP)

- **Basic Block (BB) ILP is quite small**
 - BB: a straight-line code sequence with no branches in except to the entry and no branches out except at the exit
 - average dynamic branch frequency 15% to 25%
 - => 4 to 7 instructions execute between a pair of branches
 - Plus instructions in BB likely to depend on each other
- **To obtain substantial performance enhancements, we must exploit ILP across multiple basic blocks**
- **Simplest: loop-level parallelism to exploit parallelism among iterations of a loop**
 - Vector is one way
 - If not vector, then either dynamic via branch prediction or static via loop unrolling by compiler

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Data Dependence and Hazards

- Instr_J is data dependent on Instr_I
 Instr_J tries to read operand before Instr_I writes it



- or Instr_J is data dependent on Instr_K which is dependent on Instr_I
- Caused by a "True Dependence" (compiler term)
- If true dependence caused a hazard in the pipeline, called a Read After Write (RAW) hazard

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Data Dependence and Hazards

- Dependences are a property of programs
- Presence of dependence indicates potential for a hazard, but actual hazard and length of any stall is a property of the pipeline
- Importance of the data dependencies
 - 1) indicates the possibility of a hazard
 - 2) determines order in which results must be calculated
 - 3) sets an upper bound on how much parallelism can possibly be exploited
- Today looking at HW schemes to avoid hazard

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Name Dependence #1: Anti-dependence

- Name dependence: when 2 instructions use same register or memory location, called a name, but no flow of data between the instructions associated with that name; 2 versions of name dependence
- Instr_J writes operand *before* Instr_I reads it

```
I: sub r4, r1, r3
J: add r1, r2, r3
K: mul r6, r1, r7
```

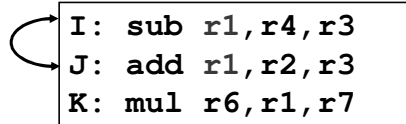
Called an "anti-dependence" by compiler writers.
This results from reuse of the name "r1"

- If anti-dependence caused a hazard in the pipeline, called a Write After Read (WAR) hazard

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Name Dependence #2: Output dependence

- Instr_J writes operand *before* Instr_I writes it.



```
I: sub r1, r4, r3
J: add r1, r2, r3
K: mul r6, r1, r7
```

- Called an "output dependence" by compiler writers
This also results from the reuse of name "r1"
- If anti-dependence caused a hazard in the pipeline,
called a Write After Write (WAW) hazard

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ILP and Data Hazards

- HW/SW must preserve program order:
order instructions would execute in if executed sequentially 1 at a time as determined by original source program
- HW/SW goal: exploit parallelism by preserving program order only where it affects the outcome of the program
- Instructions involved in a name dependence can execute simultaneously if name used in instructions is changed so instructions do not conflict
 - Register renaming resolves name dependence for regs
 - Either by compiler or by HW

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Control Dependencies

- Every instruction is control dependent on some set of branches, and, in general, these control dependencies must be preserved to preserve program order

```
if p1 {  
    S1;  
};  
if p2 {  
    S2;  
}
```

- S1 is control dependent on p1, and S2 is control dependent on p2 but not on p1.

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Control Dependence Ignored

- Control dependence need not be preserved
 - willing to execute instructions that should not have been executed, thereby violating the control dependences, if can do so without affecting correctness of the program
- Instead, 2 properties critical to program correctness are exception behavior and data flow

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Exception Behavior

- Preserving exception behavior => any changes in instruction execution order must not change how exceptions are raised in program (=> no new exceptions)
- Example:
DADDU R2, R3, R4
BEQZ R2, L1
LW R1, 0 (R2)
L1:
• Problem with moving LW before BEQZ?

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Data Flow

- Data flow: actual flow of data values among instructions that produce results and those that consume them
 - branches make flow dynamic, determine which instruction is supplier of data
- Example:
DADDU R1, R2, R3
BEQZ R4, L
DSUBU R1, R5, R6
L: ...
OR R7, R1, R8
• OR depends on DADDU or DSUBU?
Must preserve data flow on execution

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Basic Compiler Techniques for Exposing ILP

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Basic Compiler Scheduling

- **The idea: keep the pipeline full**
 - Avoid stalls due to hazards
- **Scheduling**
 - find a sequence of instructions that can be overlapped in the pipeline
- **We will look at scheduling in the compiler. The hardware then executes the scheduled code in-order**
- **How do we achieve our goal of keeping the pipeline full ?**

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Basic Compiler Scheduling

- A dependent instruction must be separated from the source instruction by a distance in clock cycles equal to the pipeline latency of the source instruction
- For example, in a pipeline with forwarding
 - latency of the EX stage (ALU) is 0.
 - The data memory latency is 1
- A compiler's ability to perform this scheduling depends on:
 - The amount of ILP in the program
 - The latencies of the functional units

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Basic Compiler Scheduling

- Assume the classic 5-stage integer pipeline
- Integer ALU latency is 0 CC
- Integer load latency is 1 CC
- Branch delay is 1 CC
- Fully pipelined FUs (assume no structural hazards)
- Assume the following FP latencies (averages):

Producer	Consumer	Latency (CCs)
FP ALU op	Another FP ALU op	3
FP ALU op	Store double	2
Load double	FP ALU op	1
Load double	Store double	0

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Loop Example

- Adding a scalar to a vector (loop is parallel since the body of each iteration is independent)

```
for (i = 1000; i > 0; i=i-1)
    x[i] = x[i] + s;
```

```
Loop: L.D    F0,0(R1)    ;F0=array element
      ADD.D  F4,F0,F2    ;add scalar from F2
      S.D    F4,0(R1)    ;store result
      DADDUI R1,R1,#-8   ;decrement pointer 8 bytes
      BNE   R1,R2,Loop  ;branch R1!=R2
```

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Loop Example

- Ignore delayed branches
- Unscheduled code: 9 clock cycles

```
1 Loop:    L.D    F0,0(R1)
2          stall
3          ADD.D  F4,F0,F2
4          stall
5          stall
6          S.D    F4,0(R1)
7          DADDUI R1,R1,#-8
8          stall
9          BNE   R1,R2,Loop
```

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Loop Example

- Scheduled code: 7 cycles
- Not trivial: S.D. depends on DAADUI. Swap them but change address

```
1 Loop:    L.D      F0,0(R1)
2          DADDUI   R1,R1,#-8
3          ADD.D    F4,F0,F2
4          stall
5          stall
6          S.D      F4,8(R1) ; altered
7          BNE     R1,R2,Loop ; delayed branch
```

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Loop Example

- 1 branch delay slot
- Unscheduled code: 10 clock cycles

```
1 Loop:    L.D      F0,0(R1)
2          stall
3          ADD.D    F4,F0,F2
4          stall
5          stall
6          S.D      F4,0(R1)
7          DADDUI   R1,R1,#-8
8          stall
9          BNE     R1,R2,Loop
10         stall
```

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Loop Example

- **Scheduled code: 6 cycles**
- **Problem: only doing work on the array element in 3/6 cycles. Other 3 are for loop overhead**

```
1 Loop:      L.D      F0,0(R1)
2            DADDUI   R1,R1,#-8
3            ADD.D    F4,F0,F2
4            stall
5            BNE     R1,R2,Loop ; delayed branch
6            S.D     F4,8(R1)  ; altered
```

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Loop Unrolling

- ***Unroll* the loop**
 - Replicate the body of the loop many times
 - Adjust the loop termination code
- **Eliminating the branch allows instructions from different iterations to be scheduled together**
 - In this case we can eliminate the data stall

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Unroll Loop Four Times (straightforward way)

```

1 Loop: L.D   F0, 0(R1)
2     ADD.D  F4, F0, F2
3     S.D   F4, 0(R1)      ; drop DADDUI & BNE
4     L.D   F6, -8(R1)
5     ADD.D  F8, F6, F2
6     S.D   F8, -8(R1)    ; drop DADDUI & BNE
7     L.D   F10, -16(R1)
8     ADD.D  F12, F10, F2
9     S.D   F12, -16(R1) ; drop DADDUI & BNE
10    L.D   F14, -24(R1)
11    ADD.D  F16, F14, F2
12    S.D   F16, -24(R1)
13    DADDUI R1, R1, #-32 ; alter to 4*8
14    BNE   R1, R2, LOOP

```

Annotations:

- 1 cycle stall (between lines 1 and 2)
- 2 cycles stall (between lines 2 and 3)
- 1 cycle stall (between lines 13 and 14)

Rewrite loop to minimize stalls?

14 + 4x(1+2) + 2 = 28 clock cycles, or 7 per iteration
 Assumes R1 is multiple of 32 (# loops a multiple of 4)

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Textbook example

- The textbook on page 77-78 does the same example, but without branch delay
- 27 clock cycles (6.75 cycles per iteration)
- Work through it to understand the difference of one clock cycle

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Unrolled Loop Detail

- Do not usually know upper bound of loop
- Suppose it is n , and we would like to unroll the loop to make k copies of the body
- Instead of a single unrolled loop, we generate a pair of consecutive loops:
 - 1st executes $(n \bmod k)$ times and has a body that is the original loop
 - 2nd is the unrolled body surrounded by an outer loop that iterates (n/k) times
 - For large values of n , most of the execution time will be spent in the unrolled loop

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Unrolled Loop That Minimizes Stalls

```
1 Loop: L.D    F0, 0(R1)
2      L.D    F6, -8(R1)
3      L.D    F10, -16(R1)
4      L.D    F14, -24(R1)
5      ADD.D  F4, F0, F2
6      ADD.D  F8, F6, F2
7      ADD.D  F12, F10, F2
8      ADD.D  F16, F14, F2
9      S.D    F4, 0(R1)
10     S.D    F8, -8(R1)
11     DADDUI R1, R1, #-32
12     S.D    F12, 16(R1)
13     BNE   R1, R2, LOOP
14     S.D    F16, 8(R1) ; 8-32 = -24
```

- What assumptions made when moved code?

- OK to move store past DADDUI even though changes register
- OK to move loads before stores: get right data?
- When is it safe for compiler to do such changes?

*14 clock cycles, or 3.5 per iteration
(textbook without branch delay has a
different schedule but also is able to do it
in 14 cycles - work through it)*

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Compiler Perspectives on Code Movement

- Compiler concerned about dependencies in program
- Whether or not a HW hazard depends on pipeline
- Try to schedule to avoid hazards that cause performance losses
- (True) Data dependencies (RAW if a hazard for HW)
 - Instruction i produces a result used by instruction j, or
 - Instruction j is data dependent on instruction k, and instruction k is data dependent on instruction i.
- If dependent, can't execute in parallel
- Easy to determine for registers (fixed names)
- Hard for memory ("memory disambiguation" problem):
 - Does 100(R4) = 20(R6)?
 - From different loop iterations, does 20(R6) = 20(R6)?

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Where are the name dependencies?

```
1 Loop: L.D    F0, 0(R1)
2      ADD.D  F4, F0, F2
3      S.D    F4, 0(R1)      ;drop DADDUI & BNE
4      L.D    F0, -8(R1)
5      ADD.D  F4, F0, F2
6      S.D    F4, -8(R1)    ;drop DADDUI & BNE
7      L.D    F0, -16(R1)
8      ADD.D  F4, F0, F2
9      S.D    F4, -16(R1)   ;drop DADDUI & BNE
10     L.D    F0, -24(R1)
11     ADD.D  F4, F0, F2
12     S.D    F4, -24(R1)
13     DADDUI R1, R1, #-32   ;alter to 4*8
14     BNE   R1, R2, LOOP
15     NOP
```

How can remove them?

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Where are the name dependencies?

```
1 Loop:L.D    F0,0(R1)
2      ADD.D  F4,F0,F2
3      S.D    F4,0(R1)      ;drop DADDUI & BNE
4      L.D    F6,-8(R1)
5      ADD.D  F8,F6,F2
6      S.D    F8,-8(R1)    ;drop DADDUI & BNE
7      L.D    F10,-16(R1)
8      ADD.D  F12,F10,F2
9      S.D    F12,-16(R1)  ;drop DADDUI & BNE
10     L.D    F14,-24(R1)
11     ADD.D  F16,F14,F2
12     S.D    F16,-24(R1)
13     DADDUI R1,R1,#-32   ;alter to 4*8
14     BNE    R1,R2,LOOP
15     NOP
```

"register renaming"

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Compiler Perspectives on Code Movement

- Name dependencies are hard to discover for memory Accesses
 - Does $100(R4) = 20(R6)$?
 - From different loop iterations, does $20(R6) = 20(R6)$?
- Our example required compiler to know that if R1 doesn't change then:

$0(R1) \neq -8(R1) \neq -16(R1) \neq -24(R1)$

There were no dependencies between some loads and stores so they could be moved by each other

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Steps Compiler Performed to Unroll

- Check OK to move the S.D after DADDUI and BNEZ, and find amount to adjust S.D offset
- Determine unrolling the loop would be useful by finding that the loop iterations were independent
- Rename registers to avoid name dependencies
- Eliminate extra test and branch instructions and adjust the loop termination and iteration code
- Determine loads and stores in unrolled loop can be interchanged by observing that the loads and stores from different iterations are independent
 - requires analyzing memory addresses and finding that they do not refer to the same address.
- Schedule the code, preserving any dependences needed to yield same result as the original code

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Drawbacks

- Code length (an issue for embedded processors)
- Uses lots of registers
 - "Register pressure"
 - Could be a problem with aggressive unrolling and scheduling

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Reducing branch costs with Branch prediction

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Branch Prediction

- The fundamental problem:
 - There is a delay between the cycle which we find out if the instruction is a branch, what its target is, whether it is taken or not,.....and the cycle from which we need to fetch the next instruction.
- One way to get around this is to *guess* whether a branch is taken or not taken...if we are correct then there could potentially be no penalty.
- We suffer a penalty if the guess was wrong

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Looking Ahead...

- To lower the IDEAL CPI, we will consider machines that can **ISSUE** more than one instruction in a clock cycle...
 - "multiple issue" (Superscalar and VLIW)

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Case for Branch Prediction when Issue N instructions per clock cycle

1. Branches will arrive up to n times faster in an n -issue processor
2. Amdahl's Law \Rightarrow relative impact of the control stalls will be larger with the lower potential CPI in an n -issue processor

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Static Branch Prediction

- We saw this idea earlier
 - Delayed branches

```
LD      R1, 0(R2)
DSUBU  R1, R1, R3
BEQZ   R1, L
NOP
OR      R4, R5, R6
DADDU  R10, R4, R3
L:     DADDU  R7, R8, R9
```

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Static Branch Prediction Strategies

- **Predict-taken**
 - Midprediction rate = untaken branch frequency
 - SPEC: 34% misprediction (9% to 59%)
- **Predict based on branch direction**
 - E.g. predict forward-going branches as not taken and backwards-going branches as taken
- **Collect profile information by running the program a few times. Recompile with this profile information.**
 - Studies have showed that even when the data changes the profile is pretty accurate

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Static Branch Prediction

- **Static branch prediction is useful when:**
 1. Branch delays are exposed by architecture
 2. Assisting dynamic predictors (IA-64)
 3. Determining which code paths are more frequent (for code scheduling)

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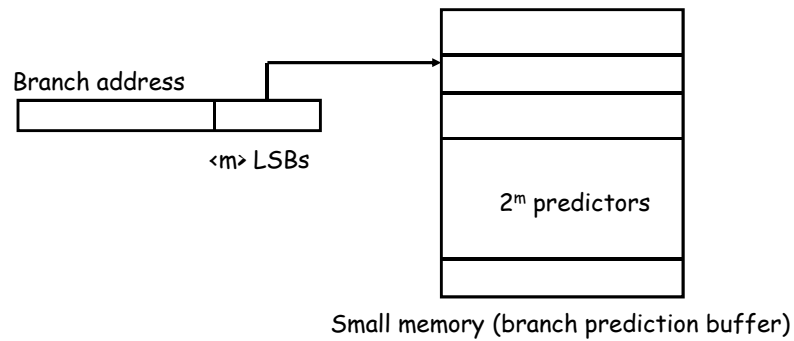
The case for dynamic branch prediction

- The performance of branch prediction rests on how accurate our predictions are.
- We have seen a compiler scheme for filling the branch delay (static branch prediction).
- Analyze each branch and try to fill the delay slot with an instruction from the branch target or the fall through.
- The problem is... it is very hard to predict the direction of branches in the compiler...we really need to consider the dynamic branch behaviour.

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Dynamic Branch Prediction

- **IDEA:** predict the outcome of a branch based on its past behaviour



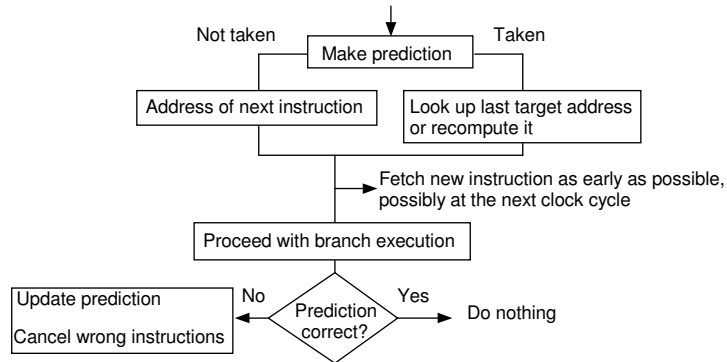
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7 Branch Prediction Schemes

1. 1-bit Branch-Prediction Buffer
2. 2-bit Branch-Prediction Buffer
3. Correlating Branch Prediction Buffer
4. Tournament Branch Predictor
5. Branch Target Buffer
6. Integrated Instruction Fetch Units
7. Return Address Predictors

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Dynamic Branch Prediction



Performance = $f(\text{accuracy, cost of misprediction})$

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1-bit Predictors

- **Branch History Table: Lower bits of PC address index table of 1-bit values**
 - Says whether or not branch taken last time
 - No address check (saves HW, but may not be right branch)
 - Adequate performance for numerical code with many loops
- **Problem: in a loop, 1-bit BHT will cause 2 mispredictions**
 - End of loop case, when it exits instead of looping as before
 - First time through loop on *next* time through code, when it predicts *exit* instead of looping
 - Only 80% accuracy even if loop 90% of the time

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Example

- Loop with 10 iterations. First 9 are taken and then the last is not.
- Mispredict 2 times for every 10 instructions
- 80% prediction accuracy
- (mispredict at twice the rate of branch not taken...should be able to at least match the taken branch frequency for highly regular loops)

...TTT N TTTTTTTTTT N TTT...

↑ ↑
mispredictions

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1-bit predictors

- Prediction is wrong whenever there is a transition in the branching pattern.
- Example
 - NTNTNT
 - 1-bit predictor is never correct ! (0%)
 - Tossing a coin (no prediction at all) gives 50%
- However, real code has bias
- A branch taken several times is likely to be taken again
- Solution: keep more "memory" than is possible by just one bit...try two bits

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2-bit predictors

- Count the number of 'taken' (not taken) outcomes
- Two taken (not taken) in a row → predict "taken" (not taken)
- A single not taken (taken) branch will not affect the prediction - there need to be two in a row to affect the prediction
- In general, with n prediction bits, it takes 2^{n-1} mispredictions before the predictor changes its mind

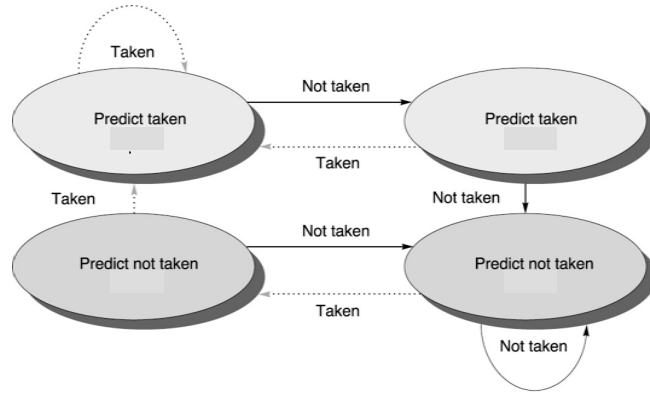
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Examples

- ...NNNNN TNTNTN TTTTTT...
- 50 % prediction accuracy
- ...TTTN TTTTTTTTTT N TTT...
- 90% prediction accuracy

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2-Bit Branch Prediction

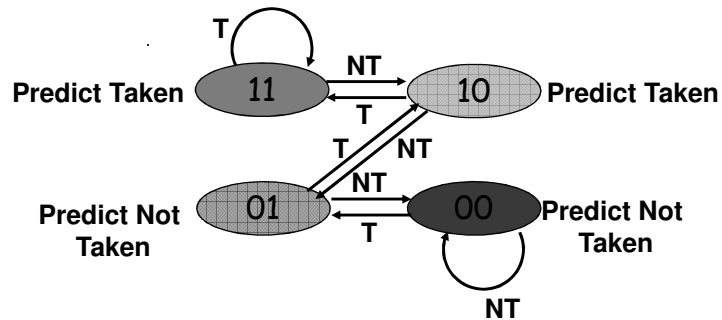


- A branch that strongly favours taken or not taken will be mispredicted less often than with a 1-bit predictor

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Counter Implementation



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Accuracy of 2-bit predictors

- 99-100% on heavy matrix code
- 80 - 90% on integer code (e.g. gcc)
- Statistics show virtually no gain in accuracy with more states and buffers of more than 1K entries.
- However, there are some cases where we can do better...

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Correlating Branch Predictors

- Why is the performance of integer code so low?
- We assumed that different branches' behaviour was not correlated..
- But, they often are...

```
If (a == 2)
```

```
  a = 0
```

```
If( b == 2)
```

```
  b = 0
```

```
If (a != b)
```

```
...
```

- A simple predictor that considers only one branch can't capture this behaviour

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Correlating Branch Predictors

- Idea: taken/not taken of recently executed branches is related to behavior of next branch (as well as the history of that branch behavior)
- Simple predictor: keep a history of 1 branch and each predictor is 1-bit (1,1)

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Example without Correlation

• E.g.

B1: If (d == 0)
d = 1

B2: If (d == 1)
...

Try a 1-bit predictor

	Branch	Pred	outcome	update
d=2	B1	N	N	N
	B2	N	N	N
d=0	B1	N	T	T
	B2	N	T	T
d=2	B1	T	N	N
	B2	T	N	N
d=0	B1	N	T	T
	B2	N	T	T

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Simple Correlating Predictor

Each branch has 2 1-bit predictors yielding four possibilities: (1,1) correlating branch predictor

Prediction bits	
Use this one if last branch not taken	Use this one if last branch taken
N	N
N	T
T	N
T	T

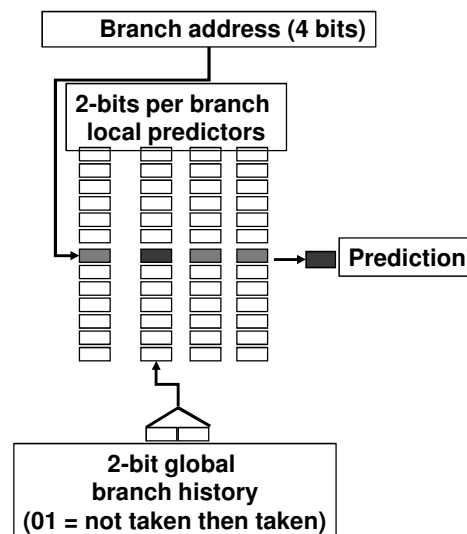
	Branch	Pred. Bits	Prediction	Outcome	Update
d=2	B1	NN	N	N	NN
	B2	NN	N	N	NN
d=0	B1	NN	N	T	TN
	B2	NN	N	T	NT
d=2	B1	TN	N	N	TN
	B2	NT	N	N	NT
d=0	B1	TN	T	T	TN
	B2	NT	T	T	NT

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Correlating Branches

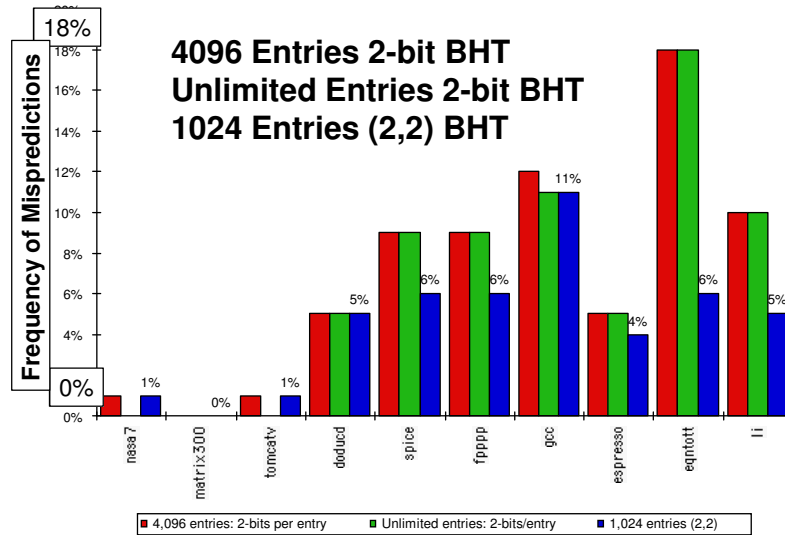
Behavior of recent branches selects between, say, 4 predictions of next branch, updating just that prediction

- (2,2) predictor: 2-bit global, 2-bit local
- General: (m,n) uses behaviour of the last m branches to choose from 2^m predictors each of which is an n-bit predictor



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Accuracy of Different Schemes



BHT Accuracy

- **Mispredict because either:**
 - Wrong guess for that branch
 - Got branch history of wrong branch when index the table
- **4096 entry table programs vary from 1% misprediction (nasa7, tomcatv) to 18% (eqntott), with spice at 9% and gcc at 12%**
- **For SPEC92, 4096 about as good as infinite table**

Tournament Predictors

- Motivation for correlating branch predictors is 2-bit predictor failed on important branches; by adding global information, performance improved
- Tournament predictors: use 2 predictors, 1 based on global information and 1 based on local information, and combine with a selector
- Hopes to select right predictor for right branch
- Pentium 4 and Power5 - 30K bits tournament predictors

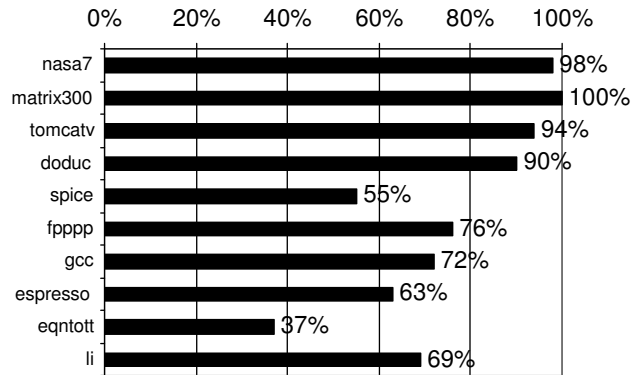
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Tournament Predictor in Alpha 21264

- 4K 2-bit counters to choose from among a global predictor and a local predictor
- Global predictor also has 4K entries and is indexed by the history of the last 12 branches; each entry in the global predictor is a standard 2-bit predictor
 - 12-bit pattern: ith bit 0 => ith prior branch not taken;
ith bit 1 => ith prior branch taken;
- Local predictor consists of a 2-level predictor:
 - Top level a local history table consisting of 1024 10-bit entries; each 10-bit entry corresponds to the most recent 10 branch outcomes for the entry. 10-bit history allows patterns 10 branches to be discovered and predicted.
 - Next level Selected entry from the local history table is used to index a table of 1K entries consisting a 3-bit saturating counters, which provide the local prediction
- Total size: $4K*2 + 4K*2 + 1K*10 + 1K*3 = 29K$ bits!
(~180,000 transistors)

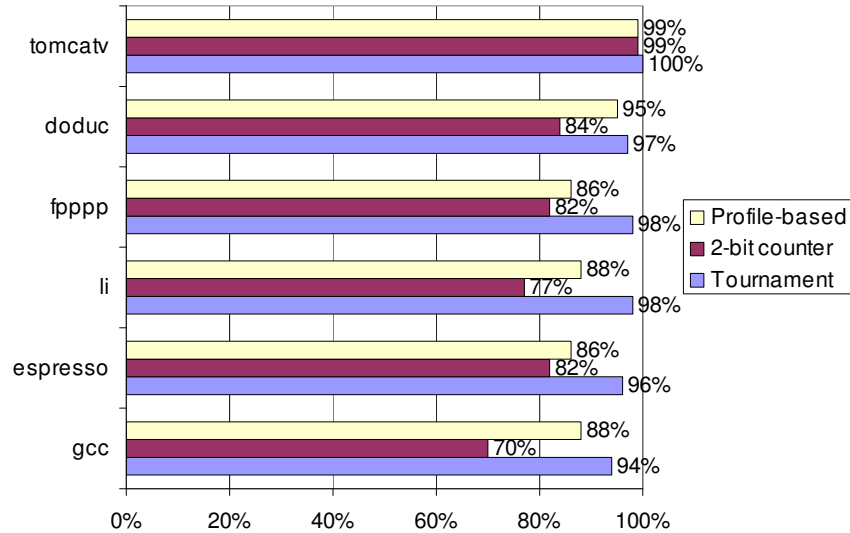
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% of predictions from local predictor in Tournament Prediction Scheme



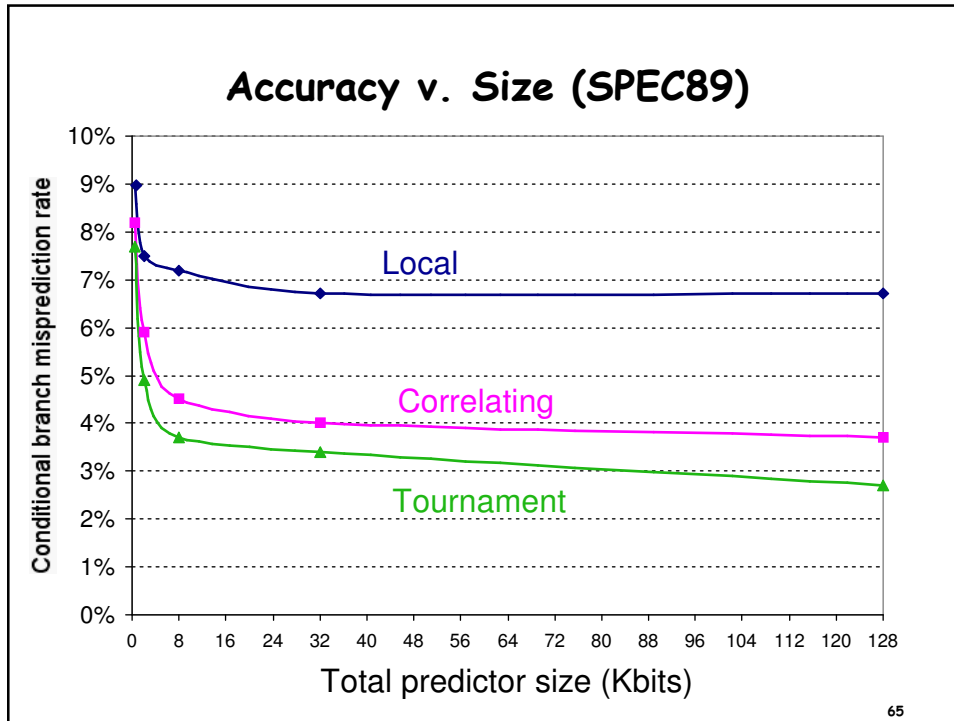
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Accuracy of Branch Prediction



- Profile: branch profile from last execution (static in that it is encoded in instruction, but profile)

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- ### Dynamic Branch Prediction Summary
- Prediction becoming important part of scalar execution
 - Branch History Table: 2 bits for loop accuracy
 - Correlation: Recently executed branches correlated with next branch.
 - Either different branches
 - Or different executions of same branches
 - Tournament Predictor: more resources to competitive solutions and pick between them
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Dynamic Scheduling

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Advantages of Dynamic Scheduling

- **Handles cases when dependences unknown at compile time**
 - (e.g., because they may involve a memory reference)
- **It simplifies the compiler**
- **Allows code that compiled for one pipeline to run efficiently on a different pipeline**
- **Hardware speculation, a technique with significant performance advantages, that builds on dynamic scheduling**

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HW Schemes: Instruction Parallelism

- **Key idea:** Allow instructions behind stall to proceed

```
DIVD  F0, F2, F4
ADDD  F10, F0, F8
SUBD  F12, F8, F14
```

- Enables out-of-order execution and allows out-of-order completion
- Will distinguish when an instruction *begins execution* and when it *completes execution*; between 2 times, the instruction is *in execution*
- In a dynamically scheduled pipeline, all instructions pass through issue stage in order (in-order issue)

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Dynamic Scheduling Step 1

- Simple pipeline had 1 stage to check both structural and data hazards: Instruction Decode (ID), also called Instruction Issue
- Split the ID pipe stage of simple 5-stage pipeline into 2 stages:
- *Issue—Decode* instructions, check for structural hazards
- *Read operands—Wait* until no data hazards, then read operands

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A Dynamic Algorithm: Tomasulo's Algorithm

- For IBM 360/91 (before caches!)
- Goal: High Performance without special compilers
- Small number of floating point registers (4 in 360) prevented interesting compiler scheduling of operations
 - This led Tomasulo to try to figure out how to get more effective registers — renaming in hardware!
- Why Study 1966 Computer?
- The descendants of this have flourished!
 - Alpha 21264, HP 8000, MIPS 10000, Pentium III, PowerPC 604, ...

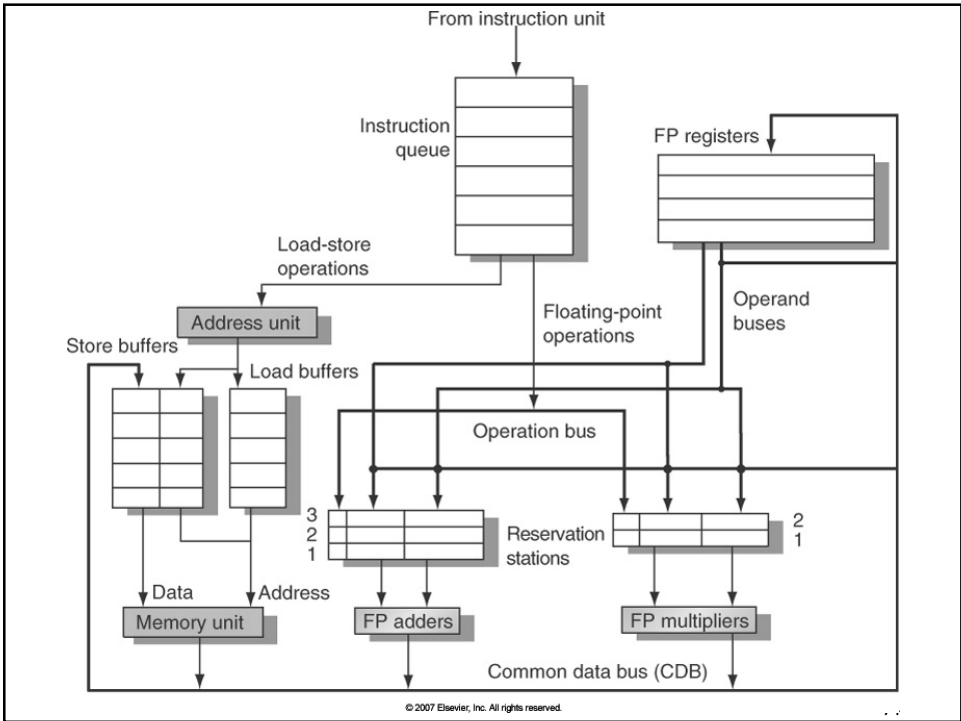
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Tomasulo Algorithm

- Control & buffers distributed with Function Units (FU)
 - FU buffers called "reservation stations"; have pending operands
- Registers in instructions replaced by values or pointers to reservation stations(RS); called register renaming ;
 - avoids WAR, WAW hazards
 - More reservation stations than registers, so can do optimizations compilers can't
- Results to FU from RS, not through registers, over Common Data Bus that broadcasts results to all FUs
- Load and Stores treated as FUs with RSs as well
- Integer instructions can go past branches, allowing FP ops beyond basic block in FP queue

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Tomasulo Organization



Dynamic Scheduling

- **Handles cases when dependences unknown at compile time**
 - (e.g., because they may involve a memory reference)
- **It simplifies the compiler**
- **Allows code that compiled for one pipeline to run efficiently on a different pipeline**
- **Hardware speculation, a technique with significant performance advantages, that builds on dynamic scheduling**

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Reservation Station Components

Op: Operation to perform in the unit (e.g., + or -)

V_j, V_k: Value of Source operands

- Store buffers has V field, result to be stored

Q_j, Q_k: Reservation stations producing source registers (value to be written)

- Note: Q_j, Q_k=0 => ready
- Store buffers only have Q_i for RS producing result

Busy: Indicates reservation station or FU is busy

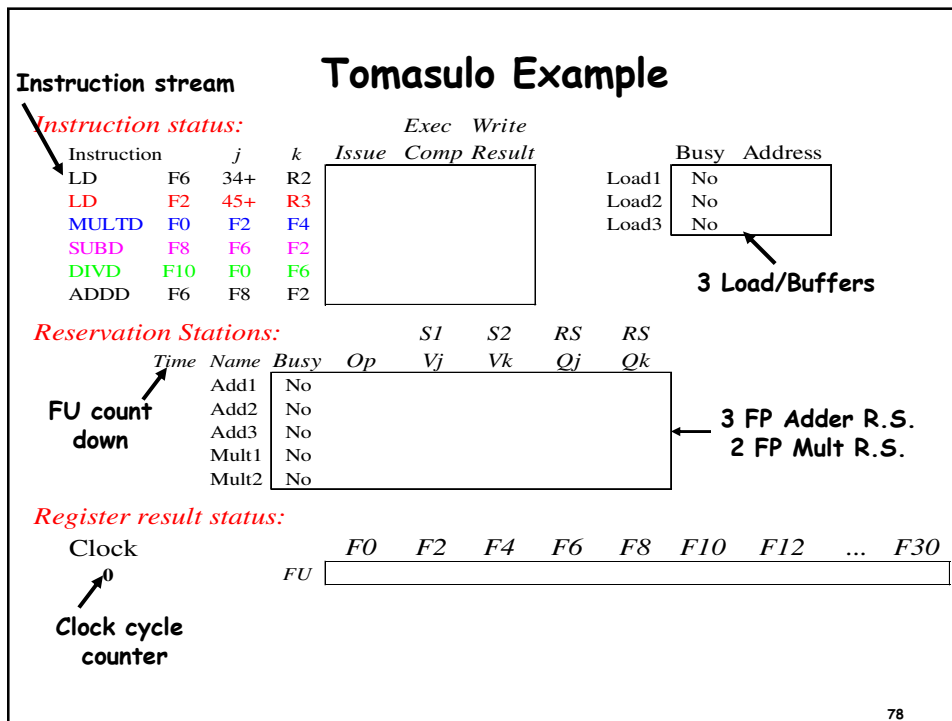
Register result status—Indicates which functional unit will write each register, if one exists. Blank when no pending instructions that will write that register.

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Three Stages of Tomasulo Algorithm

1. Issue—get instruction from FP Op Queue
If reservation station free (no structural hazard), control issues instr & sends operands (renames registers).
 2. Execute—operate on operands (EX)
When both operands ready then execute;
if not ready, watch Common Data Bus for result
 3. Write result—finish execution (WB)
Write on Common Data Bus to all awaiting units;
mark reservation station available
- Normal data bus: data + destination ("go to" bus)
 - Common data bus: data + source ("come from" bus)
 - 64 bits of data + 4 bits of Functional Unit source address
 - Write if matches expected Functional Unit (produces result)
 - Does the broadcast
 - Example speed:
3 clocks for FI .pt. +,-; 10 for * ; 40 clks for /

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Tomasulo Example Cycle 1

Instruction status:

Instruction	j	k	Exec Write		Busy	Address
			Issue	Comp Result		
LD	F6	34+	R2	1	Yes	34+R2
LD	F2	45+	R3		No	
MULTD	F0	F2	F4		No	
SUBD	F8	F6	F2		No	
DIVD	F10	F0	F6		No	
ADDD	F6	F8	F2		No	

Reservation Stations:

Time	Name	Busy	Op	S1 Vj	S2 Vk	RS Qj	RS Qk
Add1		No					
Add2		No					
Add3		No					
Mult1		No					
Mult2		No					

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
1	FU			Load1					

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Tomasulo Example Cycle 2

Instruction status:

Instruction	j	k	Exec Write		Busy	Address
			Issue	Comp Result		
LD	F6	34+	R2	1	Yes	34+R2
LD	F2	45+	R3	2	Yes	45+R3
MULTD	F0	F2	F4		No	
SUBD	F8	F6	F2		No	
DIVD	F10	F0	F6		No	
ADDD	F6	F8	F2		No	

Reservation Stations:

Time	Name	Busy	Op	S1 Vj	S2 Vk	RS Qj	RS Qk
Add1		No					
Add2		No					
Add3		No					
Mult1		No					
Mult2		No					

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
2	FU	Load2			Load1				

Note: Can have multiple loads outstanding

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Tomasulo Example Cycle 3

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3				Yes	34+R2
LD	F2	45+	R3	2					Yes	45+R3
MULTD	F0	F2	F4	3					No	
SUBD	F8	F6	F2							
DIVD	F10	F0	F6							
ADDD	F6	F8	F2							

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		No					
Add2		No					
Add3		No					
Mult1		Yes	MULTD	R(F4)	Load2		
Mult2		No					

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
3	Mult1	Load2		Load1					

- Note: registers names are removed ("renamed") in Reservation Stations; MULT issued
- Load1 completing; what is waiting for Load1?

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Tomasulo Example Cycle 4

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3				No	
LD	F2	45+	R3	2	4				Yes	45+R3
MULTD	F0	F2	F4	3					No	
SUBD	F8	F6	F2	4						
DIVD	F10	F0	F6							
ADDD	F6	F8	F2							

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		Yes	SUBD	M(A1)		Load2	
Add2		No					
Add3		No					
Mult1		Yes	MULTD	R(F4)	Load2		
Mult2		No					

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
4	Mult1	Load2		M(A1)	Add1				

- Load2 completing; what is waiting for Load2?

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Tomasulo Example Cycle 5

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4				
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2					

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
2	Add1	Yes	SUBD	M(A1)	M(A2)		
	Add2	No					
	Add3	No					
10	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
5	FU	Mult1	M(A2)		M(A1)	Add1	Mult2		

- Timer starts down for Add1, Mult1

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Tomasulo Example Cycle 6

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4				
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6				

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
1	Add1	Yes	SUBD	M(A1)	M(A2)		
	Add2	Yes	ADDD		M(A2)	Add1	
	Add3	No					
9	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
6	FU	Mult1	M(A2)		Add2	Add1	Mult2		

- Issue ADDD here despite name dependency on F6?

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Tomasulo Example Cycle 7

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3	4			No	
LD	F2	45+	R3	2	4	5			No	
MULTD	F0	F2	F4	3					No	
SUBD	F8	F6	F2	4	7					
DIVD	F10	F0	F6	5						
ADDD	F6	F8	F2	6						

Reservation Stations:

Time	Name	Busy	Op	S1 Vj	S2 Vk	RS Qj	RS Qk
0	Add1	Yes	SUBD	M(A1)	M(A2)		
	Add2	Yes	ADDD		M(A2)	Add1	
	Add3	No					
8	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
7	Mult1	M(A2)		Add2	Add1	Mult2			

- Add1 (SUBD) completing; what is waiting for it?

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Tomasulo Example Cycle 8

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3	4			No	
LD	F2	45+	R3	2	4	5			No	
MULTD	F0	F2	F4	3					No	
SUBD	F8	F6	F2	4	7	8				
DIVD	F10	F0	F6	5						
ADDD	F6	F8	F2	6						

Reservation Stations:

Time	Name	Busy	Op	S1 Vj	S2 Vk	RS Qj	RS Qk
	Add1	No					
2	Add2	Yes	ADDD	(M-M)	M(A2)		
	Add3	No					
7	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
8	Mult1	M(A2)		Add2	(M-M)	Mult2			

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Tomasulo Example Cycle 9

Instruction status:

Instruction	j	k	Exec Write			Load1	Load2	Load3	Busy	Address
			Issue	Comp	Result					
LD	F6	34+	R2	1	3	4		No		
LD	F2	45+	R3	2	4	5		No		
MULTD	F0	F2	F4	3				No		
SUBD	F8	F6	F2	4	7	8				
DIVD	F10	F0	F6	5						
ADDD	F6	F8	F2	6						

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
	Add1	No					
1	Add2	Yes	ADDD	(M-M)	M(A2)		
	Add3	No					
6	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
9	Mult1	M(A2)		Add2	(M-M)	Mult2			

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Tomasulo Example Cycle 10

Instruction status:

Instruction	j	k	Exec Write			Load1	Load2	Load3	Busy	Address
			Issue	Comp	Result					
LD	F6	34+	R2	1	3	4		No		
LD	F2	45+	R3	2	4	5		No		
MULTD	F0	F2	F4	3				No		
SUBD	F8	F6	F2	4	7	8				
DIVD	F10	F0	F6	5						
ADDD	F6	F8	F2	6	10					

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
	Add1	No					
0	Add2	Yes	ADDD	(M-M)	M(A2)		
	Add3	No					
5	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
10	Mult1	M(A2)		Add2	(M-M)	Mult2			

- Add2 (ADDD) completing; what is waiting for it?

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Tomasulo Example Cycle 11

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		No					
Add2		No					
Add3		No					
4 Mult1		Yes	MULTD	M(A2)	R(F4)		
Mult2		Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
11	FU	Mult1	M(A2)	(M-M+N)	M-M	Mult2			

- Write result of ADDD here?
- All quick instructions complete in this cycle!

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Tomasulo Example Cycle 12

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		No					
Add2		No					
Add3		No					
3 Mult1		Yes	MULTD	M(A2)	R(F4)		
Mult2		Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
12	FU	Mult1	M(A2)	(M-M+N)	(M-M)	Mult2			

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Tomasulo Example Cycle 13

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		No					
Add2		No					
Add3		No					
2	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
13	FU	Mult1	M(A2)		(M-M+N)	(M-M)	Mult2		

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Tomasulo Example Cycle 14

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3			Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
Add1		No					
Add2		No					
Add3		No					
1	Mult1	Yes	MULTD	M(A2)	R(F4)		
	Mult2	Yes	DIVD		M(A1)	Mult1	

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
14	FU	Mult1	M(A2)		(M-M+N)	(M-M)	Mult2		

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Tomasulo Example Cycle 15

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3	15		Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1		S2		RS	RS
				Vj	Vk	Qj	Qk		
Add1		No							
Add2		No							
Add3		No							
0	Mult1	Yes	MULTD	M(A2)		R(F4)			
	Mult2	Yes	DIVD		M(A1)	Mult1			

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
15	FU	Mult1	M(A2)		(M-M+N	(M-M)	Mult2		

- Mult1 (MULTD) completing; what is waiting for it?

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Tomasulo Example Cycle 16

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3	15	16	Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1		S2		RS	RS
				Vj	Vk	Qj	Qk		
Add1		No							
Add2		No							
Add3		No							
	Mult1	No							
40	Mult2	Yes	DIVD	M*F4		M(A1)			

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
16	FU	M*F4	M(A2)		(M-M+N	(M-M)	Mult2		

- Just waiting for Mult2 (DIVD) to complete

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Faster than light computation
(skip a couple of cycles)

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Tomasulo Example Cycle 55

Instruction status:

Instruction	j	k	Exec Write			Busy	Address	
			Issue	Comp	Result			
LD	F6	34+	R2	1	3	4	Load1	No
LD	F2	45+	R3	2	4	5	Load2	No
MULTD	F0	F2	F4	3	15	16	Load3	No
SUBD	F8	F6	F2	4	7	8		
DIVD	F10	F0	F6	5				
ADDD	F6	F8	F2	6	10	11		

Reservation Stations:

Time	Name	Busy	Op	S1	S2	RS	RS
				Vj	Vk	Qj	Qk
	Add1	No					
	Add2	No					
	Add3	No					
	Mult1	No					
1	Mult2	Yes	DIVD	M*F4	M(A1)		

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
55	M*F4	M(A2)		(M-M+N	(M-M)	Mult2			

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Tomasulo Example Cycle 56

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3	4			No	
LD	F2	45+	R3	2	4	5			No	
MULTD	F0	F2	F4	3	15	16			No	
SUBD	F8	F6	F2	4	7	8				
DIVD	F10	F0	F6	5	56					
ADDD	F6	F8	F2	6	10	11				

Reservation Stations:

Time	Name	Busy	Op	S1		S2		RS	RS
				Vj	Vk	Qj	Qk		
Add1		No							
Add2		No							
Add3		No							
Mult1		No							
0 Mult2	Yes		DIVD	M*F4	M(A1)				

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
56	FU	M*F4	M(A2)		(M-M+N	(M-M)	Mult2		

- Mult2 (DIVD) is completing; what is waiting for it?

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Tomasulo Example Cycle 57

Instruction status:

Instruction	j	k	Issue	Exec Write		Load1	Load2	Load3	Busy	Address
				Comp	Result					
LD	F6	34+	R2	1	3	4			No	
LD	F2	45+	R3	2	4	5			No	
MULTD	F0	F2	F4	3	15	16			No	
SUBD	F8	F6	F2	4	7	8				
DIVD	F10	F0	F6	5	56	57				
ADDD	F6	F8	F2	6	10	11				

Reservation Stations:

Time	Name	Busy	Op	S1		S2		RS	RS
				Vj	Vk	Qj	Qk		
Add1		No							
Add2		No							
Add3		No							
Mult1		No							
Mult2	Yes		DIVD	M*F4	M(A1)				

Register result status:

Clock	F0	F2	F4	F6	F8	F10	F12	...	F30
56	FU	M*F4	M(A2)		(M-M+N	(M-M)	Result		

- Once again: In-order issue, out-of-order execution and out-of-order completion.

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Tomasulo Drawbacks

- **Complexity**
 - delays of 360/91, MIPS 10000, Alpha 21264, IBM PPC 620 in CA:AQA 2/e, but not in silicon!
- **Many associative stores (CDB) at high speed**
- **Performance limited by Common Data Bus**
 - Each CDB must go to multiple functional units
⇒ high capacitance, high wiring density
 - Number of functional units that can complete per cycle limited to one!
 - » Multiple CDBs ⇒ more FU logic for parallel assoc stores
- **Non-precise interrupts!**
 - We will address this later

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Tomasulo Loop Example

```
Loop: LD      F0    0    R1
      MULTD   F4    F0   F2
      SD      F4    0    R1
      SUBI    R1    R1   #8
      BNEZ   R1    Loop
```

- This time assume Multiply takes 4 clocks
- Assume 1st load takes 8 clocks
(L1 cache miss), 2nd load takes 1 clock (hit)
- To be clear, will show clocks for SUBI, BNEZ
 - Reality: integer instructions ahead of Fl. Pt. Instructions
- Show 2 iterations

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Loop Example

Instruction status:

Iteration Count	ITER	Instruction	j	k	Exec Write			Issue	Comp	Result	Busy	Addr	Fu
					S1	S2	RS						
1	1	LD	F0	0	R1						No		
1	1	MULTD	F4	F0	F2						No		
1	1	SD	F4	0	R1						No		
2	2	LD	F0	0	R1						No		
2	2	MULTD	F4	F0	F2						No		
2	2	SD	F4	0	R1						No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
Add1		No						LD F0 0 R1
Add2		No						MULTD F4 F0 F2
Add3		No						SD F4 0 R1
Mult1		No						SUBI R1 R1 #8
Mult2		No						BNEZ R1 Loop

Register result status

Clock	R1	Fu	F0	F2	F4	F6	F8	F10	F12	...	F30
0	80										

Value of Register used for address, iteration control

Loop Example Cycle 1

Instruction status:

ITER	Instruction	j	k	Exec Write			Issue	Comp	Result	Busy	Addr	Fu
				S1	S2	RS						
1	LD	F0	0	R1			1			Yes	80	
										No		
										No		
										No		
										No		
										No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
Add1		No						LD F0 0 R1
Add2		No						MULTD F4 F0 F2
Add3		No						SD F4 0 R1
Mult1		No						SUBI R1 R1 #8
Mult2		No						BNEZ R1 Loop

Register result status

Clock	R1	Fu	F0	F2	F4	F6	F8	F10	F12	...	F30
1	80	Load1	Load1								

Loop Example Cycle 2

Instruction status:

ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Yes	80	
1	MULTD	F4	F0	F2	2		No		
							No		
							No		
							No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
	Add1	No						LD F0 0 R1
	Add2	No						MULTD F4 F0 F2 ←
	Add3	No						SD F4 0 R1
	Mult1	Yes	Multd			R(F2)	Load1	SUBI R1 R1 #8
	Mult2	No						BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
2	80	Fu	Load1	Mult1						

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Loop Example Cycle 3

Instruction status:

ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Yes	80	
1	MULTD	F4	F0	F2	2		No		
1	SD	F4	0	R1	3		No		
							Yes	80	Mult1
							No		
							No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
	Add1	No						LD F0 0 R1
	Add2	No						MULTD F4 F0 F2 ←
	Add3	No						SD F4 0 R1
	Mult1	Yes	Multd			R(F2)	Load1	SUBI R1 R1 #8
	Mult2	No						BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
3	80	Fu	Load1	Mult1						

- Implicit renaming sets up data flow graph

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Loop Example Cycle 4

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Load1	Yes	80
1	MULTD	F4	F0	F2	2		Load2	No	
1	SD	F4	0	R1	3		Load3	No	
							Store1	Yes	80
							Store2	No	
							Store3	No	

Reservation Stations:

				S1	S2	RS							
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:					
Add1	No							LD	F0	0	R1		
Add2	No							MULTD	F4	F0	F2		
Add3	No							SD	F4	0	R1		
Mult1	Yes	Multd				R(F2)	Load1	SUBI	R1	R1	#8		←
Mult2	No							BNEZ	R1	Loop			

Register result status

Clock	R1	Fu	F0	F2	F4	F6	F8	F10	F12	...	F30
4	80	Fu	Load1		Mult1						

- Dispatching SUBI Instruction (not in FP queue)

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Loop Example Cycle 5

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Load1	Yes	80
1	MULTD	F4	F0	F2	2		Load2	No	
1	SD	F4	0	R1	3		Load3	No	
							Store1	Yes	80
							Store2	No	
							Store3	No	

Reservation Stations:

				S1	S2	RS							
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:					
Add1	No							LD	F0	0	R1		
Add2	No							MULTD	F4	F0	F2		
Add3	No							SD	F4	0	R1		
Mult1	Yes	Multd				R(F2)	Load1	SUBI	R1	R1	#8		←
Mult2	No							BNEZ	R1	Loop			

Register result status

Clock	R1	Fu	F0	F2	F4	F6	F8	F10	F12	...	F30
5	72	Fu	Load1		Mult1						

- And, BNEZ instruction (not in FP queue)

106

Loop Example Cycle 6

Instruction status:

ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Yes	80	
1	MULTD	F4	F0	F2	2		Yes	72	
1	SD	F4	0	R1	3		No		
2	LD	F0	0	R1	6		Yes	80	Mult1

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
Add1	No							LD F0 0 R1
Add2	No							MULTD F4 F0 F2
Add3	No							SD F4 0 R1
Mult1	Yes	Multd						SUBI R1 R1 #8
Mult2	No							BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
6	72	Load2		Mult1						

- Notice that F0 never sees Load from location 80

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Loop Example Cycle 7

Instruction status:

ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Yes	80	
1	MULTD	F4	F0	F2	2		Yes	72	
1	SD	F4	0	R1	3		No		
2	LD	F0	0	R1	6		Yes	80	Mult1
2	MULTD	F4	F0	F2	7		No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
Add1	No							LD F0 0 R1
Add2	No							MULTD F4 F0 F2
Add3	No							SD F4 0 R1
Mult1	Yes	Multd						SUBI R1 R1 #8
Mult2	Yes	Multd						BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
7	72	Load2		Mult2						

- Register file completely detached from computation
- First and Second iteration completely overlapped

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Loop Example Cycle 8

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1		Load1	Yes	80
1	MULTD	F4	F0	F2	2		Load2	Yes	72
1	SD	F4	0	R1	3		Load3	No	
2	LD	F0	0	R1	6		Store1	Yes	80
2	MULTD	F4	F0	F2	7		Store2	Yes	72
2	SD	F4	0	R1	8		Store3	No	

Reservation Stations:

				S1	S2	RS						
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
Add1	No							LD	F0	0	R1	
Add2	No							MULTD	F4	F0	F2	
Add3	No							SD	F4	0	R1	←
Mult1	Yes	Multd				R(F2)	Load1	SUBI	R1	R1	#8	
Mult2	Yes	Multd				R(F2)	Load2	BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
8	72	Fu	Load2	Mult2						

109

Loop Example Cycle 9

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	Load1	Yes	80
1	MULTD	F4	F0	F2	2		Load2	Yes	72
1	SD	F4	0	R1	3		Load3	No	
2	LD	F0	0	R1	6		Store1	Yes	80
2	MULTD	F4	F0	F2	7		Store2	Yes	72
2	SD	F4	0	R1	8		Store3	No	

Reservation Stations:

				S1	S2	RS						
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
Add1	No							LD	F0	0	R1	
Add2	No							MULTD	F4	F0	F2	
Add3	No							SD	F4	0	R1	←
Mult1	Yes	Multd				R(F2)	Load1	SUBI	R1	R1	#8	
Mult2	Yes	Multd				R(F2)	Load2	BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
9	72	Fu	Load2	Mult2						

- Load1 completing: who is waiting?
- Note: Dispatching SUBI

110

Loop Example Cycle 10

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2			Load2	Yes 72
1	SD	F4	0	R1	3			Load3	No
2	LD	F0	0	R1	6	10		Store1	Yes 80 Mult1
2	MULTD	F4	F0	F2	7			Store2	Yes 72 Mult2
2	SD	F4	0	R1	8			Store3	No

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
	Add1	No						LD F0 0 R1
	Add2	No						MULTD F4 F0 F2
	Add3	No						SD F4 0 R1
4	Mult1	Yes	Mult	M[80]	R(F2)			SUBI R1 R1 #8
	Mult2	Yes	Mult		R(F2) Load2			BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
10	64	Fu	Load2	Mult2						

- Load2 completing: who is waiting?
- Note: Dispatching BNEZ

111

Loop Example Cycle 11

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2			Load2	No
1	SD	F4	0	R1	3			Load3	Yes 64
2	LD	F0	0	R1	6	10	11	Store1	Yes 80 Mult1
2	MULTD	F4	F0	F2	7			Store2	Yes 72 Mult2
2	SD	F4	0	R1	8			Store3	No

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:
	Add1	No						LD F0 0 R1
	Add2	No						MULTD F4 F0 F2
	Add3	No						SD F4 0 R1
3	Mult1	Yes	Mult	M[80]	R(F2)			SUBI R1 R1 #8
4	Mult2	Yes	Mult	M[72]	R(F2)			BNEZ R1 Loop

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
11	64	Fu	Load3	Mult2						

- Next load in sequence

112

Loop Example Cycle 12

Instruction status:

						Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu		
1	LD	F0	0	R1	1	9	10	Load1	No		
1	MULTD	F4	F0	F2	2			Load2	No		
1	SD	F4	0	R1	3			Load3	Yes	64	
2	LD	F0	0	R1	6	10	11	Store1	Yes	80	Mult1
2	MULTD	F4	F0	F2	7			Store2	Yes	72	Mult2
2	SD	F4	0	R1	8			Store3	No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:			
	Add1	No						LD	F0	0	R1
	Add2	No						MULTD	F4	F0	F2
	Add3	No						SD	F4	0	R1
2	Mult1	Yes	Multd	M[80]	R(F2)			SUBI	R1	R1	#8
3	Mult2	Yes	Multd	M[72]	R(F2)			BNEZ	R1	Loop	

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
12	64	Fu	Load3	Mult2						

- Why not issue third multiply?

113

Loop Example Cycle 13

Instruction status:

						Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu		
1	LD	F0	0	R1	1	9	10	Load1	No		
1	MULTD	F4	F0	F2	2			Load2	No		
1	SD	F4	0	R1	3			Load3	Yes	64	
2	LD	F0	0	R1	6	10	11	Store1	Yes	80	Mult1
2	MULTD	F4	F0	F2	7			Store2	Yes	72	Mult2
2	SD	F4	0	R1	8			Store3	No		

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:			
	Add1	No						LD	F0	0	R1
	Add2	No						MULTD	F4	F0	F2
	Add3	No						SD	F4	0	R1
1	Mult1	Yes	Multd	M[80]	R(F2)			SUBI	R1	R1	#8
2	Mult2	Yes	Multd	M[72]	R(F2)			BNEZ	R1	Loop	

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
13	64	Fu	Load3	Mult2						

- Why not issue third store?

114

Loop Example Cycle 14

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2	14		Load2	No
1	SD	F4	0	R1	3			Load3	Yes 64
2	LD	F0	0	R1	6	10	11	Store1	Yes 80 Mult1
2	MULTD	F4	F0	F2	7			Store2	Yes 72 Mult2
2	SD	F4	0	R1	8			Store3	No

Reservation Stations:

				S1	S2	RS					
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:			
	Add1	No						LD	F0	0	R1
	Add2	No						MULTD	F4	F0	F2 ←
	Add3	No						SD	F4	0	R1
0	Mult1	Yes	Multd	M[80]	R(F2)			SUBI	R1	R1	#8
1	Mult2	Yes	Multd	M[72]	R(F2)			BNEZ	R1	Loop	

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
14	64	Fu	Load3	Mult2						

• **Mult1 completing. Who is waiting?**

115

Loop Example Cycle 15

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2	14	15	Load2	No
1	SD	F4	0	R1	3			Load3	Yes 64
2	LD	F0	0	R1	6	10	11	Store1	Yes 80 [80]*R2
2	MULTD	F4	F0	F2	7	15		Store2	Yes 72 Mult2
2	SD	F4	0	R1	8			Store3	No

Reservation Stations:

				S1	S2	RS					
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:			
	Add1	No						LD	F0	0	R1
	Add2	No						MULTD	F4	F0	F2 ←
	Add3	No						SD	F4	0	R1
0	Mult1	No						SUBI	R1	R1	#8
0	Mult2	Yes	Multd	M[72]	R(F2)			BNEZ	R1	Loop	

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
15	64	Fu	Load3	Mult2						

• **Mult2 completing. Who is waiting?**

116

Loop Example Cycle 16

Instruction status:

ITER	Instruction	j	k	Issue	Exec Write			Busy	Addr	Fu
					Comp	Result				
1	LD	F0	0	R1	1	9	10	Load1	No	
1	MULTD	F4	F0	F2	2	14	15	Load2	No	
1	SD	F4	0	R1	3			Load3	Yes	64
2	LD	F0	0	R1	6	10	11	Store1	Yes	80
2	MULTD	F4	F0	F2	7	15	16	Store2	Yes	72
2	SD	F4	0	R1	8			Store3	No	

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
	Add1	No						LD	F0	0	R1	
	Add2	No						MULTD	F4	F0	F2	←
	Add3	No						SD	F4	0	R1	
4	Mult1	Yes	Multd			R(F2)	Load3	SUBI	R1	R1	#8	
	Mult2	No						BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
16	64	Fu	Load3	Mult1						

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Loop Example Cycle 17

Instruction status:

ITER	Instruction	j	k	Issue	Exec Write			Busy	Addr	Fu
					Comp	Result				
1	LD	F0	0	R1	1	9	10	Load1	No	
1	MULTD	F4	F0	F2	2	14	15	Load2	No	
1	SD	F4	0	R1	3			Load3	Yes	64
2	LD	F0	0	R1	6	10	11	Store1	Yes	80
2	MULTD	F4	F0	F2	7	15	16	Store2	Yes	72
2	SD	F4	0	R1	8			Store3	Yes	64

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
	Add1	No						LD	F0	0	R1	
	Add2	No						MULTD	F4	F0	F2	←
	Add3	No						SD	F4	0	R1	
	Mult1	Yes	Multd			R(F2)	Load3	SUBI	R1	R1	#8	
	Mult2	No						BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
17	64	Fu	Load3	Mult1						

118

Loop Example Cycle 18

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2	14	15	Load2	No
1	SD	F4	0	R1	3	18		Load3	Yes 64
2	LD	F0	0	R1	6	10	11	Store1	Yes 80 [80]*R2
2	MULTD	F4	F0	F2	7	15	16	Store2	Yes 72 [72]*R2
2	SD	F4	0	R1	8			Store3	Yes 64 Mult1

Reservation Stations:

				S1	S2	RS						
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
Add1	No							LD	F0	0	R1	
Add2	No							MULTD	F4	F0	F2	
Add3	No							SD	F4	0	R1	
Mult1	Yes	Multd			R(F2)	Load3		SUBI	R1	R1	#8	←
Mult2	No							BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
18	64	Fu	Load3	Mult1						

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Loop Example Cycle 19

Instruction status:

				Exec Write					
ITER	Instruction	j	k	Issue	Comp	Result	Busy	Addr	Fu
1	LD	F0	0	R1	1	9	10	Load1	No
1	MULTD	F4	F0	F2	2	14	15	Load2	No
1	SD	F4	0	R1	3	18	19	Load3	Yes 64
2	LD	F0	0	R1	6	10	11	Store1	No
2	MULTD	F4	F0	F2	7	15	16	Store2	Yes 72 [72]*R2
2	SD	F4	0	R1	8	19		Store3	Yes 64 Mult1

Reservation Stations:

				S1	S2	RS						
Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
Add1	No							LD	F0	0	R1	
Add2	No							MULTD	F4	F0	F2	
Add3	No							SD	F4	0	R1	
Mult1	Yes	Multd			R(F2)	Load3		SUBI	R1	R1	#8	←
Mult2	No							BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
19	56	Fu	Load3	Mult1						

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Loop Example Cycle 20

Instruction status:

ITER	Instruction	j	k	Exec Write			Busy	Addr	Fu		
				Issue	Comp	Result					
1	LD	F0	0	R1	1	9	10	Load1	Yes	56	
1	MULTD	F4	F0	F2	2	14	15	Load2	No		
1	SD	F4	0	R1	3	18	19	Load3	Yes	64	
2	LD	F0	0	R1	6	10	11	Store1	No		
2	MULTD	F4	F0	F2	7	15	16	Store2	No		
2	SD	F4	0	R1	8	19	20	Store3	Yes	64	Mult1

Reservation Stations:

Time	Name	Busy	Op	Vj	Vk	Qj	Qk	Code:				
								S1	S2	RS		
Add1	No							LD	F0	0	R1	←
Add2	No							MULTD	F4	F0	F2	
Add3	No							SD	F4	0	R1	
Mult1	Yes	Multd			R(F2)	Load3		SUBI	R1	R1	#8	
Mult2	No							BNEZ	R1	Loop		

Register result status

Clock	R1	F0	F2	F4	F6	F8	F10	F12	...	F30
20	56	Fu	Load1	Mult1						

- Once again: In-order issue, out-of-order execution and out-of-order completion.

121

Why can Tomasulo overlap iterations of loops?

- **Register renaming**
 - Multiple iterations use different physical destinations for registers (dynamic loop unrolling).
- **Reservation stations**
 - Permit instruction issue to advance past integer control flow operations
 - Also buffer old values of registers - totally avoiding the WAR stall that we saw in the scoreboard.
- **Other perspective: Tomasulo building data flow dependency graph on the fly.**

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Tomasulo's scheme offers 2 major advantages

- (1) the distribution of the hazard detection logic
 - distributed reservation stations and the CDB
 - If multiple instructions waiting on single result, & each instruction has other operand, then instructions can be released simultaneously by broadcast on CDB
 - If a centralized register file were used, the units would have to read their results from the registers when register buses are available.
- (2) the elimination of stalls for WAW and WAR hazards

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Dynamic Memory Disambiguation

- WAR and WAW hazards are eliminated by Tomasulo's algorithm by register renaming
- Easy to do since the names are exposed
- What about if two instructions share the same memory address ?

E.g. L.D. F1, 40(R6)
 S.D F4, 64(R3)

- What if $40(R6) = 64(R3)$???

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Dynamic Memory Disambiguation

L.D. F1, 40(R6)
S.D F4, 64(R3)

- If the load and store are executed out-of-order... WAR hazard

S.D F4, 64(R3)
L.D. F1, 40(R6)

- RAW hazard

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Dynamic Memory Disambiguation

- Loads/Stores have to wait until any uncompleted Stores/Loads sharing the same effective address that precede that instruction in program order complete
- To detect these hazards, we need to know the effective address of any earlier memory operation
- Solution: perform the EA calculations in program order

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Computing EAs in Program Order

- E.g. Consider a load
- When the load completes EA calculation, check the address fields of all the active store buffers
- If the load address matches any active store buffer entry, then do not send the load to the load buffer until the conflicting store completes
- Stores are similar except must check both load and store buffers

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Review Tomasulo

- Reservations stations: *implicit register renaming* to larger set of registers + buffering source operands
 - Prevents registers as bottleneck
 - Avoids WAR, WAW hazards
 - Allows loop unrolling in HW
- Not limited to basic blocks (integer units gets ahead, beyond branches)
- Today, helps cache misses as well
 - Don't stall for L1 Data cache miss (insufficient ILP for L2 miss?)
- Lasting Contributions
 - Dynamic scheduling
 - Register renaming
 - Load/store disambiguation
- 360/91 descendants are Pentium III, 4; PowerPC 604; MIPS R10000; HP-PA 8000; Alpha 21264

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Speculation

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Dynamic Scheduling with Hardware Speculation

- What is speculation? (or speculative execution)
- Let's consider dynamic scheduling (Tomasulo) with hardware branch prediction
- **Make a branch prediction and *execute the program as if the guess was correct***
 - The speculatively executed sequence of instructions probably includes other branches (which need to be predicted).
 - This is especially true in multiple-issue processors (possibly one branch per clock cycle)
- **Need the ability to undo the effects of an incorrectly speculated sequence**

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Dynamic Scheduling with Hardware Speculation

- **Dynamic scheduling without speculation only partially overlaps basic blocks**
 - It requires that a branch be resolved before executing instructions in the successor basic block
- **Speculation allows us to overcome control dependencies (data flow execution)**
- **To implement speculation we will modify Tomasulo's algorithm**

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Hardware Speculation

- **What is needed to speculatively execute a stream of instructions?**
- **We must avoid updating the state of the processor until we know for sure that an instruction should have been executed (we then say that it is no longer speculative)**
- **Registers must not be written until an instruction is no longer speculative**
 - Rely on forwarding results among instructions
 - The values forwarded might not be correct.

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Instruction Commit

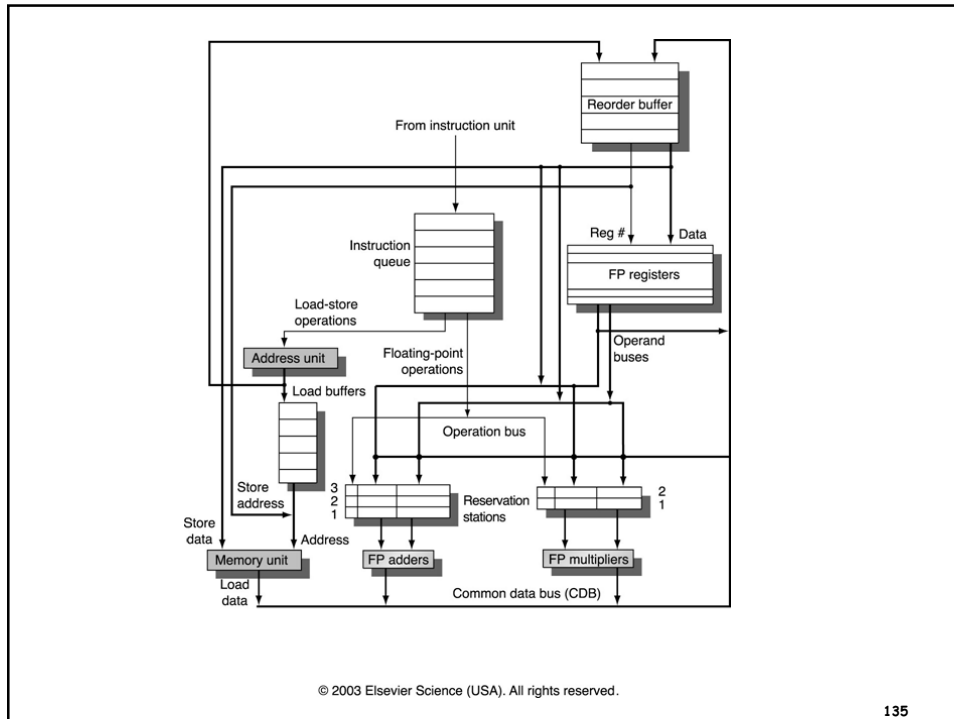
- When we finally know that an instruction is no longer speculative then we allow it to write to the register file or memory
- This extra pipeline stage is called instruction commit
- Key idea: allow instructions to *execute out-of-order* but to commit *in-order*
 - Need to prevent any irrecoverable action (state update, or exception) until the instruction commits
- Instructions may finish execution considerably before they are ready to commit

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Reorder Buffer

- Need a reorder buffer to hold the results of instructions that have finished execution but have not yet committed
- The ROB also passes results between instructions
 - Register file is updated only when the instruction commits
 - Takes over the role of register renaming from the reservation stations (still need them as buffers between instruction issue and execution)
 - ROB performs the same functionality as the store buffers and it replaces them

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Four Steps of Speculative Tomasulo Algorithm

1. **Issue—get instruction from Op Queue**
 - If reservation station and reorder buffer slot free, issue instr & send operands & reorder buffer no. for destination
2. **Execution—operate on operands (EX)**
 - When both operands ready then execute; if not ready, watch CDB for result; when both in reservation station, execute; checks RAW
3. **Write result—finish execution (WB)**
 - Write on Common Data Bus to all awaiting FUs & reorder buffer; mark reservation station available.
4. **Commit—update register with reorder result**
 - When instr. at head of reorder buffer & result present, update register with result (or store to memory) and remove instr from reorder buffer. Mispredicted branch flushes reorder buffer

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Reorder Buffer

ROB

Entry	Busy	Instruction	State	Dest	Value
1	no	L.D. F6,34(R2)	commit	F6	Mem[34+Regs[R2]]
2	yes	MUL.D F0,F6,F4	Write result	F0	#1 x Regs[F4]
3	yes	DIV.D F10,F0,F6	Execute	F10	

Reservation stations

Name	Busy	Op	Vj	Vk	Qj	Qk	Dest	A
Mult1	no	MUL.D	Mem[34+Regs[R2]]	Regs[F4]			#2	
Mult2	yes	DIV.D		Mem[34+Regs[R2]]	#2		#3	

FP Register Status

Field	F0	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10
Reorder #	2										3
Busy	yes	no	no	no	no	no	no	no	no	no	yes

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What about Precise Interrupts?

- Tomasulo had:

In-order issue, out-of-order execution, and out-of-order completion

- Need to "fix" the out-of-order completion aspect so that we can find precise breakpoint in instruction stream.

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Relationship between precise interrupts and speculation:

- **Speculation is a form of guessing.**
- **Important for branch prediction:**
 - Need to "take our best shot" at predicting branch direction.
- **If we speculate and are wrong, need to back up and restart execution to point at which we predicted incorrectly:**
 - Need to "fix" the out-of-order completion aspect so that we can find precise breakpoint in instruction stream.
- **What about precise exceptions?**
 - Need to "fix" the out-of-order completion aspect so that we can find precise breakpoint in instruction stream.
- **Technique for both precise interrupts/exceptions and speculation: *in-order completion or commit***

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Again we take the example of the add-scalar-to-vector loop example. We assume that all integer operations are finished and focus on FP.

Entry	Busy	Instruction	State	Destination	Value
1	no	L.D F0, 0(R1)	Commit	F0	Mem[0+Reg[R1]]
2	no	ADD.D F4, F0, F2	Commit	F4	#1 * Reg[F2]
3	yes	S.D F4, 0(R1)	Write result	0+Reg[R1]	#2
4	yes	DADDIU R1, R1, -8	Write result	R1	Regs[R1] - 8
5	yes	BNE R1, R2, L	Write result		
6	yes	L.D F0, 0(R1)	Write result	F0	Mem[#4]
7	yes	ADD.D F4, F0, F2	Write result	F4	#6 * Reg[F2]
8	yes	S.D F4, 0(R1)	Write result	0+#4	#7
9	yes	DADDIU R1, R1, -8	Write result	R1	#4 - 8
10	yes	BNE R1, R2, L	Write result		

At this particular time, two complete loops have issued and the first two entries have committed, freeing the ROB entries (fields are left filled for clarity but could be rewritten by other instructions). When the head (currently at entry 3) reaches the branch, if the BNE at entry 5 was mispredicted when issued, then instructions following it are flushed and will never commit.

In essence, the ROB executes **in-order** a simplified version of the original code: it performs just the writes according to the actual outcomes of branches. The actual computations are done speculatively according to branch predictions.

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Multiple-Issue Processors

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Getting CPI < 1: Issuing Multiple Instructions/Cycle

- **Basic idea: parallel pipelines.**
 - Allow the fetching, issuing, and completion of more than one instruction every clock cycle
- **Superscalar: varying no. instructions/cycle (1 to 8), scheduled by compiler or by HW (Tomasulo)**
 - IBM PowerPC, Sun UltraSparc, DEC Alpha, Pentium III/4
- **Very Long Instruction Words (VLIW): fixed number of instructions (4-16) scheduled by the compiler; put ops into wide templates (TBD)**
 - Intel Architecture-64 (IA-64) 64-bit address
 - » Renamed: "Explicitly Parallel Instruction Computer (EPIC)"
 - Will discuss in next chapter

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Multiple-Issue Processors

Common Name	Issue Structure	Hazard detection	Scheduling	Distinguishing Characteristic	Examples
Superscalar (static)	Dynamic	Hardware	Static	In-order execution	MIPS, ARM (mainly embedded)
Superscalar (dynamic)	Dynamic	Hardware	Dynamic	Some out-of-order execution (no speculation)	none presently
Superscalar (speculative)	Dynamic	Hardware	Dynamic with speculation	Out-of-order execution with speculation	Pentium 4, MIPS R12K, IBM Power 5
VLIW	Static	Mostly Software	Static	All hazards determined and indicated by compiler (often implicitly)	C6X
EPIC	Mostly static	Mostly software	Mostly static	Explicit dependences marked by compiler	Itanium

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Getting CPI < 1: Issuing Multiple Instructions/Cycle

- **Superscalar MIPS: 2 instructions, 1 FP & 1 integer**
 - Fetch 64-bits/clock cycle; Int on left, FP on right
 - Can only issue 2nd instruction if 1st instruction issues
 - More ports for FP registers to do FP load & FP op in a pair

Type

Pipe Stages

Int. instruction	IF	ID	EX	MEM	WB		
FP instruction	IF	ID	EX	MEM	WB		
Int. instruction		IF	ID	EX	MEM	WB	
FP instruction		IF	ID	EX	MEM	WB	
Int. instruction			IF	ID	EX	MEM	WB
FP instruction			IF	ID	EX	MEM	WB

- **1 cycle load delay expands to 3 instructions in SS**
 - instruction in right half can't use it, nor instructions in next slot

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Remember the Unrolled Loop...

```

1 Loop: L.D    F0, 0(R1)
2       L.D    F6, -8(R1)
3       L.D    F10, -16(R1)
4       L.D    F14, -24(R1)
5       ADD.D  F4, F0, F2
6       ADD.D  F8, F6, F2
7       ADD.D  F12, F10, F2
8       ADD.D  F16, F14, F2
9       S.D    F4, 0(R1)
10      S.D    F8, -8(R1)
11      DADDUI R1, R1, #-32
12      S.D    F12, -16(R1)
13      BNE   R1, R2, LOOP
14      S.D    F16, 8(R1) ; 8-32 = -24
    
```

14 clock cycles, or 3.5 per iteration

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- Consider a simple statically scheduled 2-issue MIPS

Loop	Integer instruction	FP instruction
	L.D F0, 0(R1)	
	L.D F6, -8(R1)	
	L.D F10, -16(R1)	ADD.D F4, F0, F2
	L.D F14, -24(R1)	ADD.D F8, F6, F2
	L.D F18, -32(R1)	ADD.D F12, F10, F2
	S.D F4, 0(R1)	ADD.D F16, F14, F2
	S.D F8, -8(R1)	ADD.D F20, F18, F2
	S.D F12, -16(R1)	
	DADDUI R1, R1, #-40	
	S.D F16, 16(R1)	
	BNE R1, R2, Loop	
	S.D F20, 8(R1)	

2.4 cc per iteration

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Multiple Issue Issues

- **issue packet: group of instructions from fetch unit that could potentially issue in 1 clock**
 - If instruction causes structural hazard or a data hazard either due to earlier instruction in execution or to earlier instruction in issue packet, then instruction does not issue
 - 0 to N instruction issues per clock cycle, for N-issue
- **Performing issue checks in 1 cycle could limit clock cycle time: $O(n^2-n)$ comparisons**
 - => issue stage usually split and pipelined
 - 1st stage decides how many instructions from within this packet can issue, 2nd stage examines hazards among selected instructions and those already been issued
 - => higher branch penalties => prediction accuracy important
- **While Integer/FP split is simple for the HW, get CPI of 0.5 only for programs with:**
 - Exactly 50% FP operations AND No hazards

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Static Multiple Issue: VLIW

- **Recall superscalar multiple-issue processors:**
 - Decide how many instructions to issue on-the-fly
- **Statically scheduled superscalar:**
 - HW to check for dependencies between instructions in a packet and between instructions in a packet and ones already in the pipeline
- **What if we do the dependence checking in the compiler?**
 - Format an instruction packet with either no dependencies or at least indicate if they are present
 - Simpler hardware

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VLIW

- Very long instruction word (VLIW)
- Idea has been around for a long time
- 64 to 128 bit packets
- Drawback: they can be inflexible.
 - Requires recompilation for different versions of the hardware
- Latest versions use software to assist hardware decisions (EPIC → IA-64)

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The VLIW Idea

- Multiple, independent FUs
- Find independent operations and package them together into a very long instruction word
- Eliminates the expensive hardware that does this in a superscalar
- Superscalar processors are especially expensive for wide issue widths (e.g. > 4) so VLIW machines tend to focus on issue widths of > 4

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VLIW

- **E.g. 5-issue VLIW**
 - 1 integer (incl. branch)
 - 2 FP
 - 2 memory ref.
- **Code must have enough parallelism to fill the operation slots and keep the FUs busy**
- **Find this parallelism by loop unrolling and scheduling**

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VLIW Example

Mem Ref 1	Mem Ref 2	FP op1	FP op2	Int. op/Branch
L.D F0,0(R1)	L.D F6,-8(R1)			
L.D F10,-16(R1)	L.D F14,-24(R1)			
L.D F18,-32(R1)	L.D F22,-24(R1)	ADD.D F4,F0,F2	ADD.D F8,F6,F2	
L.D F26,-32(R1)		ADD.D F12,F10,F2	ADD.D F16,F14,F2	
		ADD.D F20,F18,F2	ADD.D F24,F22,F2	
S.D F4,0(R1)	S.D. F8,-8(R1)	ADD.D F28,F26,F2		
S.D F12,-16(R1)	S.D F16,-24(R1)			DADDUI R1,R1,#-56
S.D F20,24(R1)	S.D F24,16(R1)			
S.D F28,8(R1)				BNE R1,R2,Loop

- **9 cycles**
- **23 operations**
- **2.5 operations / cycle**
- **Efficiency (percent of available slots used) = 60%**
- **Large number of registers used !**

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VLIW Issues

- **Increased code size**
 - Need to aggressively unroll loops
 - Waste bits whenever instructions are not full
 - Use clever encoding or compression
- **Limitations of lock-step operation**
 - No hazard detection h/w
 - A stall in one FU must stall the whole processor (can't predict cache stalls)
 - Recent processors relax this and use h/w to allow unsynchronized execution
- **Binary code compatibility**
 - Different pipeline organizations require different code (i.e. more FUs)
 - One solution: object code translation (Crusoe: rapidly developing)
 - Another solution: relax this approach (IA-64)

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Dynamic scheduling approach:

Similarly the Tomasulo algorithm can be applied to the superscalar case. Instead of issuing one instruction per clock cycle, two or more can be issued. Here is an example for the scalar-add-to-vector loop for dual issue. The CC# when events occur are indicated.

Iter.	Instruction	Issue	Exec	Mem	Write	CDB	Comment
1	L.D F0,0(R1)	1	2	3		4	
1	ADD.D F4,F0,F2	1	5			8	Wait for L.D
1	S.D F4,0(R1)	2	3	9			Wait for ADD.D
1	DADDIU R1,R1,-8	2	4			5	Wait for result
1	BNE R1,R2,L	3	6				Wait for DADDIU
2	L.D F0,0(R1)	4	7	8		9	Wait for BNE
2	ADD.D F4,F0,F2	4	10			13	Etc.
2	S.D F4,0(R1)	5	8	14			
2	DADDIU R1,R1,-8	5	9			10	
2	BNE R1,R2,L	6	11				

Quite complex to analyze: many things happen simultaneously.

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Multiple Issue with Speculation

No speculation:

Iter.	Instruction	Issue	Exec	Mem	Write	CDB	Comment
1	LD R2,0(R1)	1	2	3		4	
1	DADDIU R2,R2,#1	1	5			6	Wait for LD
1	SD R2,0(R1)	2	3	7			Wait for DADDIU
1	DADDIU R1,R1,-8	2	3			4	Executes directly
1	BNE R1,R2,L	3	7				Wait for DADDIU
2	LD R2,0(R1)	4	8	9		10	Wait for BNE
2	DADDIU R2,R2,#1	4	11			12	Etc.
2	SD R2,0(R1)	5	9	13			
2	DADDIU R1,R1,-8	5	8			9	
2	BNE R1,R2,L	6	15				

Speculation:

Iter.	Instruction	Issue	Exec	Read Access	Write CDB	Commits	Comment
1	LD R2,0(R1)	1	2	3	4	5	
1	DADDIU R2,R2,#1	1	5		6	7	Wait for LD
1	SD R2,0(R1)	2	3			7	Wait for DADDIU
1	DADDIU R1,R1,-8	2	3		4	8	Commit in order
1	BNE R1,R2,L	3	7			8	Wait for DADDIU
2	LD R2,0(R1)	4	5	6	7	9	No delay
2	DADDIU R2,R2,#1	4	8		9	10	Etc.
2	SD R2,0(R1)	5	6			10	
2	DADDIU R1,R1,-8	5	6		7	11	
2	BNE R1,R2,L	6	15			11	

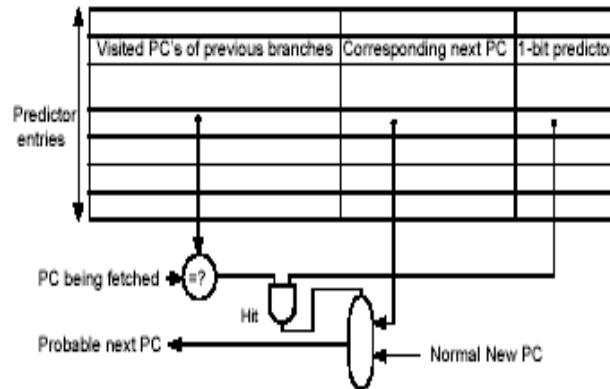
155

High Performance Instruction Delivery

- Delivering instructions becomes bottleneck, especially in multiple-issue processors
- Have to go beyond simple branch prediction
- Classic 5-stage pipeline: branch target address and branch direction (outcome) are known early (in ID)
 - 1 cycle branch delay
- Predictors don't give much benefit for this pipeline unless they can give the prediction in the IF stage
- Seems impossible: don't even know the instruction yet!

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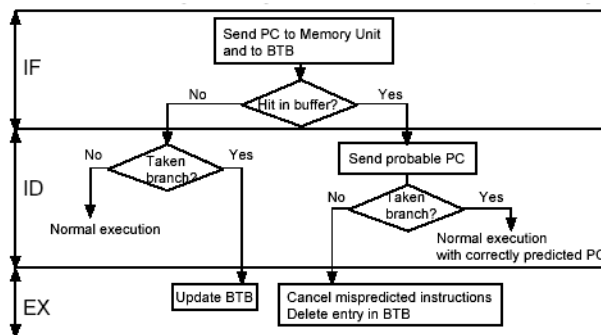
Branch Target Buffer



- Table look up can be done in hardware for small tables
- Usually, only store predicted taken branches in BTB

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Branch Target Buffer



Example of cost in CC for all cases. This, plus statistics allows to predict speedup.

Hit	Prediction	Outcome	Penalty
yes	taken	taken	0: correct instruction fetched next clock cycle
yes	taken	not taken	2: 1 CC to update buffer + 1 CC to restart fetching
no	don't care	taken	2: 1 CC
no	don't care	not taken	0: correct instruction fetched next clock cycle

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Branch Folding

- Next step in this idea is to store the target instruction (instead of just its address)
- Works perfectly for jumps (unconditional branches) - eliminates them completely (negative penalty!)

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Integrated Instruction Fetch Units

- Fetching instructions becomes the bottleneck in multiple-issue processors
- Integrated instruction fetch/prediction unit
- Instruction prefetch
 - Fetch ahead several instructions (Chapter 5)

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Return Address Predictors

- For the procedure call instruction, the return PC is typically stored in a stack in memory
- Instead of loading the return address from memory, some processors provide for a small buffer of the 8-16 most recent return addresses
- Just the knowledge of the PC of a return instruction provides the return address directly without decoding.

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Advanced Software Approaches

(Appendix G.1, G.2, G.3)

Omit material in G.3 after software pipelining

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Advanced Compiler Support

- We will study techniques used by modern compilers such as gcc
- Dependencies: true and name
- This concept also applies to high-level code
- Compilers can detect parallelism in high-level code that hardware would be blind to

```
for (i = 1000; i > 0; i=i-1)
    x[i] = x[i] + s
```

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Loop-Carried Dependencies

```
for (i = 1000; i > 0; i=i-1)
    x[i] = x[i] + s
```

- If data accesses in an iteration depend on data values produced in earlier iterations we say there is a loop-carried dependence
- This is a parallel loop since there are no loop-carried dependencies.
 - Except for the "induction variable" *i*, but this can be recognized and eliminated (e.g. loop unrolling)

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Detecting and Exposing Loop-Level Parallelism

- Inspect the code to detect name and data dependencies
- Name dependencies can be eliminated by using more storage ("software renaming")
 - Left with a chain of data dependencies
- If the data dependency chain can be broken, then the loop has some parallelism
- If all data dependencies are within one iteration, the loop is parallel

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Loop-Carried Dependencies

- Dependencies can exist between statements in a block or across blocks
- Example: recurrences
 - A variable is defined based on the value of that variable in an earlier iteration

e.g.

```
for (i=0; i<=100; ++i)
    y[i] = y[i-5] + y[i]
```

Carries a dependency with a dependence distance of 5

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Finding Dependencies in Loops

- Need to analyze memory references to look for ones that refer to the same addresses
- Difficult in the general case

e.g. $X[Y[i]]$

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Finding Dependencies in Loops

- Consider finding dependencies in the case when the array indices are "affine"
- An affine index has the form $ai + b$ where i is the loop index and a and b are constants
- To detect a dependence, we need to determine if two affine array indices are equal. i.e

$$ai + b = cj + d$$

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GCD Test

- A sufficient test to test for the *absence* of a dependency is the GCD test:
- for references $a_i + b$ and $c_j + d$, if a loop dependency exists, then $GCD(c, a)$ divides $(d-b)$
 - x divides y if y/x is an integer and there is no remainder
- Therefore, do the GCD test. If $GCD(c, a)$ does not divide $d-b$ then there is no dependency.
 - However, the case exists where $GCD(c, a)$ divides $d-b$ and there is still no dependency. (because the loop bounds are not considered)

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Examples of GCD Test

```
for(i=1; i<=100; ++i)
  x[2i+3] = x[2i] + 1.0
```

- $GCD(2, 2)$ does not divide -3
 - No dependency is possible

```
for(i=1; i<=100; ++i)
  x[2i+3] = x[2i+1] + 1.0
```

- 2 divides -2
 - dependency is possible
- In general, deciding if a dependency definitely exists requires an algorithm with an exponential number of steps ("NP-complete") and is not practical
 - A few important sub cases are implemented in modern compilers

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Classifying Dependencies

- In addition to detecting the presence of dependencies, compilers want to classify the type of dependencies
- E.g. Find the dependencies in:

```
for (i=1; i<=100; i=i+1) {  
  Y[i] = X[i] / c      /* S1 */  
  X[i] = X[i] + c     /* S2 */  
  Z[i] = Y[i] + c     /* S3 */  
  Y[i] = c - Y[i]    /* S4 */  
}
```

True dependence
Antidependence
Output dependence

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Example cont'd

```
for (i=1; i<100; i=i+1) {  
  /* Y renamed to T to remove o.d. */  
  T[i] = X[i] / c;  
  /* X renamed to U to remove a.d. */  
  U[i] = X[i] + c;  
  /* Y renamed to T to remove a.d. */  
  Z[i] = T[i] + c;  
  Y[i] = c - T[i];  
}
```

- Second statement is now independent
- Third and fourth only dependent on first

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Compiler Loop-Level Transformations

- Transform this loop to make it parallel

```
for (i=1; i < 100; i++) {  
    a[i] = b[i] + c[i];    /* S1 */  
    b[i] = a[i] + d[i];    /* S2 */  
    a[i+1] = a[i] + e[i];  /* S3 */  
}
```

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Dependence Analysis

```
for (i=1; i < 100; i++) {  
    a[i] = b[i] + c[i];    /* S1 */  
    b[i] = a[i] + d[i];    /* S2 */  
    a[i+1] = a[i] + e[i];  /* S3 */  
}
```

true data dependency
(not loop-carried)

Output dependency
(loop-carried)

true data dependency
(loop-carried)

Antidependency
(not loop-carried)

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Dependence Analysis

```
a[1] = b[1] + c[1];    /* S1 */
b[1] = a[1] + d[1];    /* S2 */
a[2] = a[1] + e[1];    /* S3 */
a[2] = b[2] + c[2];    /* S1 */
b[2] = a[2] + d[2];    /* S2 */
a[3] = a[2] + e[2];    /* S3 */
a[3] = b[3] + c[3];    /* S1 */
b[3] = a[3] + d[3];    /* S2 */
a[4] = a[3] + e[3];    /* S3 */
```

...

- **S3 does no useful work as its result is overwritten by S1 (except on last iteration)**

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Remove S3

```
for (i=1; i < 100; i++) {
    a[i] = b[i] + c[i];    /* S1 */
    U[i] = a[i] + d[i];    /* S2 */
}
a[100] = a[99] + e[99];
```

- **Remove antidependence by software renaming**
- **No loop carried dependencies (parallel loop)**

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Another Example of LLP

```
for (i=1; i < 100; i++) {  
    a[i] = a[i] + b[i];    /* S1 */  
    b[i+1] = c[i] + d[i]; /* S2 */  
} True Dep (loop carried)
```

- No dependence from S1 to S2
- Can this loop be made parallel?
- No cycles in the dependencies, so yes!

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Transformed Parallel Loop

```
a[1] = a[1] + b[1]  
for (i=1; i <= 99; i++) {  
    b[i+1] = c[i] + d[i];  
    a[i+1] = a[i+1] + b[i+1];  
}  
b[101] = c[100] + d[100]
```

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Algebraic Optimization of Recurrences

- E.g. $\text{sum} = \text{sum} + x;$
- Unroll a loop with this recurrence 5 times
 $\text{sum} = \text{sum} + x1 + x2 + x3 + x4 + x5;$
 - 5 dependent operations

- Algebraic optimization

$$\text{sum} = ((\text{sum} + x1) + (x2 + x3)) + (x4 + x5)$$

- 3 dependent operations

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Arithmetic Techniques

- Transformations based on associative and commutative properties of arithmetic
 - not true for limited range and precision, so be careful...
 - Compilers usually will not do these unless explicitly enabled

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Back Substitution

- E.g. replace

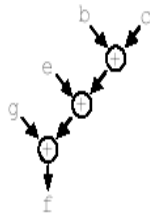
```
DADDUI R1,R2,#4    /* a = b + 4 */
DADDUI R1,R1,#4    /* a = a + 4 */
```

with

```
DADDUI R1,R2,#8    /* a = b + 8 */
```

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Tree Height Reduction

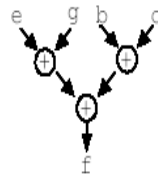


```
ADD R1,R2,R3 // a=b+c
ADD R4,R1,R6 // d=a+e
ADD R8,R4,R7 // f=d+g
```

Three clock cycles

This applies to cases such as

$sum = sum + x1 + x2 + x4 + x5 = ((sum + x1) + (x2 + x3)) + (x4 + x5)$,
etc. The goal of all these transformations is to reduce unnecessary dependencies.



```
ADD R1,R2,R3 // a=b+c
ADD R4,R6,R7 // d=e+g
ADD R8,R1,R4 // f=a+d
```

Two clock cycles

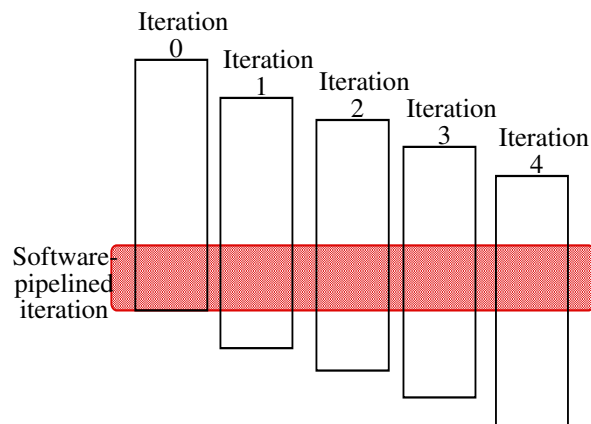
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Software Pipelining

- The general idea of these optimizations is to uncover long sequences of statements without control statements
- Reorganize loops to interleave instructions from different iterations
 - This is the software counterpart to what Tomasulo's algorithm does in hardware
- Dependent instructions within a single loop iteration are then separated from one another by an entire loop body
 - Increases possibilities of scheduling without stalls

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Software Pipelining



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Software Pipelining Example

```
Loop:   L.D.      F0, 0(R1)
        ADD.D    F4, F0, F2
        S.D      F4, 0(R1)
        DADDUI   R1, R1, #-8
        BNE     R1, R2, LOOP
```

• 10 cycles

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Step 1: Symbolic Loop Unrolling

```
ITER i   L.D.      F0, 0(R1)
        ADD.D    F4, F0, F2
        S.D      F4, 0(R1)
ITER i+1 L.D.      F0, 0(R1)
        ADD.D    F4, F0, F2
        S.D      F4, 0(R1)
ITER i+2 L.D.      F0, 0(R1)
        ADD.D    F4, F0, F2
        S.D      F4, 0(R1)
```

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Step 2: Select Instructions from Different Iterations

```
ITER i    L.D.    F0, 0(R1)
          ADD.D   F4, F0, F2
          S.D     F4, 0(R1)
ITER i+1  L.D.    F0, 0(R1)
          ADD.D   F4, F0, F2
          S.D     F4, 0(R1)
ITER i+2  L.D.    F0, 0(R1)
          ADD.D   F4, F0, F2
          S.D     F4, 0(R1)
```

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Step 3. Combine into loop and add init and cleanup code

INIT CODE

```
Loop:    S.D.    F4, 16(R1) ; stores into M[i]
          ADD.D   F4, F0, F2 ; adds to M[i-1]
          L.D     F0, 0(R1) ; loads M[i-2]
          DADDUI  R1, R1, #-8
          BNE     R1, R2, LOOP
```

CLEAN UP CODE

- 5 clock cycles (assuming DADDUI scheduled before the ADD.D and the L.D is scheduled in the branch delay slot)

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Software Pipelining

- **Advantage: yields shorter code than loop unrolling and uses fewer registers**
- **Software pipelining is crucial for VLIW processors**
 - The above example could be compiled into one instruction
- **Often, both software pipelining and loop unrolling are used**