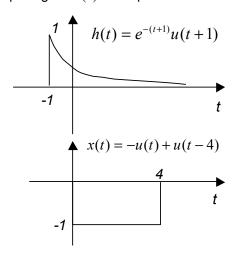
Sample Midterm Test 1 (mt1s03) Covering Chapters 1-3 of Fundamentals of Signals & Systems

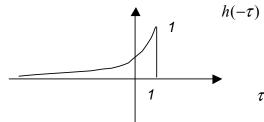
Problem 1 (25 marks)

(a) [20 marks] Compute the output y(t) of the continuous-time LTI system with impulse response h(t) for an input signal x(t) as depicted below.



Answer:

SOLUTION 1: Let's time-reverse and shift the impulse response. The intervals of time of interest are:



t < -1: no overlap, so y(t) = 0.

 $-1 \le t < 3$: overlap over $0 \le \tau < t + 1$, so

$$y(t) = \int_{0}^{t+1} x(\tau)h(t-\tau)d\tau = -\int_{0}^{t+1} e^{-t+\tau-1}d\tau = -e^{-1-t} \left[e^{\tau}\right]_{0}^{t+1}$$
$$= -e^{-1-t} \left[e^{t+1} - 1\right] = e^{-t-1} - 1$$

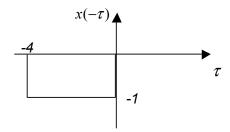
 $t \ge 3$: overlap over $0 \le \tau < 4$, so

$$y(t) = \int_{0}^{4} x(\tau)h(t-\tau)d\tau = -\int_{0}^{4} e^{-t-1+\tau}d\tau = -e^{-t-1}\int_{0}^{4} e^{\tau}d\tau = -e^{-t-1}\left[e^{\tau}\right]_{0}^{4}$$
$$= -e^{-t-1}\left[e^{4}-1\right] = -e^{-(t-3)} + e^{-(t+1)} = \left(e^{-1}-e^{3}\right)e^{-t}$$

Finally, piecing all three intervals together, we get:

$$y(t) = \begin{cases} 0, & t < -1 \\ e^{-t-1} - 1, & -1 \le t < 3 \\ \left(e^{-1} - e^{3}\right)e^{-t}, & t \ge 3 \end{cases}$$

SOLUTION 2: Time reversing and shifting x(t).



$$t < -1$$
: no overlap, so $v(t) = 0$.

$$-1 \le t < 3$$
: overlap over $-1 \le \tau < t$, so

$$y(t) = \int_{-1}^{t} h(\tau)x(t-\tau)d\tau = -\int_{-1}^{t} e^{-\tau-1}d\tau = e^{-1} \left[e^{-\tau} \right]_{-1}^{t}.$$
$$= e^{-1} \left[e^{-t} - e \right] = e^{-t-1} - 1$$

$$t \ge 3$$
: overlap over $t - 4 \le \tau < t$, so

$$y(t) = \int_{t-4}^{t} h(\tau)x(t-\tau)d\tau = -\int_{t-4}^{t} e^{-\tau-1}d\tau = e^{-1} \left[e^{-\tau} \right]_{t-4}^{t}.$$
$$= e^{-t-1} - e^{-t+3}$$

Finally, piecing all three intervals together, we get:

$$y(t) = \begin{cases} 0, & t < -1 \\ e^{-t-1} - 1, & -1 \le t < 3 \\ \left(e^{-1} - e^{3}\right)e^{-t}, & t \ge 3 \end{cases}$$

(b) [5 marks] Is the LTI system S_0 in (a) stable? Is it causal? Justify your answers.

Answer:

Yes it is BIBO stable, because the impulse response is absolutely integrable, as shown below.

$$\int_{-\infty}^{+\infty} |h(t)| dt = \int_{-\infty}^{+\infty} |e^{-t-1}u(t+1)| dt = \int_{-1}^{+\infty} e^{-t-1} dt$$
$$= -e^{-1} \left[e^{-t} \right]_{-1}^{+\infty} = -e^{-1} \left[-e \right] = 1 < +\infty$$

The system is <u>noncausal</u> because $h(t) \neq 0, -1 \leq t < 0$.

Problem 2 (20 marks)

Determine if the system S described by $y(t) = \frac{x(t)}{1 + x(t-1)}$ is

- (a) [5 marks] Time-invariant
- (b) [5 marks] Linear
- (c) [5 marks] Memoryless
- (d) [5 marks] Causal

Justify your answers.

Answer:

(a) The system $\,S\,$ is $\underline{\text{time-invariant}}\,$ since

$$y_1(t) := Sx(t-T) = \frac{x(t-T)}{1+x(t-1-T)} = y(t-T)$$

(b) The system S is <u>nonlinear</u> since it doesn't have the superposition property:

For
$$x_1(t)$$
, $x_2(t)$, let $y_1(t) = \frac{x_1(t)}{1 + x_1(t-1)}$, $y_2(t) = \frac{x_2(t)}{1 + x_2(t-1)}$

Define $x(t) = ax_1(t) + bx_2(t)$.

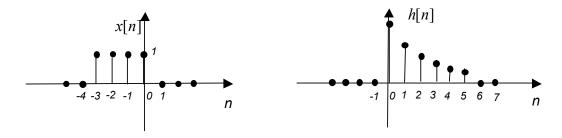
Then
$$y(t) = \frac{ax_1(t) + bx_2(t)}{1 + ax_1(t-1) + bx_2(t-1)} \neq \frac{ax_1(t)}{1 + x_1(t-1)} + \frac{bx_2(t)}{1 + x_2(t-1)} = ay_1(t) + by_2(t)$$

- (c) The system has $\underline{\text{memory}}$ since for time t it uses the past value of the input x(t-1).
- (d) The system is causal as the output is a function of past and current values of the input only.

Problem 3 (30 marks)

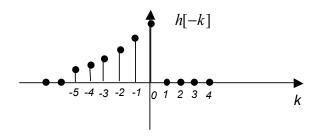
Compute the response of an LTI system described by its impulse response

$$h[n] = \begin{cases} (0.8)^n, & 0 \le n \le 5 \\ 0, & \text{otherwise} \end{cases}$$
 to the input signal shown below.



Answer:

We break down the problem into 5 intervals for n.



For n < -3: h[n-k] is zero for k>0, hence y[n] = 0.

For $-3 \le n \le 0$: Then $g[k] = x[k]h[n-k] \ne 0$ for k = -3,...,n. We get

$$y[n] = \sum_{k=-3}^{n} g[k] = \sum_{k=-3}^{n} (0.8)^{n-k} = (0.8)^{n} \sum_{m=0}^{n+3} (0.8)^{-(m-3)} = (0.8)^{n+3} \sum_{m=0}^{n+3} (0.8)^{-m}$$
$$= (0.8)^{n+3} \left(\frac{1 - (0.8^{-1})^{n+4}}{1 - (0.8)^{-1}} \right)$$
$$= \frac{(0.8)^{n+4} - 1}{-0.2} = 5 - 5(0.8)^{n+4}$$

For $1 \le n \le 2$: Then $g[k] = x[k]h[n-k] \ne 0$ for k = -3, ..., 0. We get

$$y[n] = \sum_{k=-3}^{0} g[k] = \sum_{k=-3}^{0} (0.8)^{n-k} = (0.8)^{n} \sum_{m=0}^{3} (0.8)^{-(m-3)} = (0.8)^{n+3} \sum_{m=0}^{3} (0.8)^{-m}$$
$$= (0.8)^{n+3} \left(\frac{1 - (0.8^{-1})^{4}}{1 - (0.8)^{-1}} \right)$$
$$= \frac{(0.8)^{n+4} - (0.8)^{n}}{-0.2} = \left[5 - 5(0.8)^{4} \right] (0.8)^{n}$$

For $3 \le n \le 5$: Then $g[k] = x[k]h[n-k] \ne 0$ for $n-5 \le k \le 0$. We have

$$y[n] = \sum_{k=n-5}^{0} g[k] = \sum_{k=n-5}^{0} (0.8)^{n-k} = \sum_{m=0}^{5-n} (0.8)^{n-(m+n-5)} = (0.8)^{5} \sum_{m=0}^{5-n} (0.8)^{-m}$$
$$= (0.8)^{5} \left(\frac{1 - (0.8^{-1})^{6-n}}{1 - (0.8)^{-1}} \right)$$
$$= \frac{(0.8)^{6} - (0.8)^{n}}{-0.2} = 5(0.8)^{n} - 5(0.8)^{6}$$

<u>Finally for $n \ge 6$ the two signals x[k], h[n-k] don't overlap, so y[n] = 0.</u>

In summary, the output signal of the LTI system is

$$y[n] = \begin{cases} 0, & n \le -4 \\ 5 - 5(0.8)^{n+4}, & -3 \le n \le 0 \\ \left[5 - 5(0.8)^4\right](0.8)^n, & 1 \le n \le 2 \\ 5(0.8)^n - 5(0.8)^6, & 3 \le n \le 5 \\ 0, & n \ge 6 \end{cases}$$

Problem 4 (25 marks)

Compute the impulse response h[n] of the following causal LTI second-order difference system initially at rest:

$$y[n] + \sqrt{3}y[n-1] + y[n-2] = x[n-1] + x[n-2]$$

Simplify your expression of h[n] to obtain a real function of time.

Answer:

$$y[n] + \sqrt{3}y[n-1] + y[n-2] = x[n-1] - x[n-2]$$

Write:

$$y[n] + \sqrt{3}y[n-1] + y[n-2] = \delta[n]$$

Initial conditions for the homogeneous equation for n > 0 are y[0] = 1, y[-1] = 0.

characteristic polynomial and zeros:

$$p(z)=z^2+\sqrt{3}z+1=(z-e^{j\frac{5\pi}{6}})(z-e^{-j\frac{5\pi}{6}})$$
 The zeros are $z_1=e^{j\frac{5\pi}{6}}$, $z_2=e^{-j\frac{5\pi}{6}}$.

The homogeneous response for n > 0 is given by

$$h_a[n] = A(e^{j\frac{5\pi}{6}})^n + B(e^{-j\frac{5\pi}{6}})^n.$$

Use initial conditions to compute the coefficients A and B:

$$h_a[-1] = 0 = Ae^{-j\frac{5\pi}{6}} + Be^{j\frac{5\pi}{6}}$$

 $h_a[0] = 1 = A + B$

We get $A = e^{j\frac{\pi}{3}}$, $B = e^{-j\frac{\pi}{3}}$,

the homogeneous response is

$$h_a[n] = \left[e^{j\frac{\pi}{3}} (e^{j\frac{5\pi}{6}})^n + e^{-j\frac{\pi}{3}} (e^{-j\frac{5\pi}{6}})^n \right] u[n]$$

$$= 2\operatorname{Re}\left\{ e^{j(\frac{5\pi}{6}n + \frac{\pi}{3})} \right\} u[n] = 2\cos(\frac{5\pi}{6}n + \frac{\pi}{3})u[n]$$

The impulse response is:

$$h[n] = h_a[n-1] + h_a[n-2]$$

$$= 2\cos(\frac{5\pi}{6}(n-1) + \frac{\pi}{3})u[n-1] + 2\cos(\frac{5\pi}{6}(n-2) + \frac{\pi}{3})u[n-2]$$