

# **ECSE 210: Circuit Analysis**

## **Lecture #9: Second Order Circuits**

# Example 3: Critically Damped

$$C=0.125\text{F}$$

$$R_1=10\Omega$$

$$L=2\text{H}$$

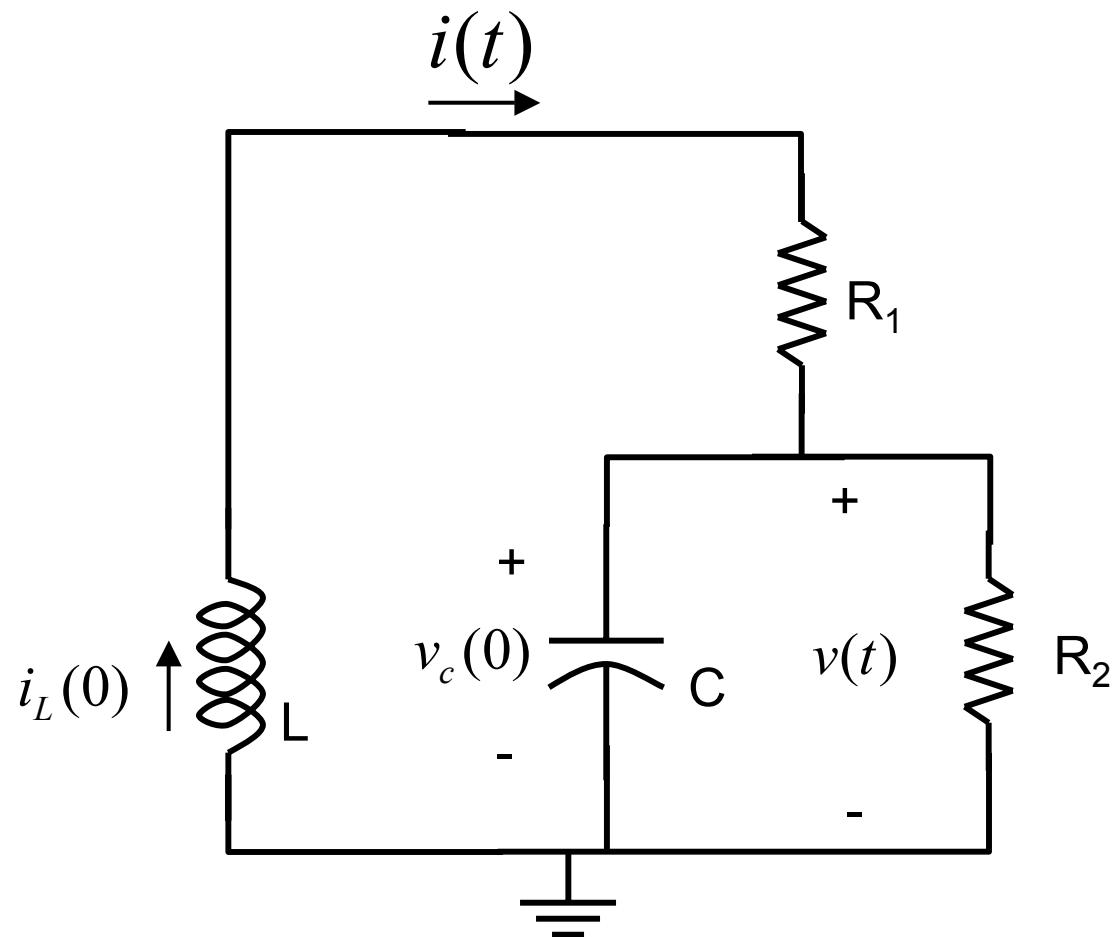
$$R_2=8\Omega$$

$$i_L(0)=0.5A$$

$$v_c(0)=1V$$

KVL     $L \frac{di}{dt} + R_1 i + v = 0$

KCL     $i(t) = C \frac{dv}{dt} + \frac{v}{R_2}$



Combine two first order ODE's into one second-order ODE in  $v(t)$  and solve.

# Example 3: Critically Damped

KVL       $L \frac{di}{dt} + R_1 i + v = 0$

KCL       $i(t) = C \frac{dv}{dt} + \frac{v}{R_2}$

$$\frac{di}{dt} = C \frac{d^2v}{dt^2} + \frac{1}{R_2} \frac{dv}{dt}$$

**KVL**       $L \left( C \frac{d^2v}{dt^2} + \frac{1}{R_2} \frac{dv}{dt} \right) + R_1 \left( C \frac{dv}{dt} + \frac{v}{R_2} \right) + v = 0$

$$LC \frac{d^2v}{dt^2} + \left( \frac{L}{R_2} + R_1 C \right) \frac{dv}{dt} + \left( R_1 + \frac{1}{R_2} \right) v = 0$$

$$\frac{d^2v}{dt^2} + \left( \frac{1}{R_2 C} + \frac{R_1}{L} \right) \frac{dv}{dt} + \left( \frac{R_1 + R_2}{R_2 L C} \right) v = 0$$

## Example 3: Critically Damped

$$\frac{d^2v}{dt^2} + \left( \frac{1}{R_2C} + \frac{R_1}{L} \right) \frac{dv}{dt} + \left( \frac{R_1 + R_2}{R_2LC} \right) v = 0$$

$$\frac{d^2v}{dt^2} + 6 \frac{dv}{dt} + 9v = 0$$

Recall

$$\frac{d^2x(t)}{dt^2} + 2\alpha \frac{dx(t)}{dt} + \omega_o^2 x(t) = 0$$

Damping coefficient  $\alpha = 3$

Resonant Frequency  $\omega_o = 3$

→ Critically damped response

$$s^2 + 6s + 9 = 0$$

→ Roots  $\lambda_1 = -3$  and  $\lambda_2 = -3$ . The roots are real and equal

## Example 3: Critically Damped

$$C=0.125\text{F}$$

$$R_1=10\Omega$$

$$L=2\text{H}$$

$$R_2=8\Omega$$

$$i_L(0)=0.5\text{A}$$

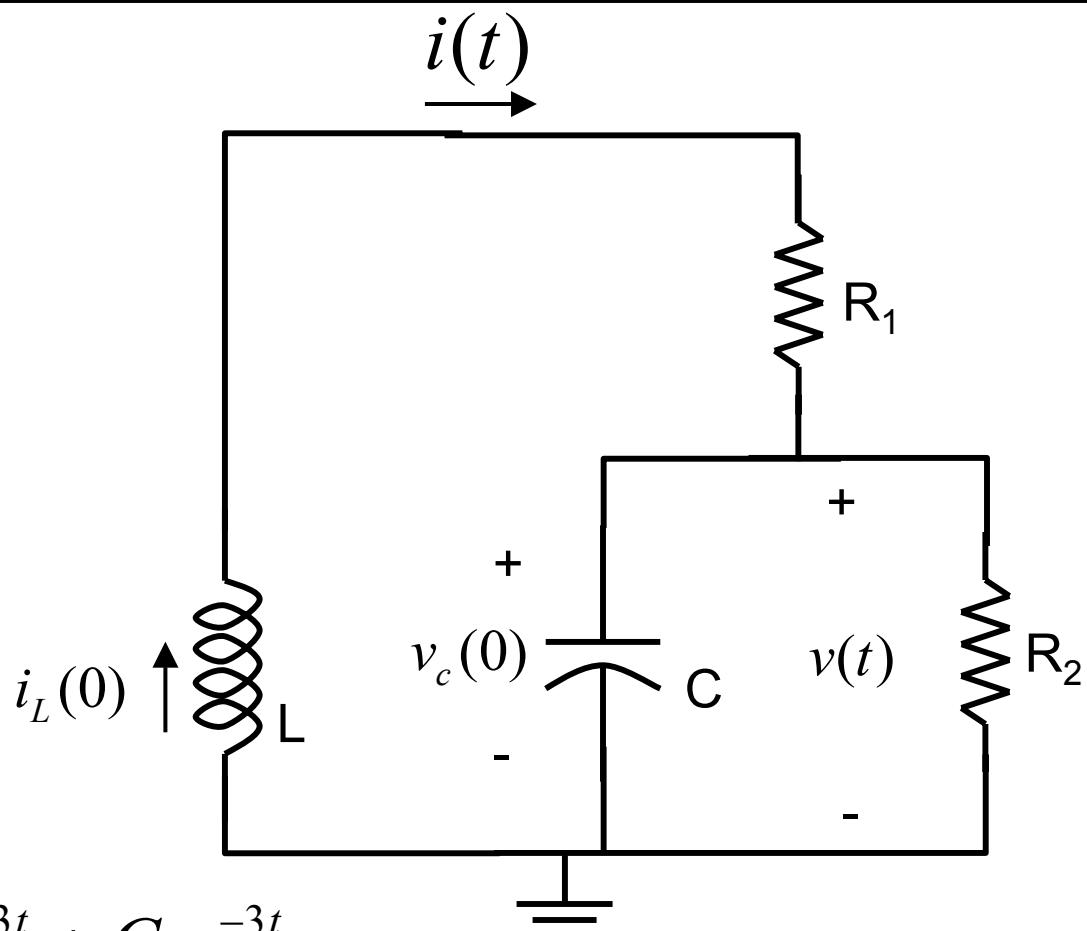
$$v_c(0)=1\text{V}$$

$$v(t) = C_1 e^{-3t} + C_2 t e^{-3t}$$

$$v(0) = C_1 = 1\text{V}$$

$$\frac{dv(t)}{dt} = -3C_1 e^{-3t} - 3C_2 e^{-3t} + C_2 e^{-3t}$$

$$\frac{dv(0)}{dt} = -3C_1 + C_2$$



## Example 3: Critically Damped

$$C=0.125\text{F}$$

$$R_1=10\Omega$$

$$i_L(0)=0.5A$$

$$L=2\text{H}$$

$$R_2=8\Omega$$

$$v_c(0)=1V$$

$$\frac{dv(0)}{dt} = -3C_1 + C_2$$

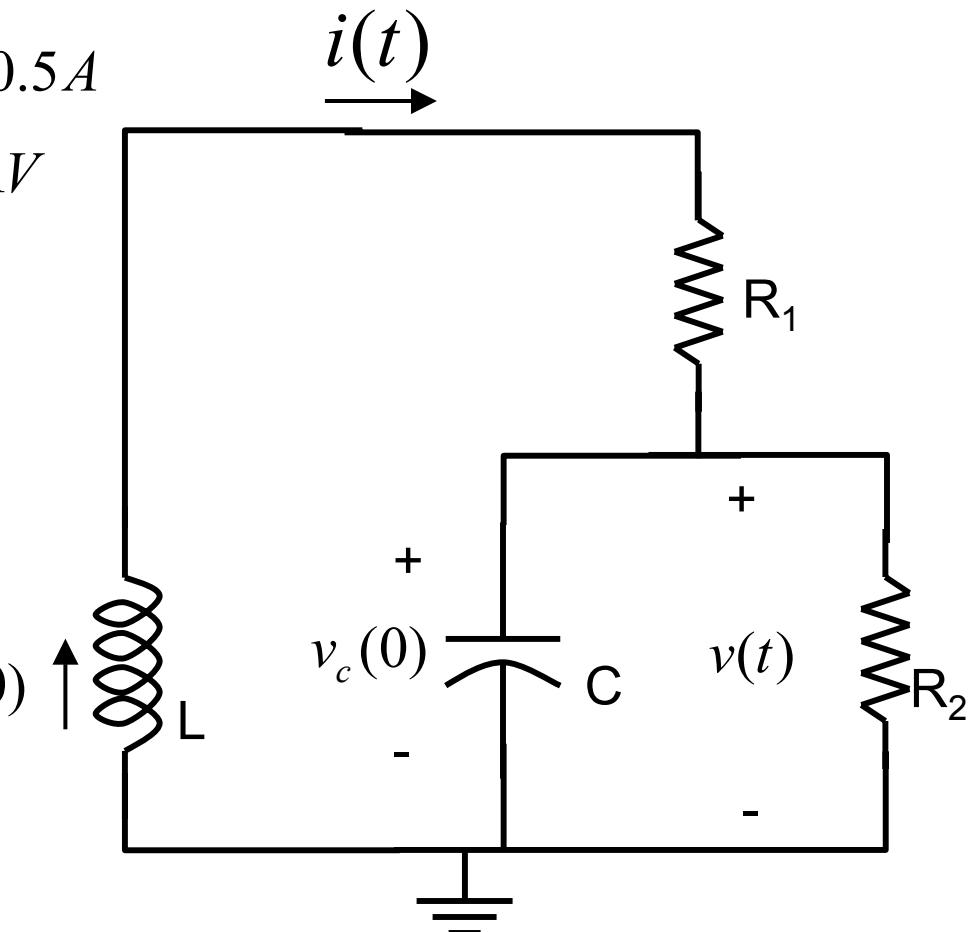
KCL     $C \frac{dv}{dt} + \frac{v}{R_2} - i = 0$

$$\frac{dv(0)}{dt} = -\frac{v(0)}{CR_2} + \frac{i(0)}{C} = -\frac{1}{CR_2} + \frac{4}{C} = -\frac{1}{2} + 4 = 3$$

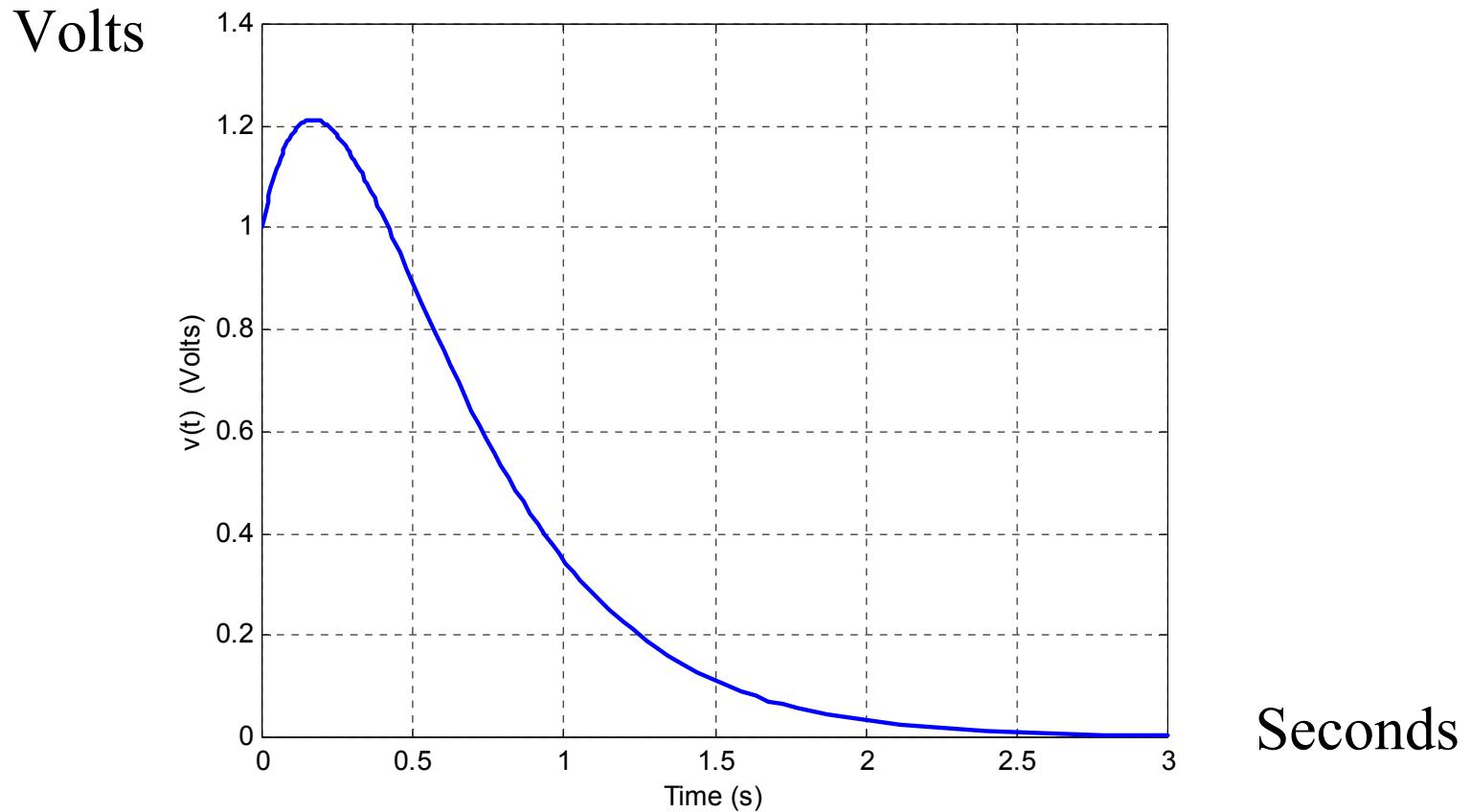
$$-3C_1 + C_2 = 3$$

$$C_1 = 1 \quad C_2 = 6$$

$$\rightarrow v(t) = e^{-3t} + 6te^{-3t} \text{ V}$$



## Example 3: Critically Damped



$$\rightarrow v(t) = e^{-3t} + 6te^{-3t}$$

# Example 3: Critically Damped

$$C=0.125\text{F}$$

$$R_1=10\Omega$$

$$i_L(0) = 0.5A$$

$$L=2\text{H}$$

$$R_2=8\Omega$$

$$v_c(0) = 1V$$

$$i(t) = ?$$

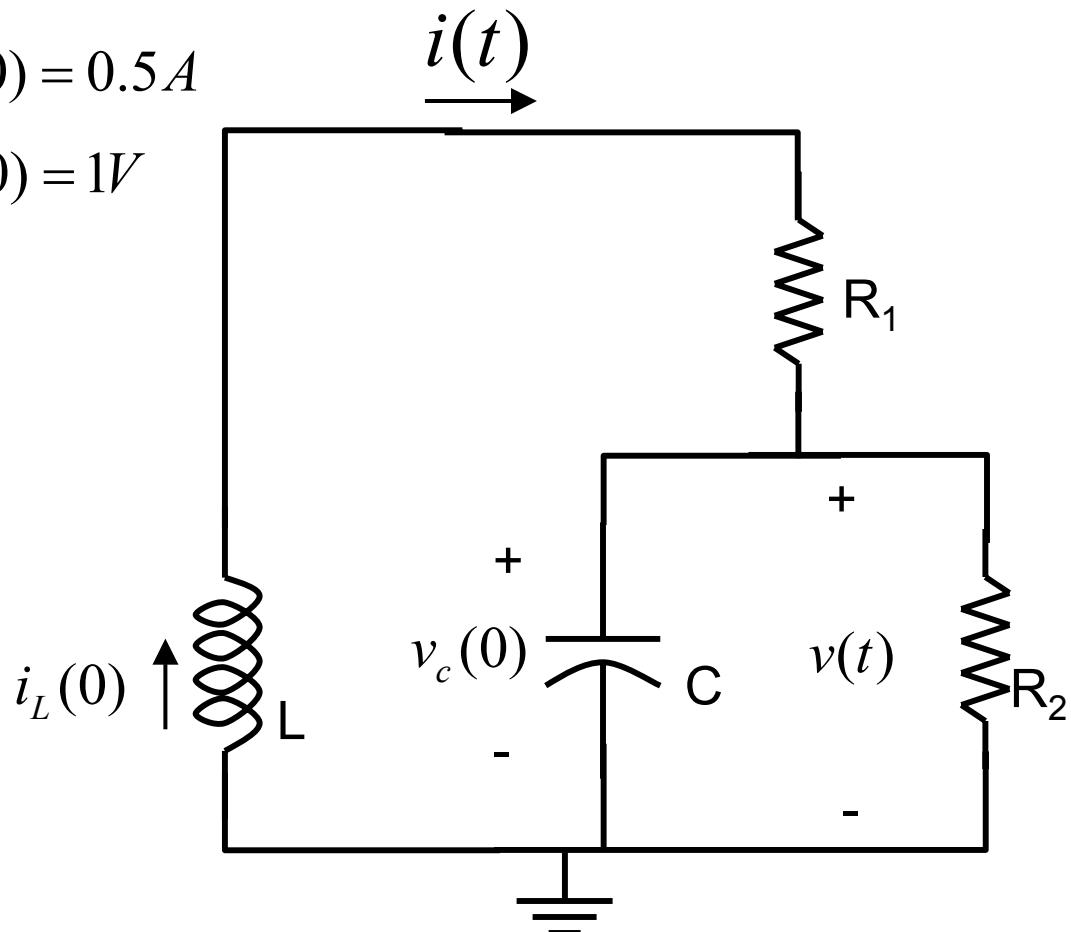
$$i(t) = C_1 e^{-3t} + C_2 t e^{-3t}$$

$$i(0) = C_1 = 0.5$$

$$\frac{di(0)}{dt} = -3C_1 + C_2$$

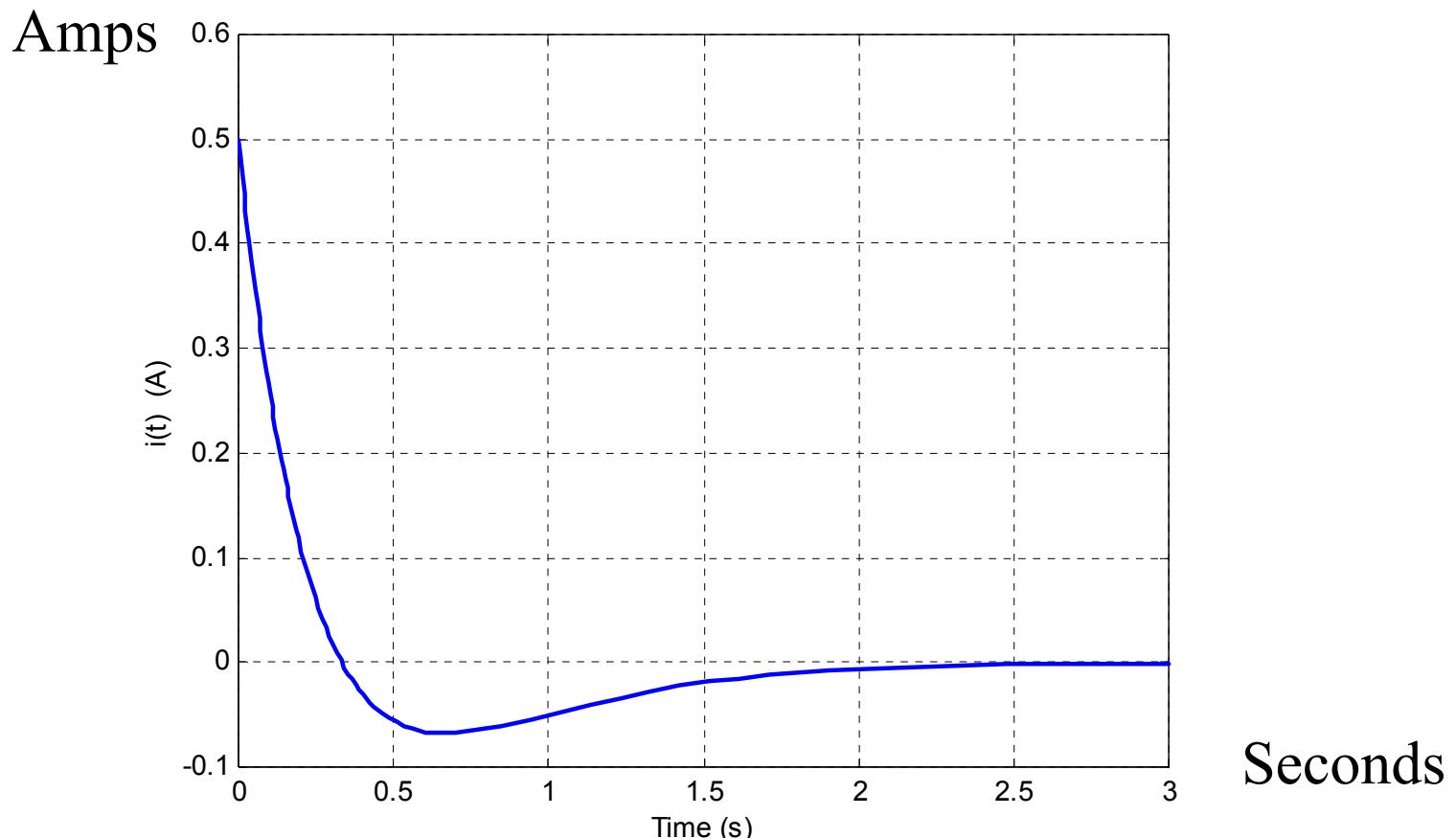
$$\underline{\text{KVL}} \quad L \frac{di}{dt} + R_1 i + v = 0$$

$$\frac{di(0)}{dt} = -\frac{R_1}{L} i(0) - \frac{v(0)}{L} = -3$$



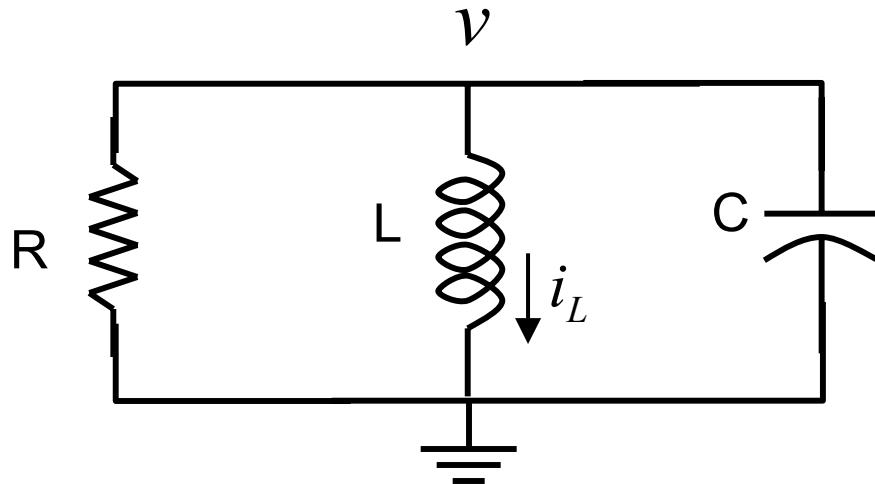
$$\left. \begin{array}{l} C_1 = 0.5 \\ -3C_1 + C_2 = -3 \end{array} \right\} C_2 = -1.5$$

# Example 3: Critically Damped



$$\rightarrow i(t) = 0.5e^{-3t} - 1.5te^{-3t} \quad t > 0$$

# Back to Example 1: Overdamped



$$R=2\Omega$$

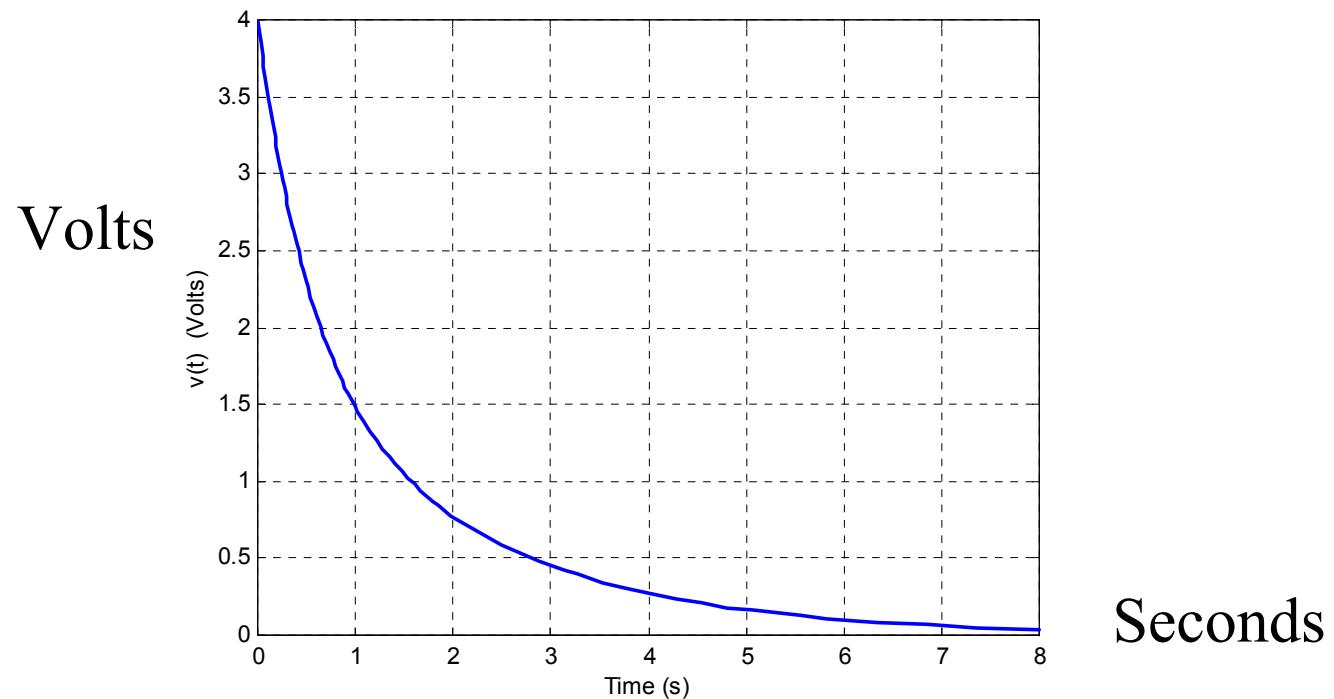
$$i_L(0) = -1A$$

$$L=5H$$

$$v(0) = 4V$$

$$C=0.2F$$

$$\rightarrow v(t) = 2e^{-2t} + 2e^{-0.5t} \text{ V}$$



## Back to Example 2: Underdamped

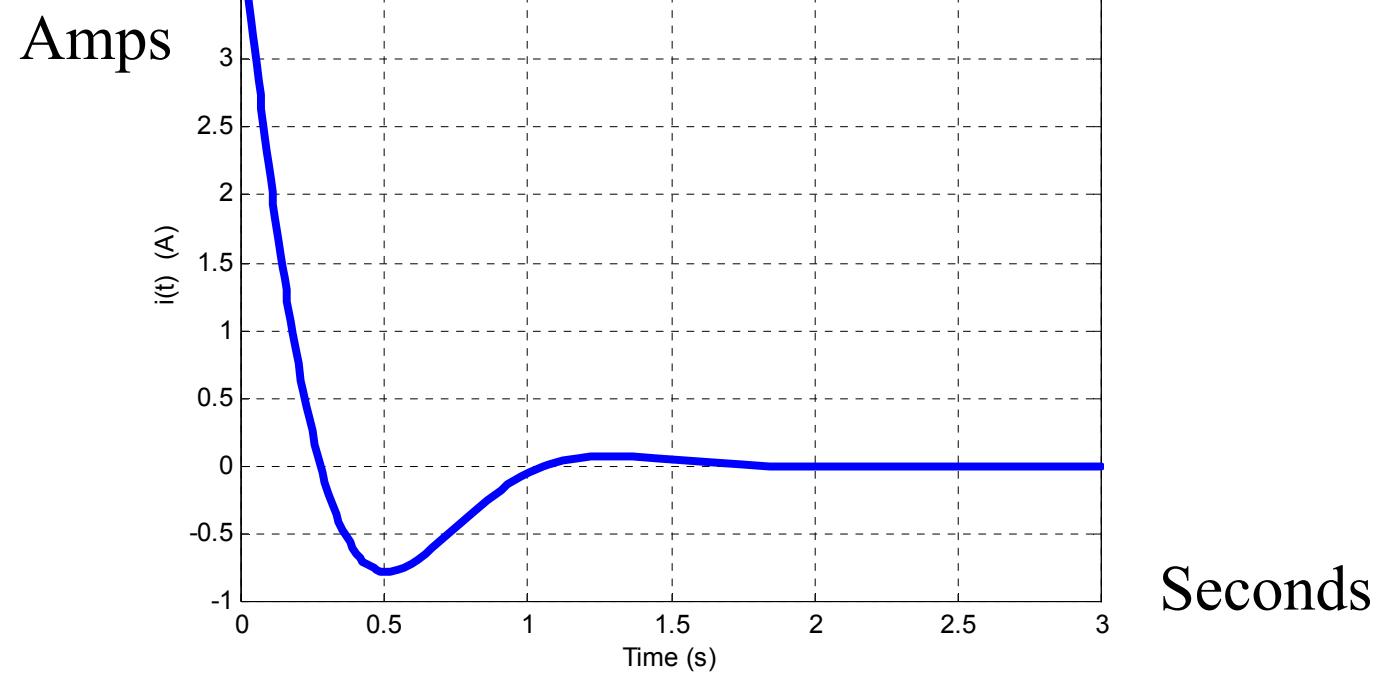
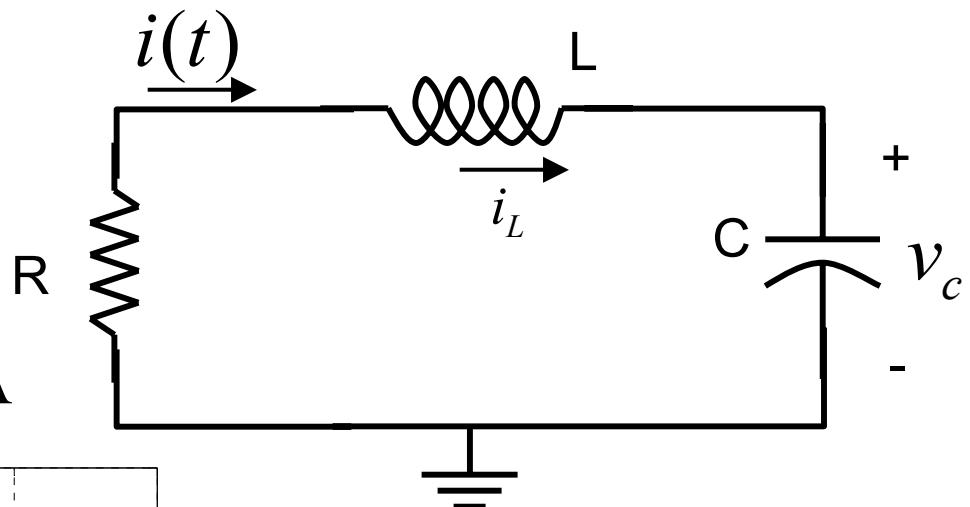
$$R=6\Omega$$

$$i_L(0) = 4A$$

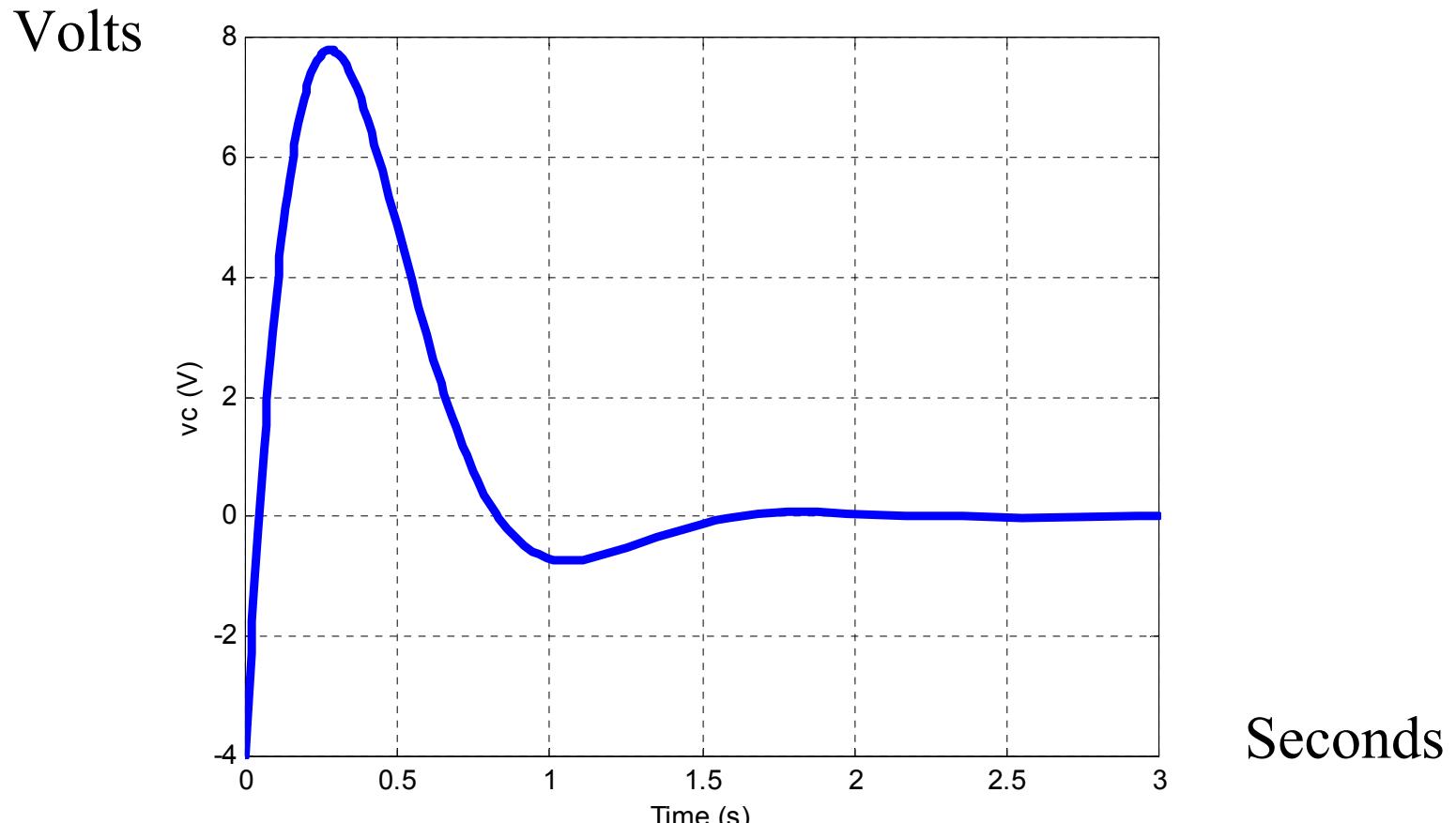
$$L=1H$$

$$C=0.04F \quad v_c(0) = -4V$$

$$i(t) = 4e^{-3t} \cos(4t) - 2e^{-3t} \sin(4t) \text{ A}$$



## Back to Example 2: Underdamped



$$\rightarrow v_c(t) = -4e^{-3t} \cos(4t) + 22e^{-3t} \sin(4t) \text{ V} \quad t > 0$$

# The Forced Response

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Recall:  $x(t) = x_n + x_f$

Solves:  $\frac{d^2x(t)}{dt} + a_1 \frac{dx}{dt} + a_2 x = f(t)$

Where:

→  $x_n$  is the homogeneous solution or the natural response

→  $x_f$  is the particular solution or the forced response

How is  $x_f$  determined? → Guessing method.

# Common Guesses for $x_f$

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$$f(t)$$

$$x_f(t)$$

---

$$k$$

$$A$$

$$t$$

$$At + B$$

$$t^2$$

$$At^2 + Bt + C$$

$$e^{at}$$

$$Ae^{at}$$

$$\sin(bt), \cos(bt)$$

$$A \sin(bt) + B \cos(bt)$$

$$e^{at} \sin(bt), e^{at} \cos(bt)$$

$$e^{at} (A \sin(bt) + B \cos(bt))$$

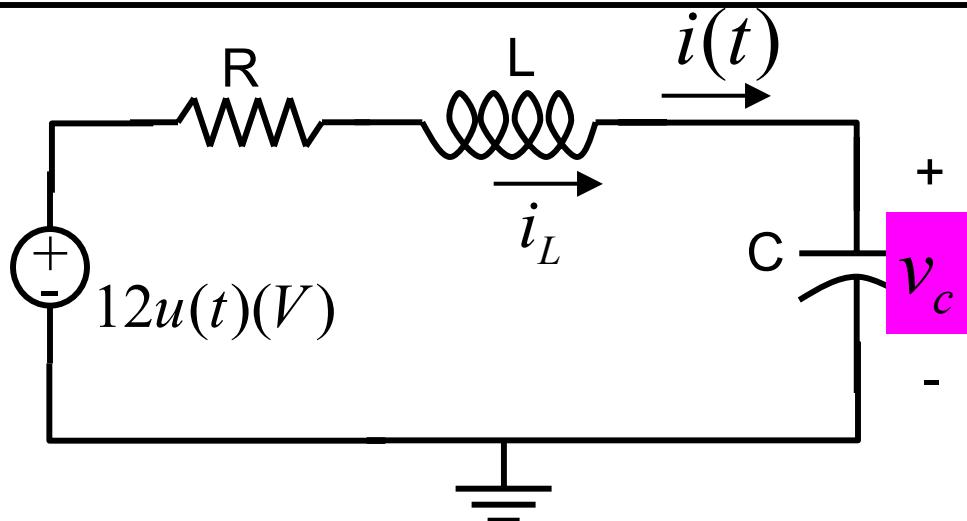
# Example: Forced Response

$$R=6\Omega$$

$$i_L(0) = 4A$$

$$L=1H$$

$$C=0.04F \quad v_c(0) = -4V$$



KVL     $Ri + L \frac{di}{dt} + v_c = 12 \quad t > 0$

KCL     $i(t) = C \frac{dv_c}{dt} \quad \rightarrow \quad \frac{di}{dt} = C \frac{d^2v_c}{dt^2} \quad t > 0$

Combine two equations:     $RC \frac{dv_c}{dt} + LC \frac{d^2v_c}{dt^2} + v_c = 12$

$$\frac{d^2v_c}{dt^2} + \frac{R}{L} \frac{dv_c}{dt} + \frac{1}{LC} v_c = \frac{12}{LC}$$

# Example: Forced Response

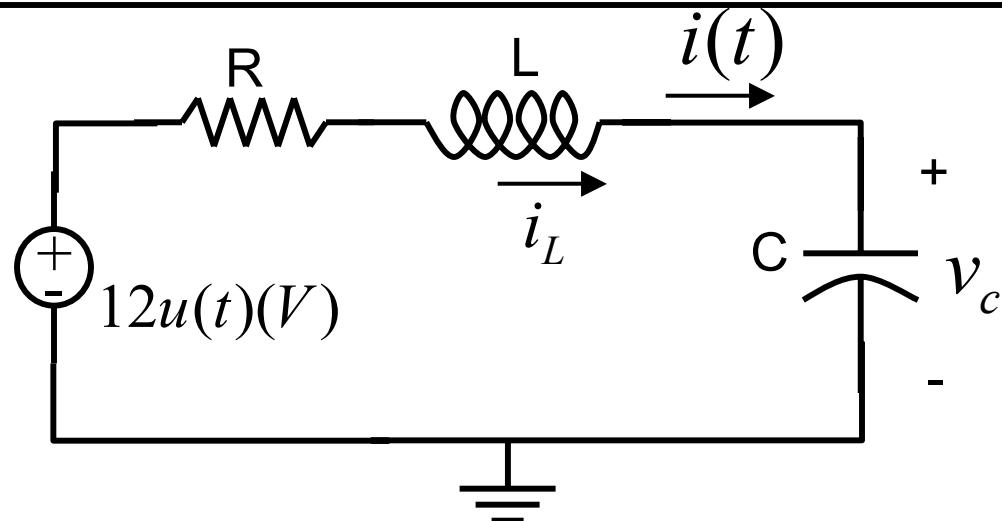
$$R=6\Omega$$

$$i_L(0) = 4A$$

$$L=1H$$

$$C=0.04F \quad v_c(0) = -4V$$

$$\frac{d^2v_c}{dt^2} + \frac{R}{L} \frac{dv_c}{dt} + \frac{1}{LC} v_c = \frac{12}{LC}$$



$$\underbrace{\frac{d^2v_c}{dt^2} + 6\frac{dv_c}{dt} + 25v_c}_{= 300} = 300$$

Same as Lecture 8

$$v_c(t) = v_f + v_n$$

Now we have a forcing function.

# Example: Forced Response

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The natural or homogeneous solution has the **form (see Lecture 8)**:

$$v_n(t) = B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

The particular solution or forced response has the **form (see Table)**:

$$v_f(t) = A \quad \text{a constant}$$

Therefore the total solution is:

$$v_c(t) = A + B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

**Find the three constants!**

# Example: Forced Response

$$R=6\Omega$$

$$i_L(0) = 4A$$

$$L=1H$$

$$C=0.04F \quad v_c(0) = -4V$$

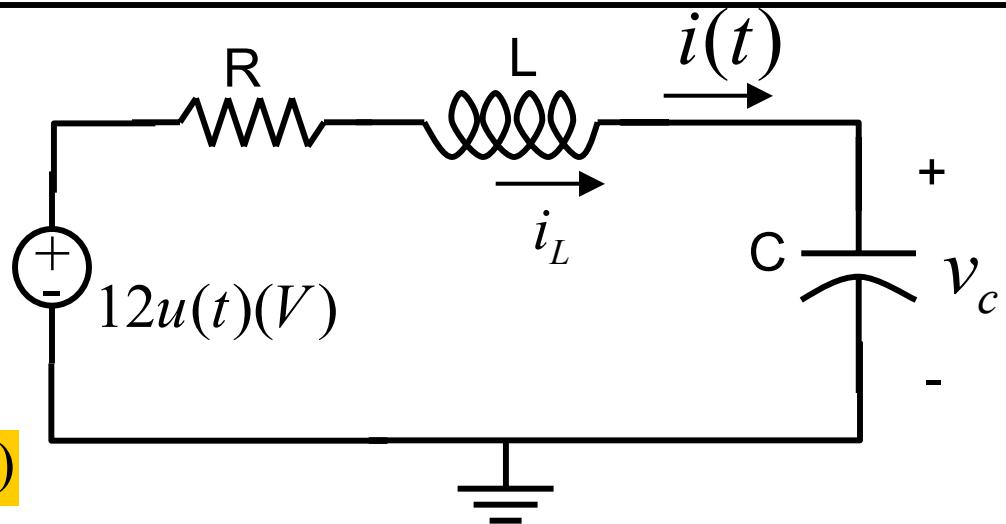
$$v_c(t) = A + B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

$$v_c(0) = A + B_1 = -4$$

$$v_c(\infty) = A = 12 \rightarrow B_1 = -16$$

$$\frac{dv_c(0)}{dt} = -3B_1 + 4B_2$$

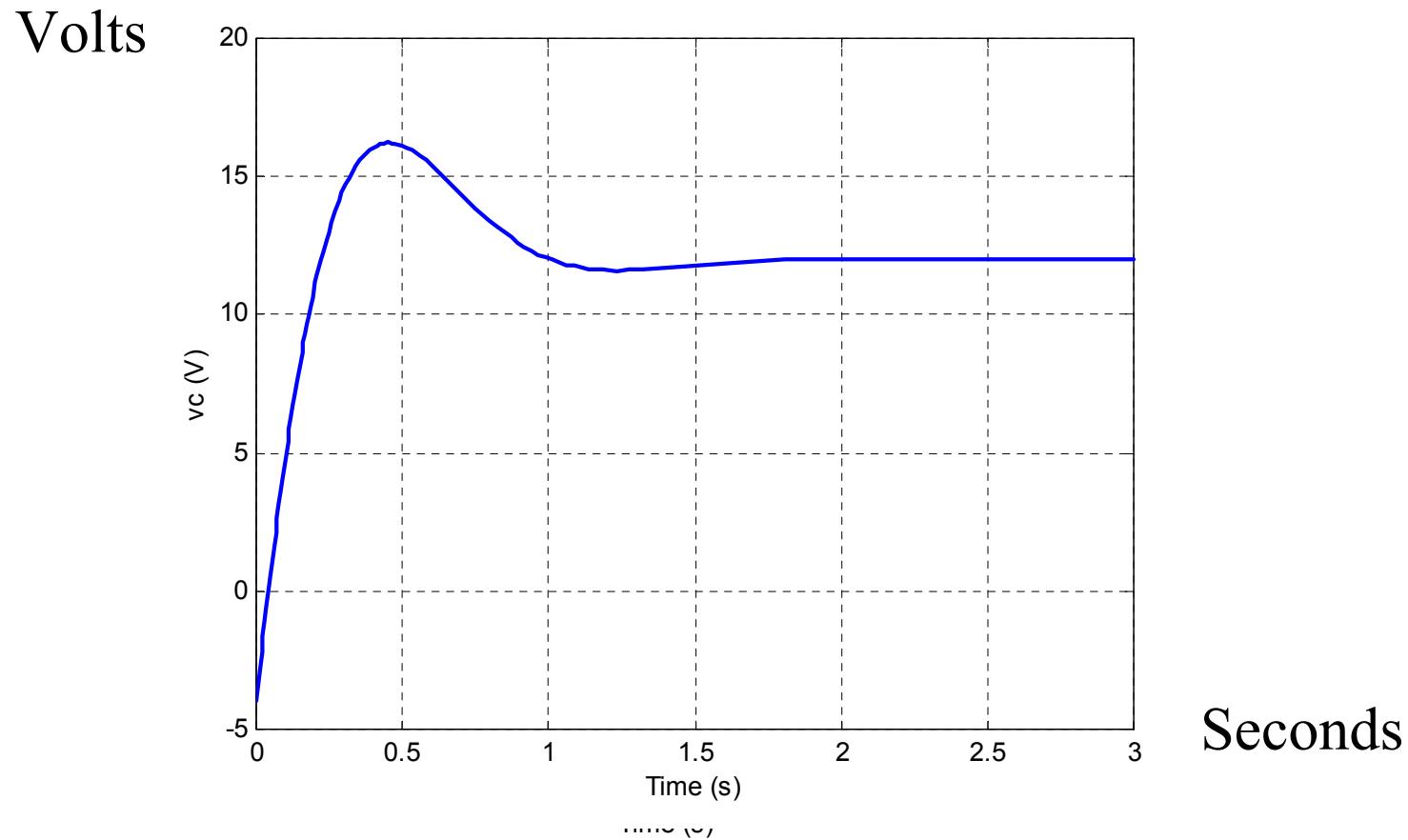
$$C \frac{dv_c(0)}{dt} = i_L(0) \rightarrow \frac{dv_c(0)}{dt} = \frac{i_L(0)}{C} = 100$$



$$\rightarrow -3B_1 + 4B_2 = 100$$

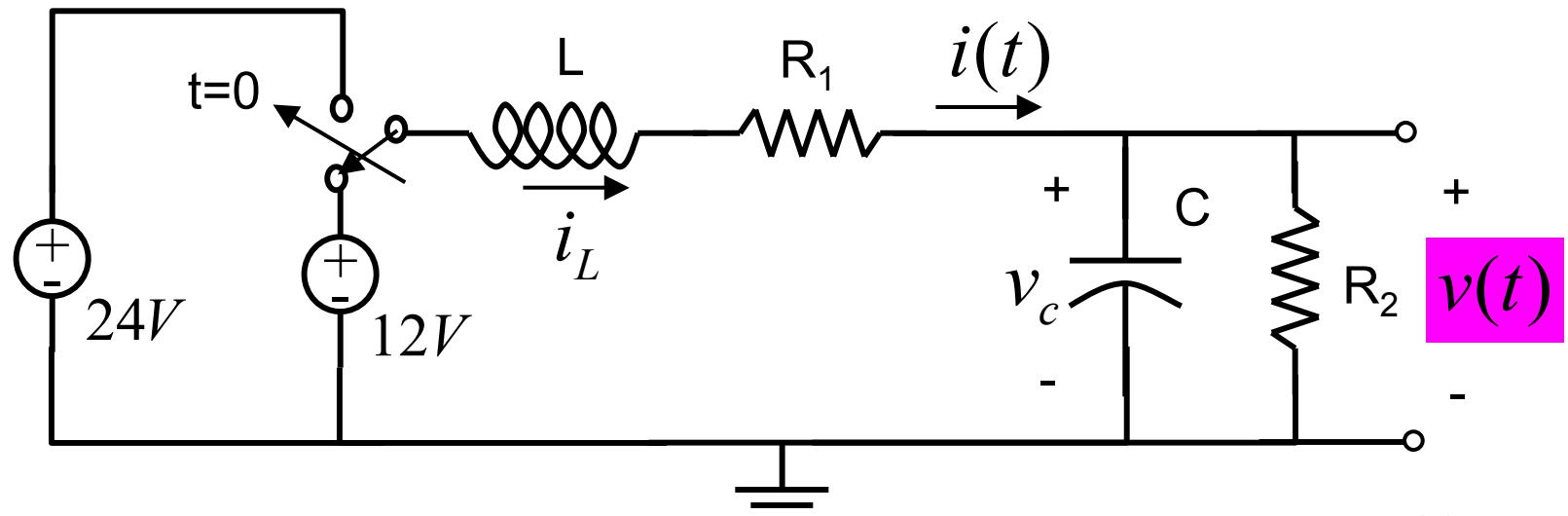
$$\rightarrow B_2 = 13$$

# Example: Forced Response



$$v_c(t) = 12 - 16e^{-3t} \cos(4t) + 13e^{-3t} \sin(4t)$$

# Example: Forced Response



$t > 0$

KVL       $L \frac{di}{dt} + R_1 i + v = 24$        $R_1 = 10\Omega$

KCL       $i(t) = C \frac{dv}{dt} + \frac{v}{R_2}$        $R_2 = 2\Omega$

$$L = 2H$$

$$C = 0.25F$$

**Combining equations**      
$$\frac{dv^2}{dt^2} + \left( \frac{1}{R_2 C} + \frac{R_1}{L} \right) \frac{dv}{dt} + \left( \frac{R_1 + R_2}{R_2 LC} \right) v = \frac{24}{LC}$$

# Example: Forced Response

$$\frac{dv^2}{dt^2} + \left( \frac{1}{R_2 C} + \frac{R_1}{L} \right) \frac{dv}{dt} + \left( \frac{R_1 + R_2}{R_2 L C} \right) v = \frac{24}{LC}$$

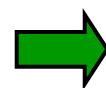
$$\frac{dv^2}{dt^2} + 7 \frac{dv}{dt} + 12v = 48$$

$$v(t) = v_f + v_n$$

Solution of homogeneous equation

Forced response (constant in this case)

Homogeneous equation



$$\frac{dv^2}{dt^2} + 7 \frac{dv}{dt} + 12v = 0$$

# Example: Forced Response

Homogeneous equation

$$\rightarrow \frac{dv^2}{dt^2} + 7 \frac{dv}{dt} + 12v = 0$$

Characteristic equation

$$\rightarrow s^2 + 7s + 12 = 0$$

Roots

$$\rightarrow \lambda_1 = -3 \quad \lambda_2 = -4$$

**Overdamped Response**

The natural response has the form:

$$v_n = C_1 e^{-3t} + C_2 e^{-4t}$$

The total response has the form:

$$v(t) = A + C_1 e^{-3t} + C_2 e^{-4t}$$

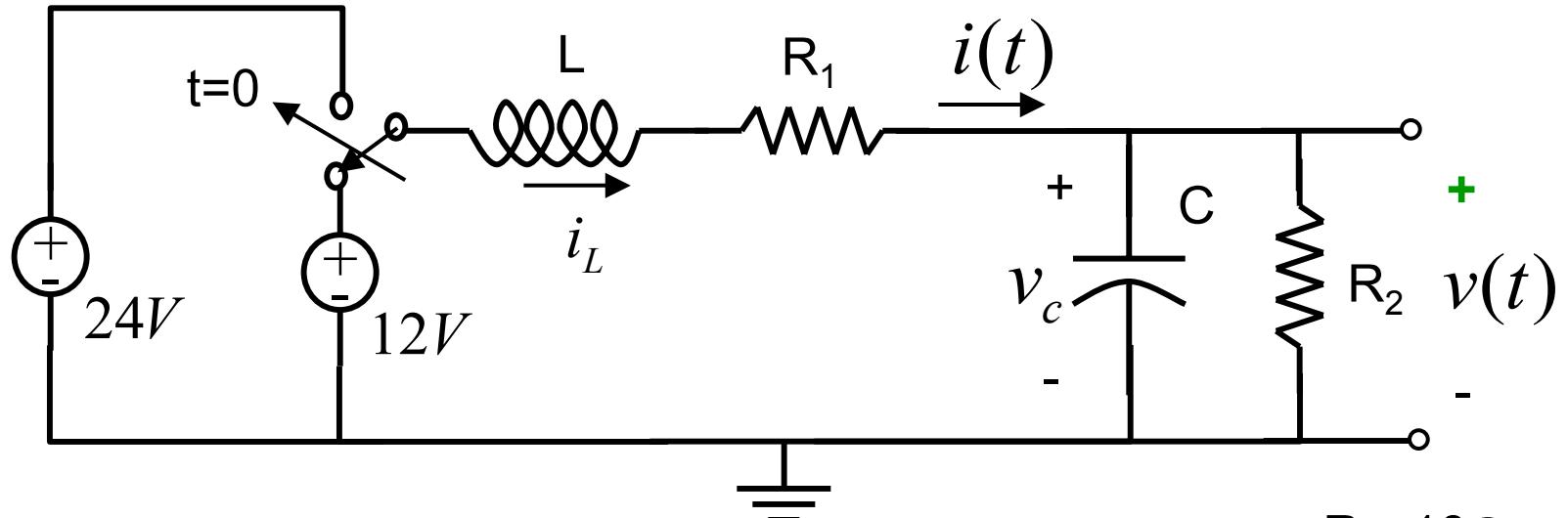
**Find constants:**

**At steady-state derivatives  
are zero (or use circuit)**

$$\frac{dv^2}{dt^2} + 7 \frac{dv}{dt} + 12v = 48$$

$$v(\infty) = A = 4$$

# Example: Forced Response



$$v(t) = A + C_1 e^{-3t} + C_2 e^{-4t}$$

$$R_1 = 10\Omega$$

$$R_2 = 2\Omega$$

$$L = 2H$$

$$C = 0.25F$$

$$\star v(\infty) = A = 4$$

**Switch in position 2**

$$\odot v(0) = A + C_1 + C_2 = 2$$

**Switch in position 1**

$$\frac{dv(0)}{dt} = -3C_1 - 4C_2$$

$$\frac{dv(0)}{dt} = \frac{i(0)}{C} - \frac{v(0)}{CR_2} = 0$$

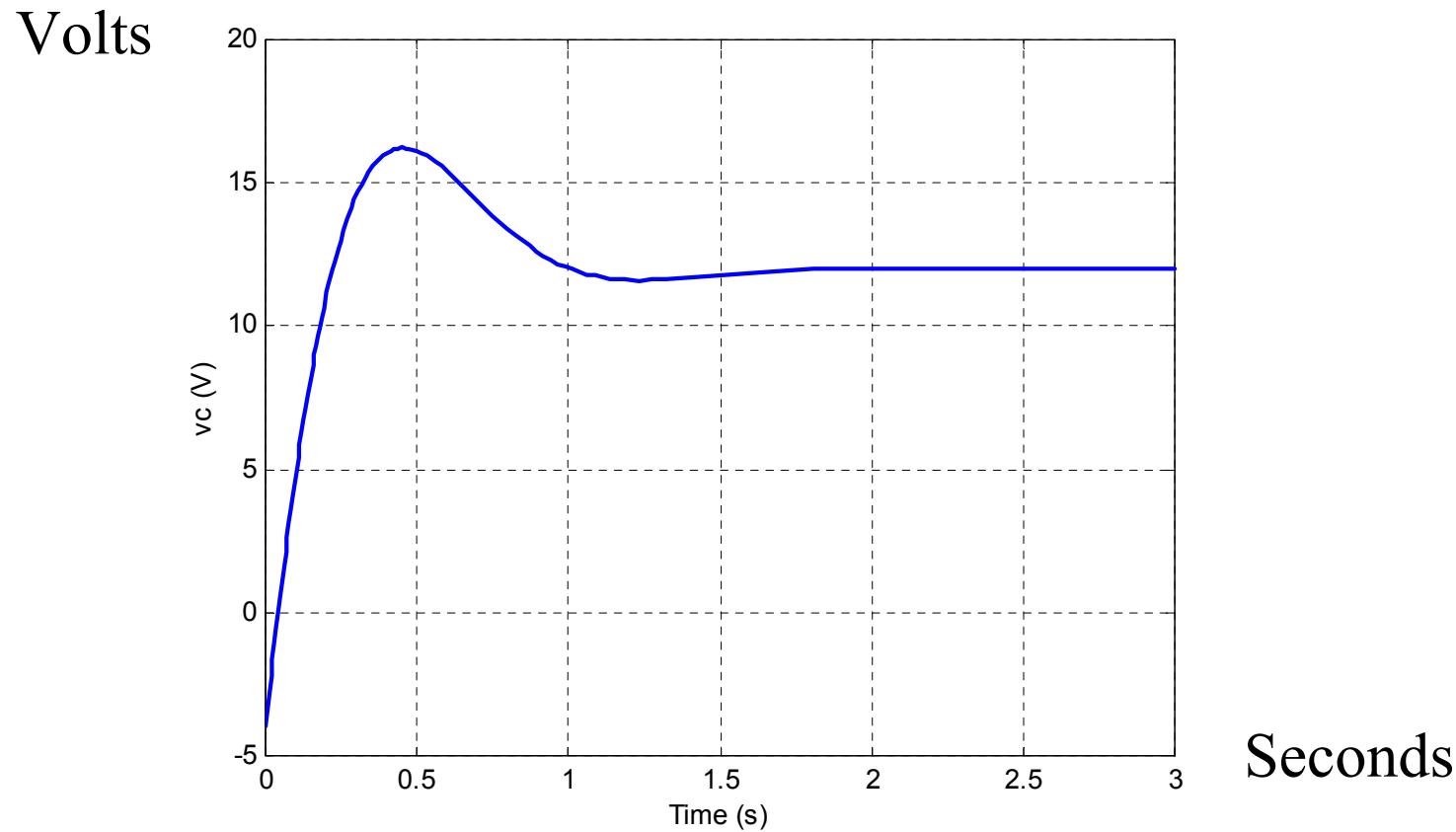
Top equation

KCL at + output

$$\odot 3C_1 - 4C_2 = 0$$

$$\uparrow C_1 = -8 \quad C_2 = 6$$

# Example: Forced Response



$$v(t) = 4 - 8e^{-3t} + 6e^{-4t}$$