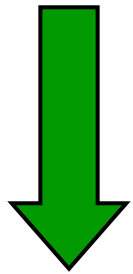


ECSE 210: Circuit Analysis

Lecture #8: Second Order Circuits

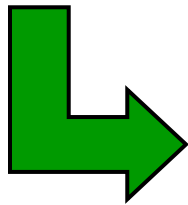
Conventions

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_2 x(t) = 0 \quad \longrightarrow \quad \text{Homogeneous Equation}$$



$$a_1 = 2\alpha \quad a_2 = \omega_o^2$$

$$\frac{d^2 x(t)}{dt^2} + 2\alpha \frac{dx(t)}{dt} + \omega_o^2 x(t) = 0$$



$$\underbrace{s^2 + 2\alpha s + \omega_o^2 = 0}$$

Characteristic equation

Conventions

$$s^2 + 2\alpha s + \omega_o^2 = 0 \quad \longrightarrow \quad \text{Characteristic equation}$$

The roots of the characteristic equation are:

$$\lambda_1, \lambda_2 = -\alpha \pm \sqrt{\alpha^2 - \omega_o^2}$$

→ α is called the exponential **damping coefficient**.

→ ω_o is called the **undamped natural frequency**.

→ The roots of the characteristic polynomial λ_1 and λ_2 are called the natural frequencies of the circuit because they determine the natural (unforced) response.

Three Solution Types

→ Type 1: **Overdamped**

$\alpha > \omega_o$ → λ_1 and λ_2 are **real** and **unequal**

$$x_n(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$$

?

→ The natural response is the sum of two decaying exponentials

→ Type 2: **Critically damped**

$\alpha = \omega_o$ → λ_1 and λ_2 are **real** and **equal**

$$\lambda_1 = \lambda_2 = -\alpha$$

$$x_n(t) = C_1 e^{-\alpha t} + C_2 t e^{-\alpha t}$$

Three Solution Types

→ Type 3: **Underdamped**

$\alpha < \omega_o \rightarrow \lambda_1$ and λ_2 are **complex** and **unequal**

$$\lambda_1, \lambda_2 = -\alpha \pm j\sqrt{\omega_o^2 - \alpha^2} = -\alpha \pm j\omega_d$$

$$x_n(t) = C_1 e^{-\alpha t} e^{j\omega_d t} + C_2 e^{-\alpha t} e^{-j\omega_d t}$$

$$x_n(t) = e^{-\alpha t} \left(C_1 e^{j\omega_d t} + C_2 e^{-j\omega_d t} \right)$$

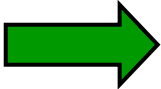
→ ω_d is called the **damped natural frequency**

→ C_1 and C_2 can be complex.

Three Solution Types

→ Type 3: Underdamped

$$x_n(t) = e^{-\alpha t} \left(C_1 e^{j\omega_d t} + C_2 e^{-j\omega_d t} \right)$$

Euler  $e^{\pm j\omega t} = \cos \omega t \pm j \sin \omega t$

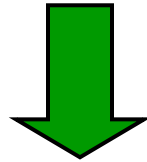
$$x_n(t) = e^{-\alpha t} \left(C_1 \cos \omega_d t + jC_1 \sin \omega_d t + C_2 \cos \omega_d t - jC_2 \sin \omega_d t \right)$$

$$x_n(t) = e^{-\alpha t} \left[(C_1 + C_2) \cos \omega_d t + j(C_1 - C_2) \sin \omega_d t \right]$$

Three Solution Types

→ Type 3: Underdamped

$$x_n(t) = e^{-\alpha t} \left[(C_1 + C_2) \cos \omega_d t + j(C_1 - C_2) \sin \omega_d t \right]$$

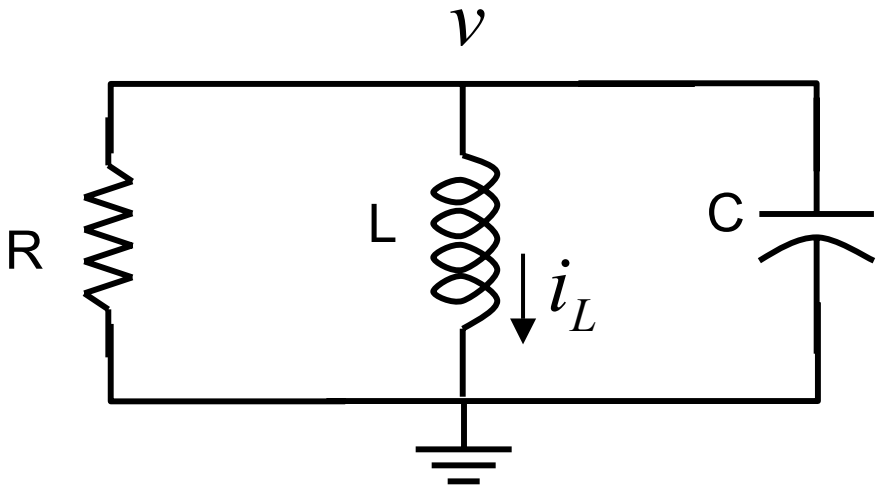


$$x_n(t) = e^{-\alpha t} \left[B_1 \cos \omega_d t + B_2 \sin \omega_d t \right]$$

- B_1 and B_2 are arbitrary constants.
- For B_1 and B_2 **to be real**, C_1 and C_2 must be complex conjugates. **This is always the case for circuits.**
- The natural underdamped response is oscillatory with an exponentially decaying magnitude.

Example: Overdamped

Find $v(t)$ and $i_L(t)$.



$$R=2\Omega$$

$$L=5\text{H}$$

$$C=0.2\text{F}$$

$$i_L(0) = -1\text{A}$$

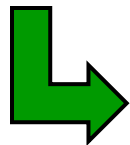
$$v(0) = 4\text{V}$$



**Given two
boundary
conditions**

KCL

$$\frac{v}{R} + \frac{1}{L} \int_0^t v(\tau) d\tau + i_L(0) + C \frac{dv}{dt} = 0$$



$$C \frac{d^2v}{dt^2} + \frac{1}{R} \frac{dv}{dt} + \frac{1}{L} v = 0$$

Example: Overdamped

$$\frac{d^2 v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

Recall

$$\frac{d^2 v}{dt^2} + 2.5 \frac{dv}{dt} + v = 0$$

$$\frac{d^2 x(t)}{dt^2} + 2\alpha \frac{dx(t)}{dt} + \omega_o^2 x(t) = 0$$

Damping Coefficient: $\alpha = \frac{1}{2RC} = 1.25$

Resonant Frequency: $\omega_o = \frac{1}{\sqrt{LC}} = 1$


$\alpha > \omega_o$  Overdamped

Example: Overdamped

$$\frac{d^2v}{dt^2} + 2.5\frac{dv}{dt} + v = 0$$

Characteristic equation: $s^2 + 2.5s + 1 = 0$

Roots: $\lambda_1, \lambda_2 = -\alpha \pm \sqrt{\alpha^2 - \omega_o^2}$

$$\lambda_1 = -2 \quad \lambda_2 = -0.5$$


Real and Unequal 

**Overdamped
Response**

$$v(t) = C_1 e^{-2t} + C_2 e^{-0.5t}$$

Example: Overdamped

$$v(t) = C_1 e^{-2t} + C_2 e^{-0.5t}$$

Find coefficients C_1 and C_2

$$v(0) = v_c(0) = C_1 + C_2 = 4$$

First boundary condition

→ Need one more equation!

→ Use $i_L(0)$

KCL

$$C \frac{dv}{dt} + \frac{v}{R} + \text{[yellow box]} = 0$$

From the circuit
Same as 1st equation

$$\rightarrow \frac{dv(0)}{dt} = -\frac{1}{RC} v(0) - \frac{1}{C} i_L(0) = -5$$

Second boundary condition

Example: Overdamped

$$v(t) = C_1 e^{-2t} + C_2 e^{-0.5t} \quad \text{Next use the proposed solution}$$

$$\frac{dv(t)}{dt} = -2C_1 e^{-2t} - 0.5C_2 e^{-0.5t}$$

$$\frac{dv(0)}{dt} = -2C_1 - 0.5C_2 = -5$$

Remember $C_1 + C_2 = 4$

$$\rightarrow C_1 = 2 \quad C_2 = 2$$

$$v(t) = 2e^{-2t} + 2e^{-0.5t} \quad ; t > 0$$

Example: Overdamped

Find the inductor current for $t > 0$.

Linear circuit $\rightarrow i_L(t)$ has the same form:

$$i_L(t) = C_1 e^{-2t} + C_2 e^{-0.5t}$$

$$i_L(0) = C_1 + C_2 = -1$$

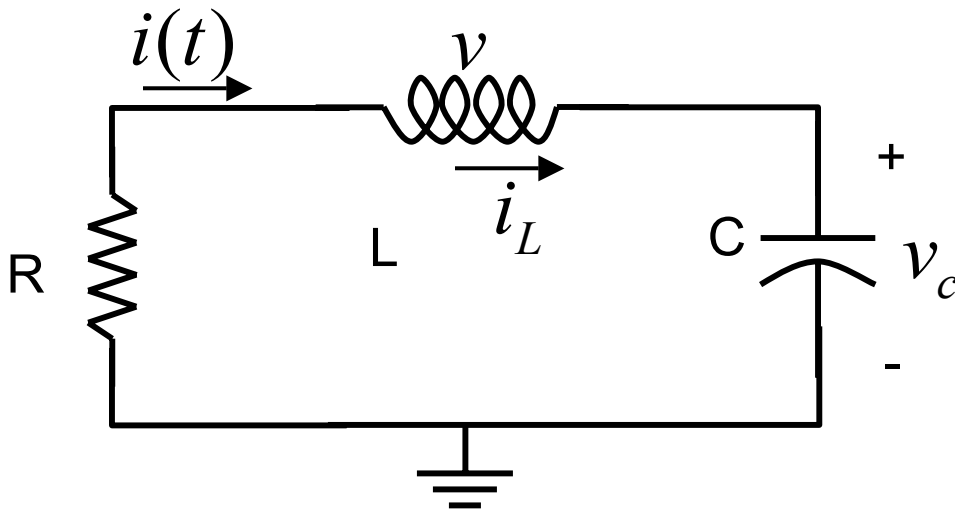
$$v(0) = L \frac{di_L(0)}{dt} = L(-2C_1 - 0.5C_2) = 4$$

$$\rightarrow C_1 = -0.2 \quad C_2 = -0.8$$

$$i_L(t) = -0.2e^{-2t} - 0.8e^{-0.5t} \quad ; t > 0$$

**Two
boundary
conditions**

Example 2: Underdamped

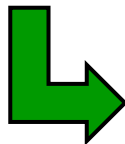


$$\begin{aligned} R &= 6\Omega & i_L(0) &= 4A \\ L &= 1\text{H} \\ C &= 0.04\text{F} & v_c(0) &= -4V \end{aligned}$$

Find $i(t)$ and $v_c(t)$

KVL

$$Ri + L \frac{di}{dt} + \frac{1}{C} \int_0^t i(\tau) d\tau + v_c(0) = 0$$

 $L \frac{d^2i}{dt^2} + R \frac{di}{dt} + \frac{1}{C} i = 0$

Example 2: Underdamped

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0$$

$$\frac{d^2 i}{dt^2} + 6 \frac{di}{dt} + 25i = 0$$

Recall

$$\frac{d^2 x(t)}{dt^2} + 2\alpha \frac{dx(t)}{dt} + \omega_o^2 x(t) = 0$$

Damping Coefficient:

$$\alpha = \frac{R}{2L} = 3$$

Resonant Frequency:

$$\omega_o = \frac{1}{\sqrt{LC}} = 5$$

$$\alpha < \omega_o$$



underdamped

Example 2: Underdamped

$$\frac{d^2 i}{dt^2} + 6 \frac{di}{dt} + 25i = 0$$

Characteristic equation: $s^2 + 6s + 25 = 0$

Roots: $\lambda_1, \lambda_2 = -\alpha \pm j\sqrt{\omega_o^2 - \alpha^2}$

$$\underbrace{\lambda_1 = -3 + j4 \quad \lambda_2 = -3 - j4}$$

Complex



Underdamped
Response

$$i(t) = B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

Example 2: Underdamped

$$\star i(t) = B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

$$i(0) = B_1 = i_L(0) = 4$$

$$\textcircled{v} \frac{di(t)}{dt} = -3B_1 e^{-3t} \cos(4t) - 4B_1 e^{-3t} \sin(4t) \\ - 3B_2 e^{-3t} \sin(4t) + 4B_2 e^{-3t} \cos(4t)$$

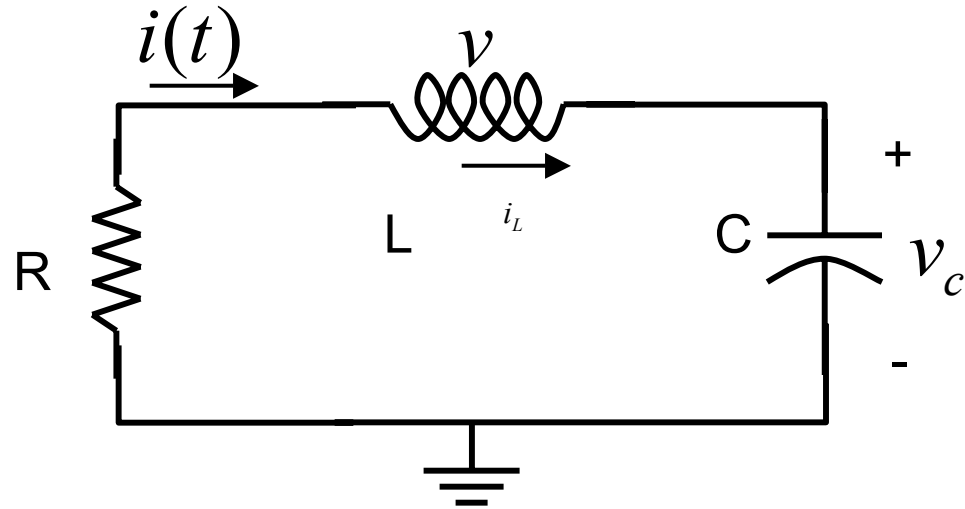
$$\frac{di(0)}{dt} = -3B_1 + 4B_2$$

Example 2: Underdamped

KVL

$$Ri + L \frac{di}{dt} + v_c = 0$$

↳
$$\frac{di(0)}{dt} = -\frac{R}{L}i(0) - \frac{v_c(0)}{L}$$



$$\frac{di(0)}{dt} = -24 + 4 = -20 \quad \text{from circuit}$$

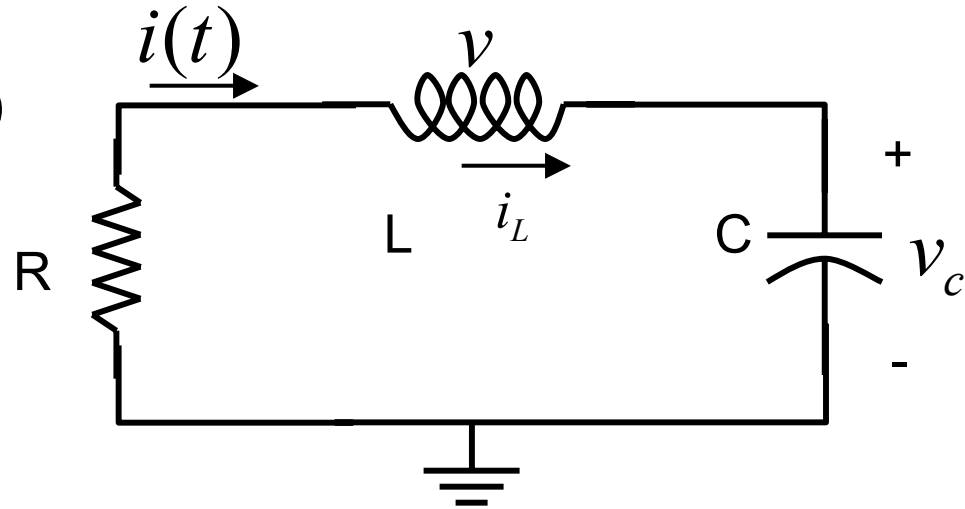
$$\frac{di(0)}{dt} = -3B_1 + 4B_2 = -20 \quad \rightarrow \quad \begin{cases} B_2 = -2 \\ B_1 = 4 \end{cases}$$

from differential equation

$$i(t) = 4e^{-3t} \cos(4t) - 2e^{-3t} \sin(4t)$$

Example 2: Underdamped

Find the capacitor voltage for $t > 0$



$$v_c(t) = B_1 e^{-3t} \cos(4t) + B_2 e^{-3t} \sin(4t)$$

$$v_c(0) = B_1 = -4$$

$$\frac{dv_c(0)}{dt} = -3B_1 + 4B_2 = \frac{i(0)}{C} = 100 \quad \longrightarrow \quad B_2 = 22$$

$$v_c(t) = -4e^{-3t} \cos(4t) + 22e^{-3t} \sin(4t)$$