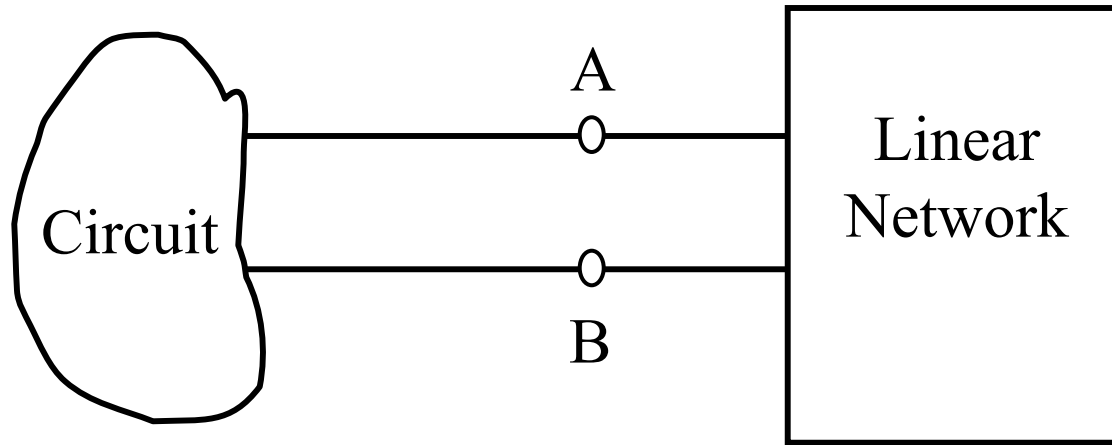


ECSE 210: Circuit Analysis

Lecture #29:

Two-Port Networks

Single-Port Network

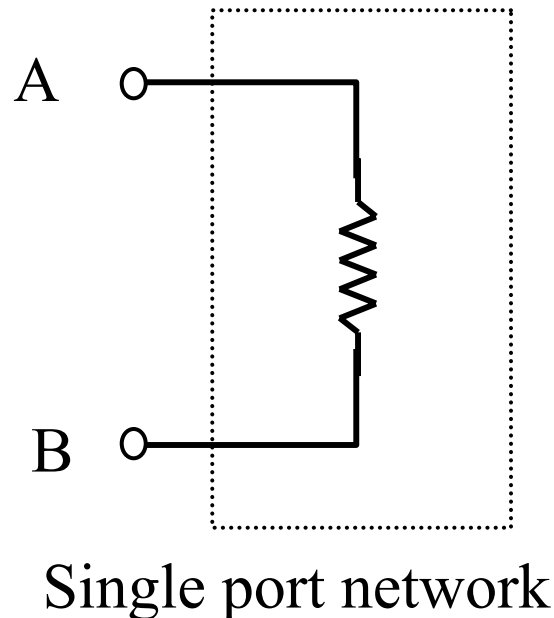


The linear network is connected to the circuit through a *single pair of terminals* (A-B), called a **port**.

→ Network is called a **single-port** or **one-port** network.

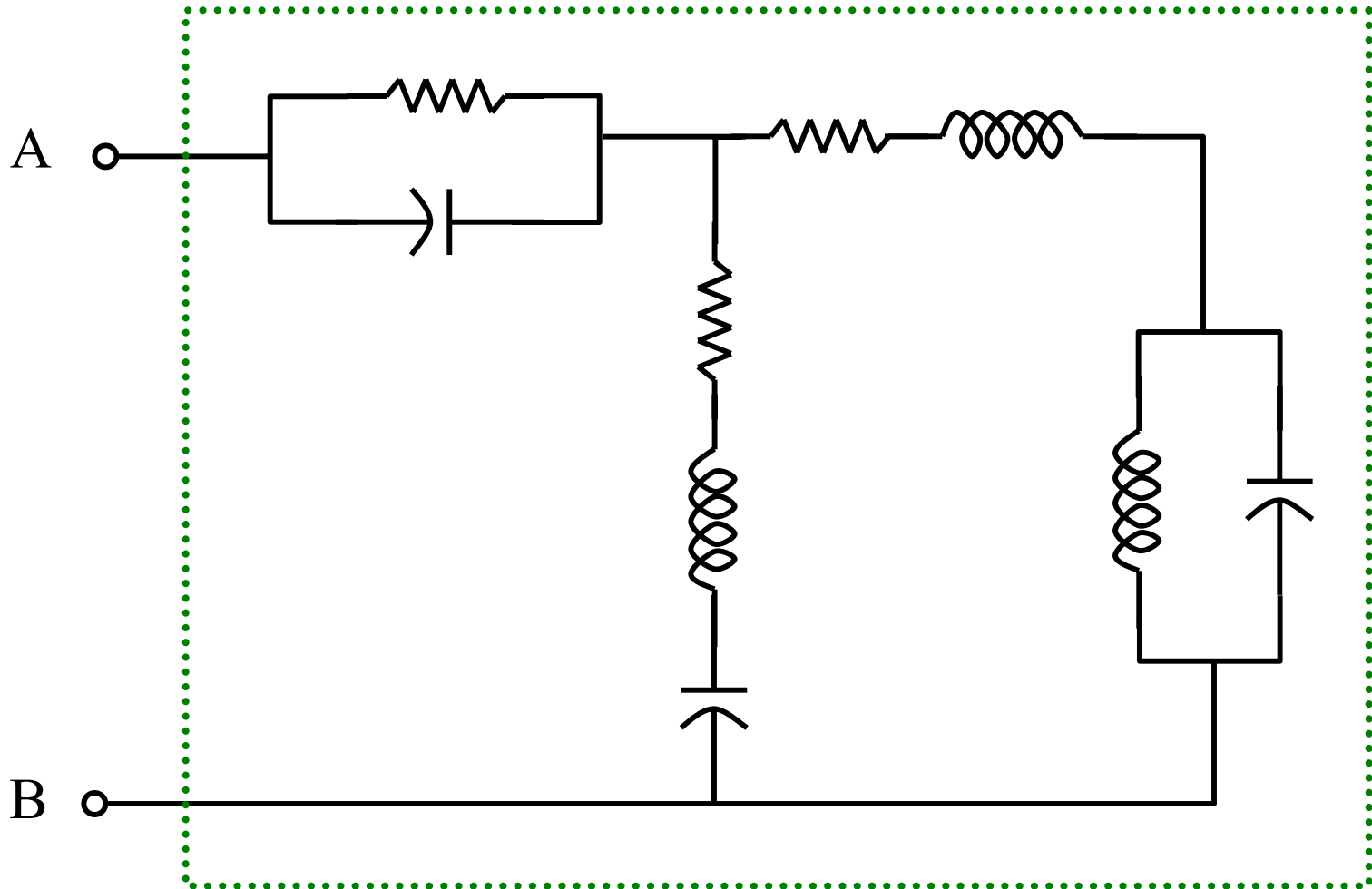
Example: Two Port Network

- A single-port network may consist of a single circuit element (e.g., R, L or C) or a complex interconnection of such elements.

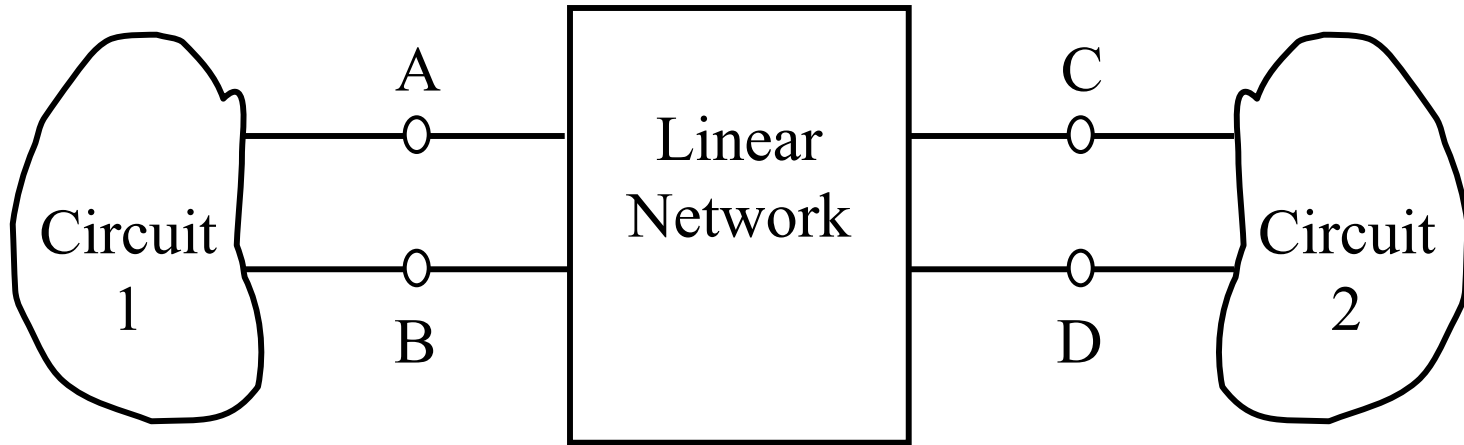


Example: Single Port Network

Single port network



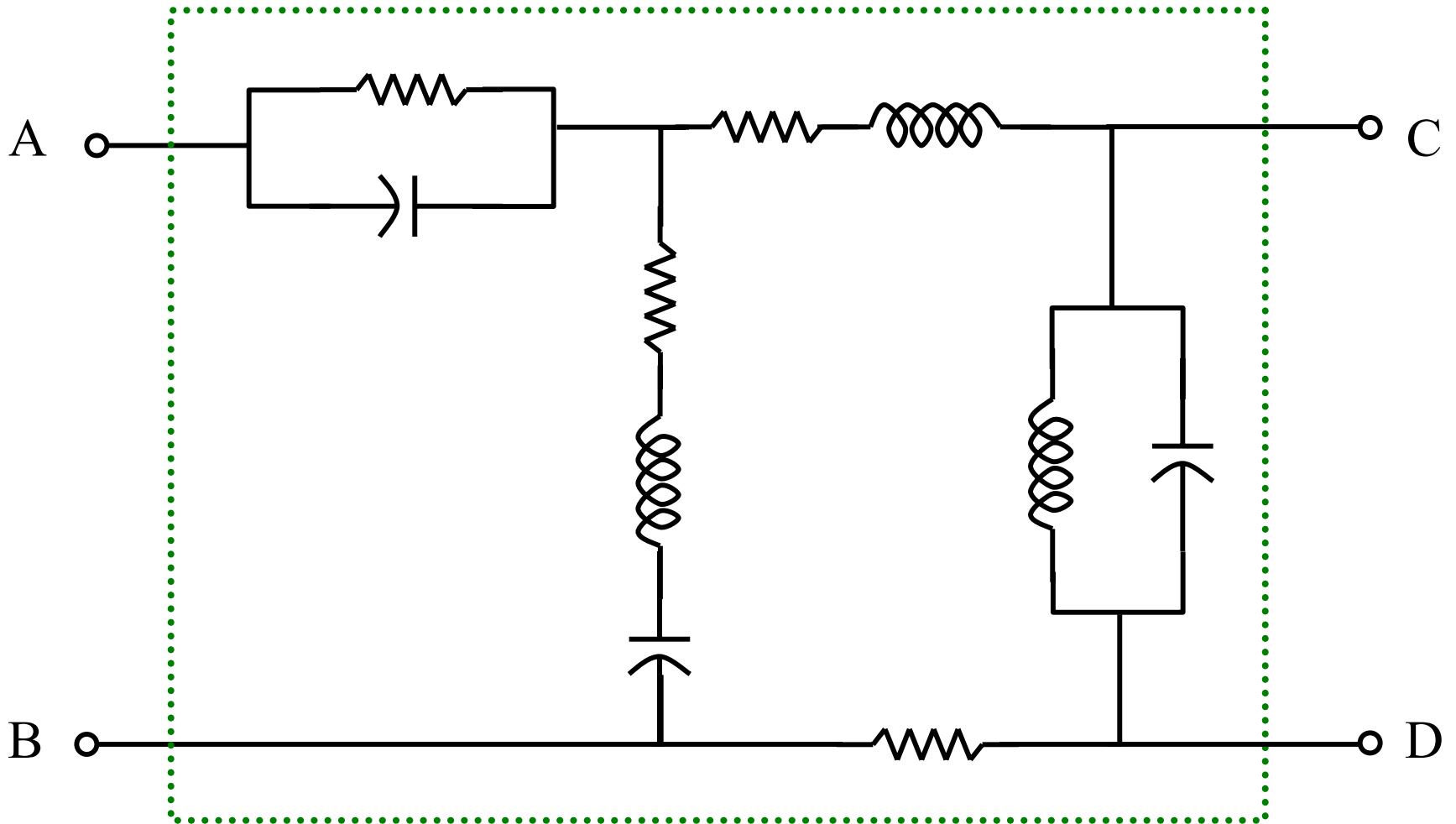
Two-Port Network



- This linear network is called a *two-port* network.
- Generally, the terminal pairs or *ports* are identified as:
 - A-B: *input port* of the linear network;
 - C-D: *output port* of the linear network.

Example: Two-Port Network

Two-port network

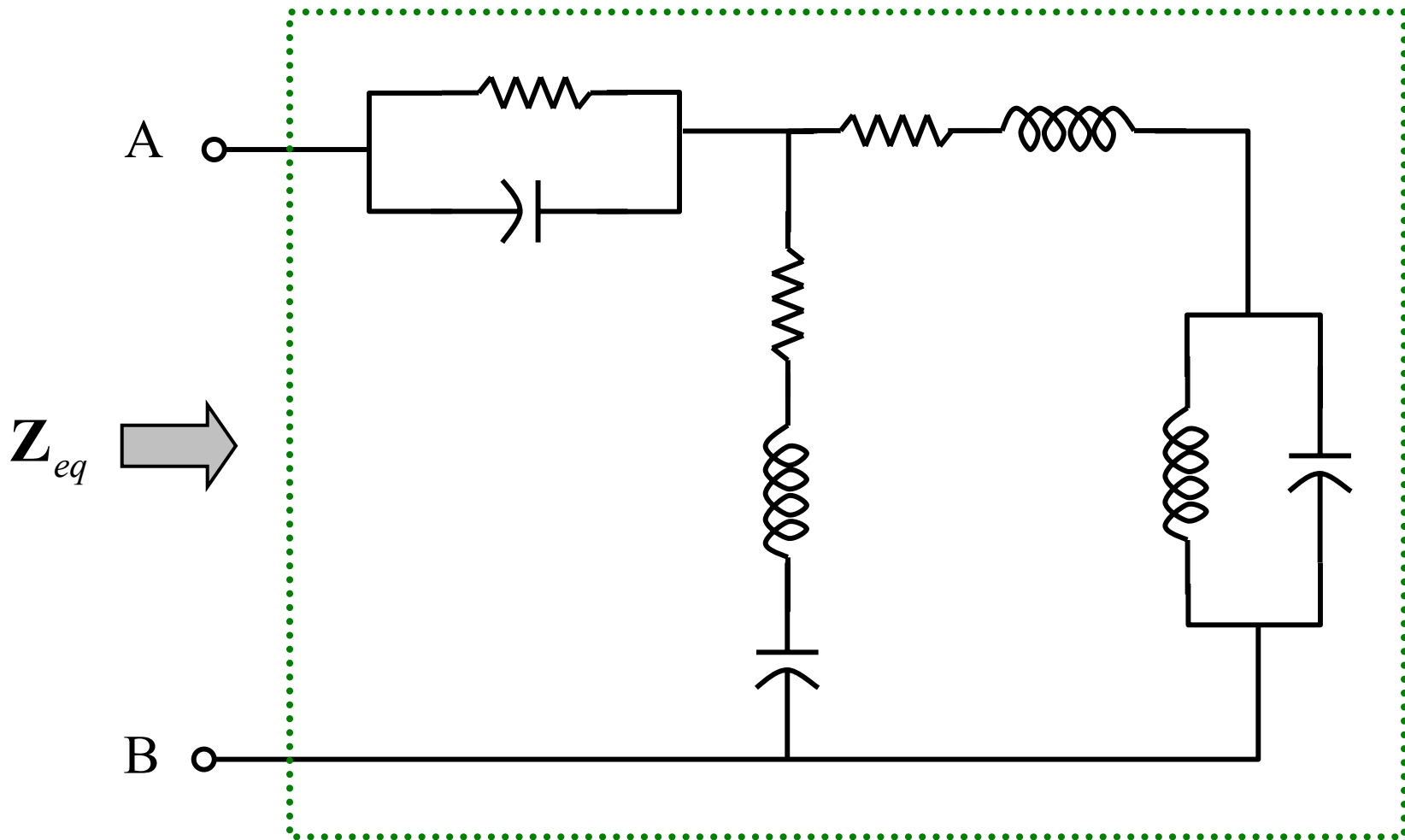


Two-Port Networks

- Most practical circuits and systems have at least two ports (an input and an output).
- Two-ports are used extensively in the modeling of many electronic devices and system components:
 1. Transistors and OpAmps
 2. Transformers and transmission lines
- In general, a two-port linear network may contain any combination of *R, L and C circuit elements, op-amps and controlled sources*.
 - * *However, independent sources are excluded.*
- The operation of a two-port network is fully described by the voltage-current relationships at the two ports, called the **two port-parameters**.

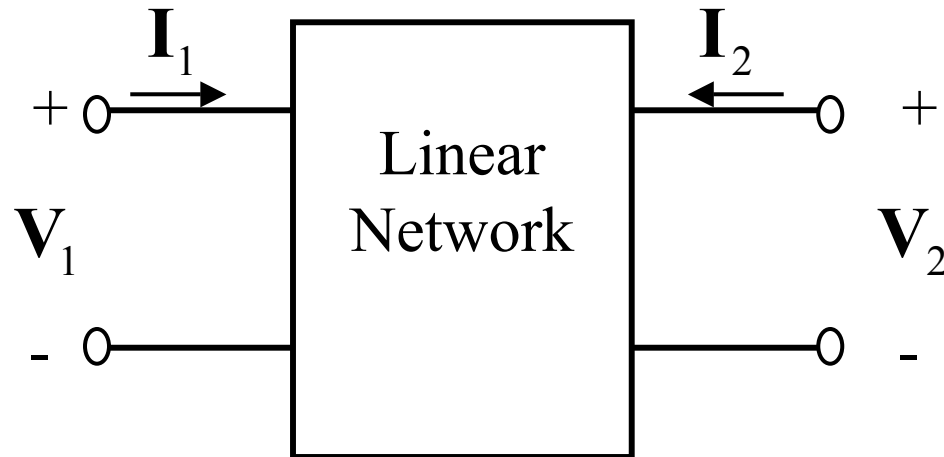
Two-Port vs. Single-Port Parameters

→ The **driving point impedance or admittance** (input impedance or admittance) completely describe the circuit.



Two-Port Admittance Parameters

→ Commonly referred to as the *Y-parameters*.



→ Note the voltage polarities, and current directions.

→ Using the principle of superposition we get:

$$\mathbf{I}_1 = y_{11} \mathbf{V}_1 + y_{12} \mathbf{V}_2$$

$$\mathbf{I}_2 = y_{21} \mathbf{V}_1 + y_{22} \mathbf{V}_2$$

Y- Parameters

$$\begin{aligned} \mathbf{I}_1 &= y_{11} \mathbf{V}_1 + y_{12} \mathbf{V}_2 \\ \mathbf{I}_2 &= y_{21} \mathbf{V}_1 + y_{22} \mathbf{V}_2 \end{aligned} \quad \longrightarrow \quad \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

- y_{ij} are complex constants of proportionality with units of siemens (S).
- Two equations describe the two-port operation.
- Once y_{11} , y_{12} , y_{21} , y_{22} are known, the input/output operation of the two-port network is *completely* defined.
- y_{ij} are the **admittance parameters** or Y-parameters.
- The Y-parameter matrix is:

$$\mathbf{Y} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix}$$

Y- Parameters

$$\begin{aligned} \mathbf{I}_1 &= y_{11} \mathbf{V}_1 + y_{12} \mathbf{V}_2 \\ \mathbf{I}_2 &= y_{21} \mathbf{V}_1 + y_{22} \mathbf{V}_2 \end{aligned} \quad \Rightarrow \quad \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

$$\mathbf{V}_2 = 0 \quad \Rightarrow \quad \mathbf{I}_1 = y_{11} \mathbf{V}_1 \quad \Rightarrow \quad y_{11} = \left. \frac{\mathbf{I}_1}{\mathbf{V}_1} \right|_{\mathbf{V}_2=0}$$

$$\mathbf{V}_1 = 0 \quad \Rightarrow \quad \mathbf{I}_1 = y_{12} \mathbf{V}_2 \quad \Rightarrow \quad y_{12} = \left. \frac{\mathbf{I}_1}{\mathbf{V}_2} \right|_{\mathbf{V}_1=0}$$

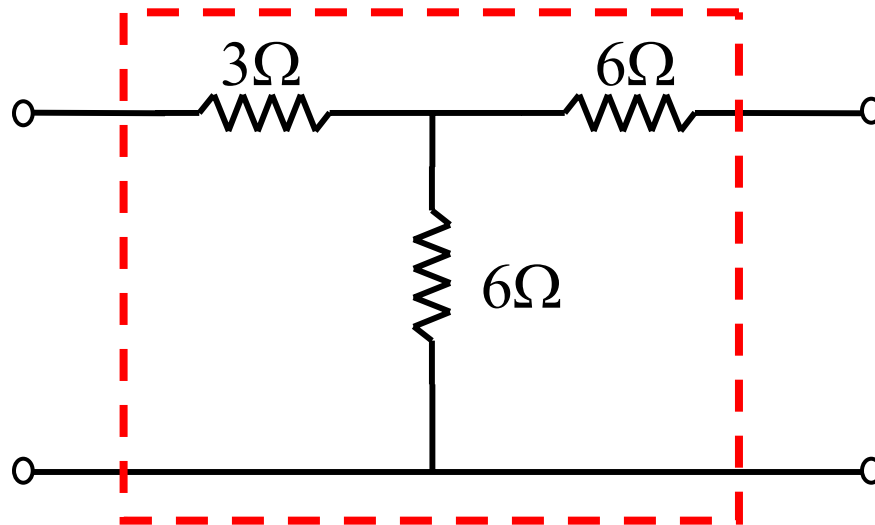
$$\mathbf{V}_2 = 0 \quad \Rightarrow \quad \mathbf{I}_2 = y_{21} \mathbf{V}_1 \quad \Rightarrow \quad y_{21} = \left. \frac{\mathbf{I}_2}{\mathbf{V}_1} \right|_{\mathbf{V}_2=0}$$

$$\mathbf{V}_1 = 0 \quad \Rightarrow \quad \mathbf{I}_2 = y_{22} \mathbf{V}_2 \quad \Rightarrow \quad y_{22} = \left. \frac{\mathbf{I}_2}{\mathbf{V}_2} \right|_{\mathbf{V}_1=0}$$

Example

→ Find the Y-parameters for the two-port below.

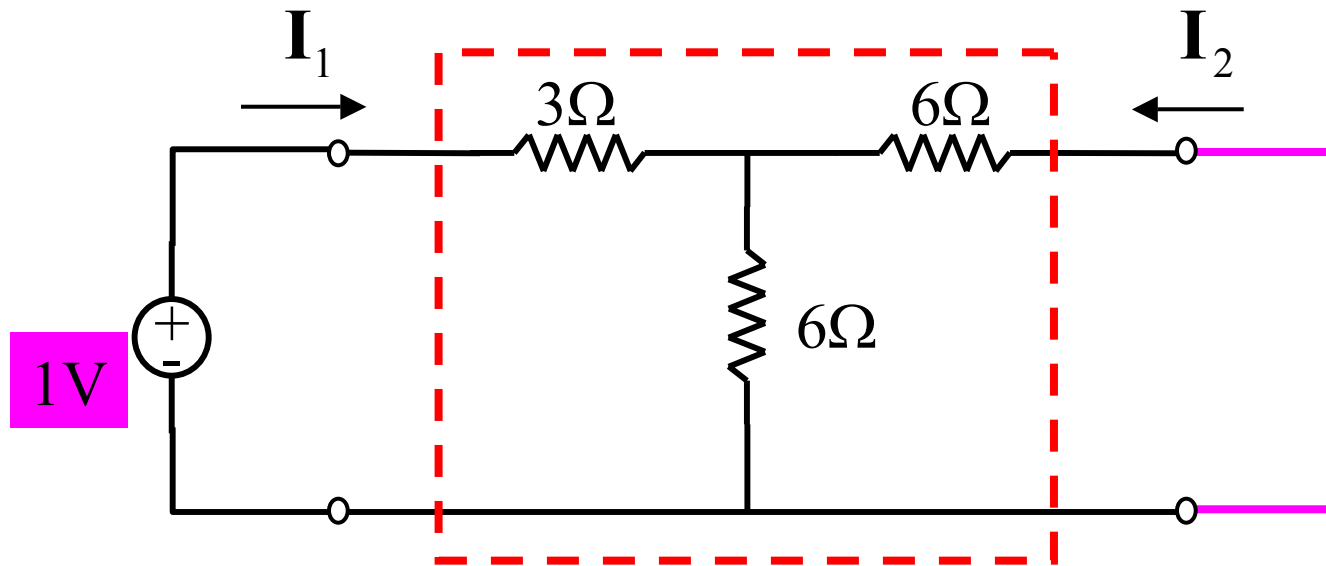
$$\begin{aligned} \mathbf{I}_1 &= y_{11} \mathbf{V}_1 + y_{12} \mathbf{V}_2 \\ \mathbf{I}_2 &= y_{21} \mathbf{V}_1 + y_{22} \mathbf{V}_2 \end{aligned} \quad \rightarrow \quad \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$



Example

→ Y-parameters can be found “experimentally”

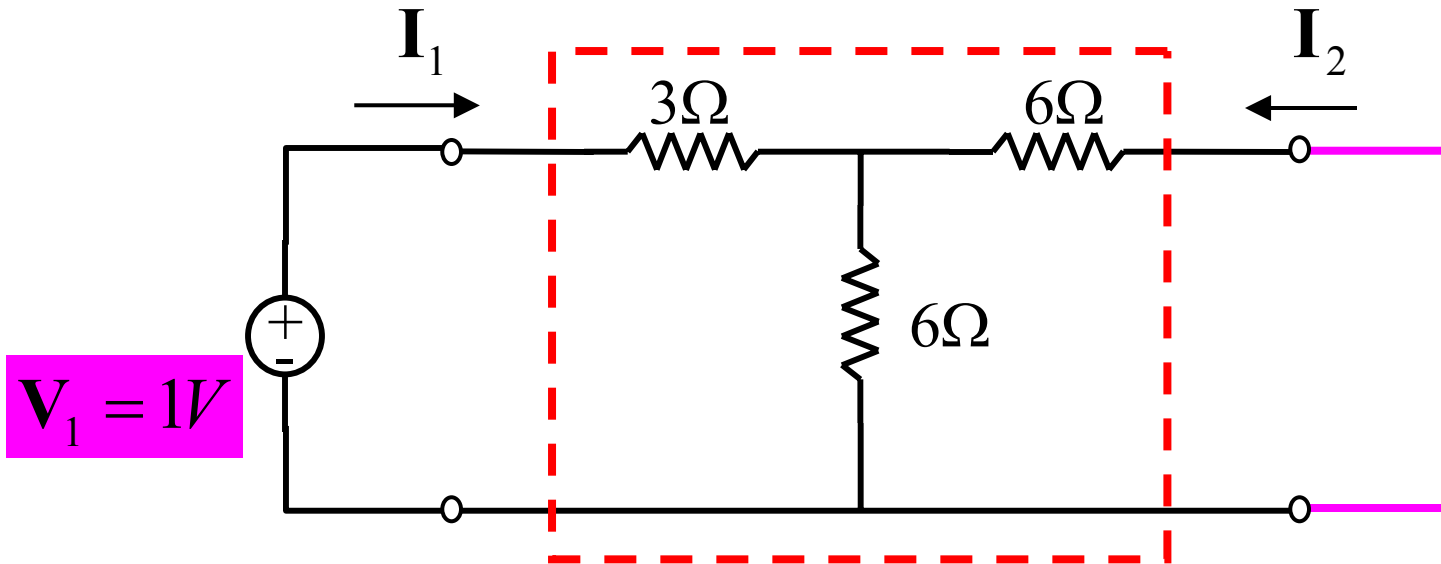
$$\begin{aligned} \mathbf{I}_1 &= y_{11} \mathbf{V}_1 + y_{12} \mathbf{V}_2 \\ \mathbf{I}_2 &= y_{21} \mathbf{V}_1 + y_{22} \mathbf{V}_2 \end{aligned} \quad \Rightarrow \quad \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$



From the above equations: $\mathbf{I}_1 = y_{11}(1V)$

$\mathbf{I}_2 = y_{21}(1V)$

Example



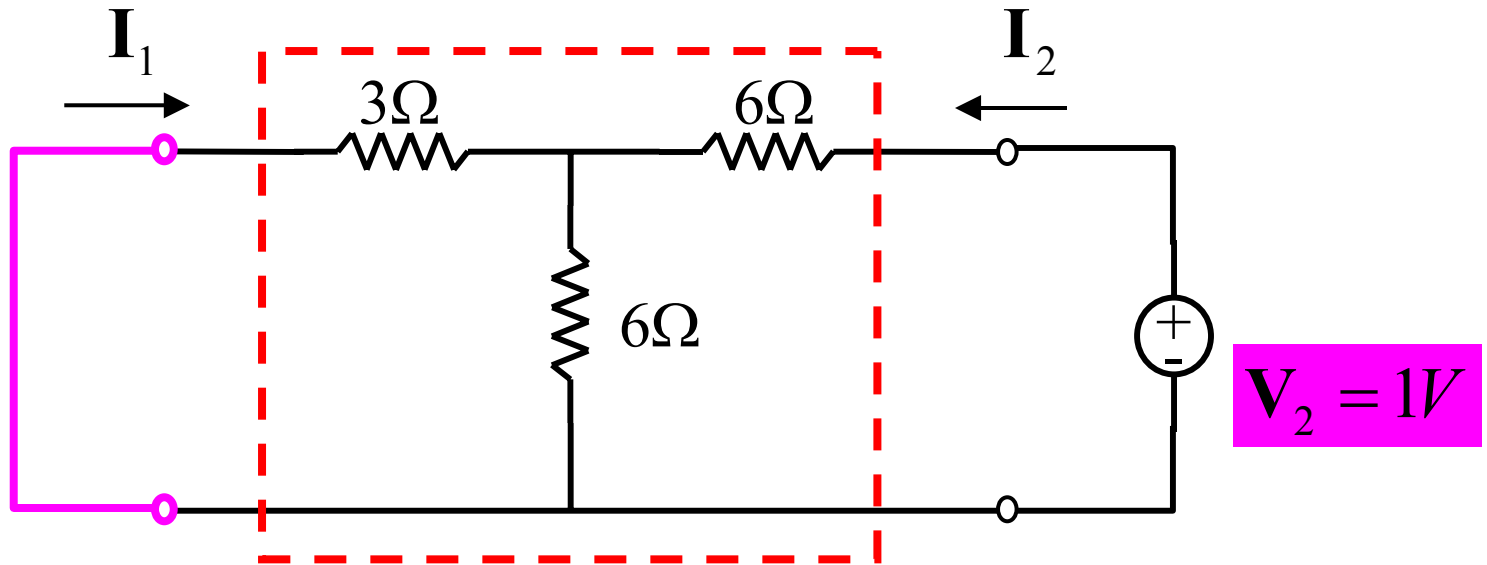
$$V_1 = (3 + 6 \parallel 6)I_1 = 6I_1$$

$$y_{11} = \left. \frac{I_1}{V_1} \right|_{V_2=0} = \frac{1}{6} S$$

$$I_2 = -\frac{6}{6+6}I_1 = -\frac{1}{12}V_1$$

$$y_{21} = \left. \frac{I_2}{V_1} \right|_{V_2=0} = -\frac{1}{12} S$$

Example



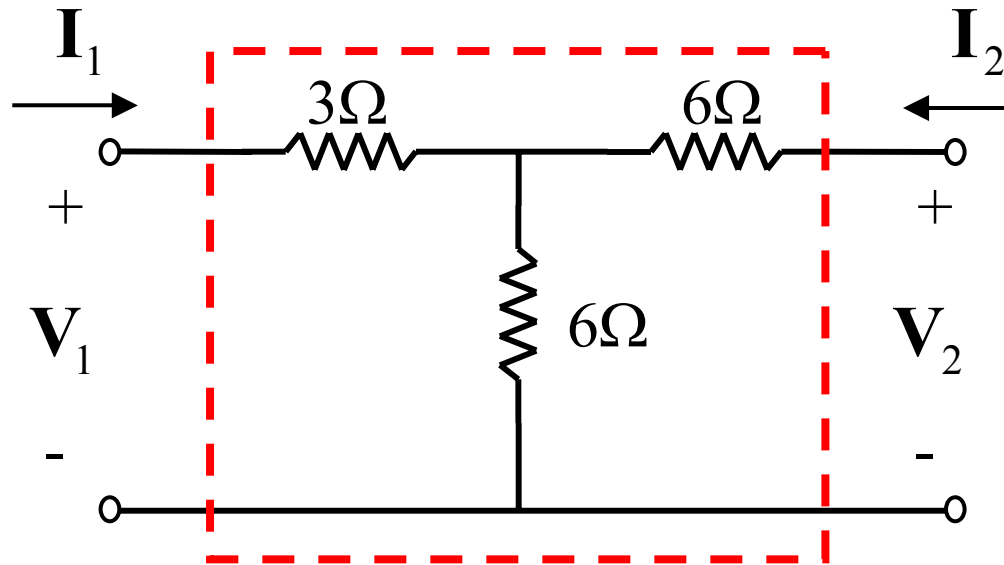
$$V_2 = (6 + 3 \parallel 6)I_2 = 8I_2$$

$$y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0} = \frac{1}{8} S$$

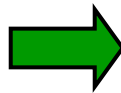
$$I_1 = -\frac{6}{6+3}I_2 = -\frac{1}{12}V_2$$

$$y_{21} = \frac{I_1}{V_2} \Big|_{V_1=0} = -\frac{1}{12} S$$

Example



$$\mathbf{I}_1 = \frac{1}{6} \mathbf{V}_1 - \frac{1}{12} \mathbf{V}_2$$
$$\mathbf{I}_2 = -\frac{1}{12} \mathbf{V}_1 + \frac{1}{8} \mathbf{V}_2$$



$$\begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{6} & -\frac{1}{12} \\ -\frac{1}{12} & \frac{1}{8} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

Example 2

π -network

