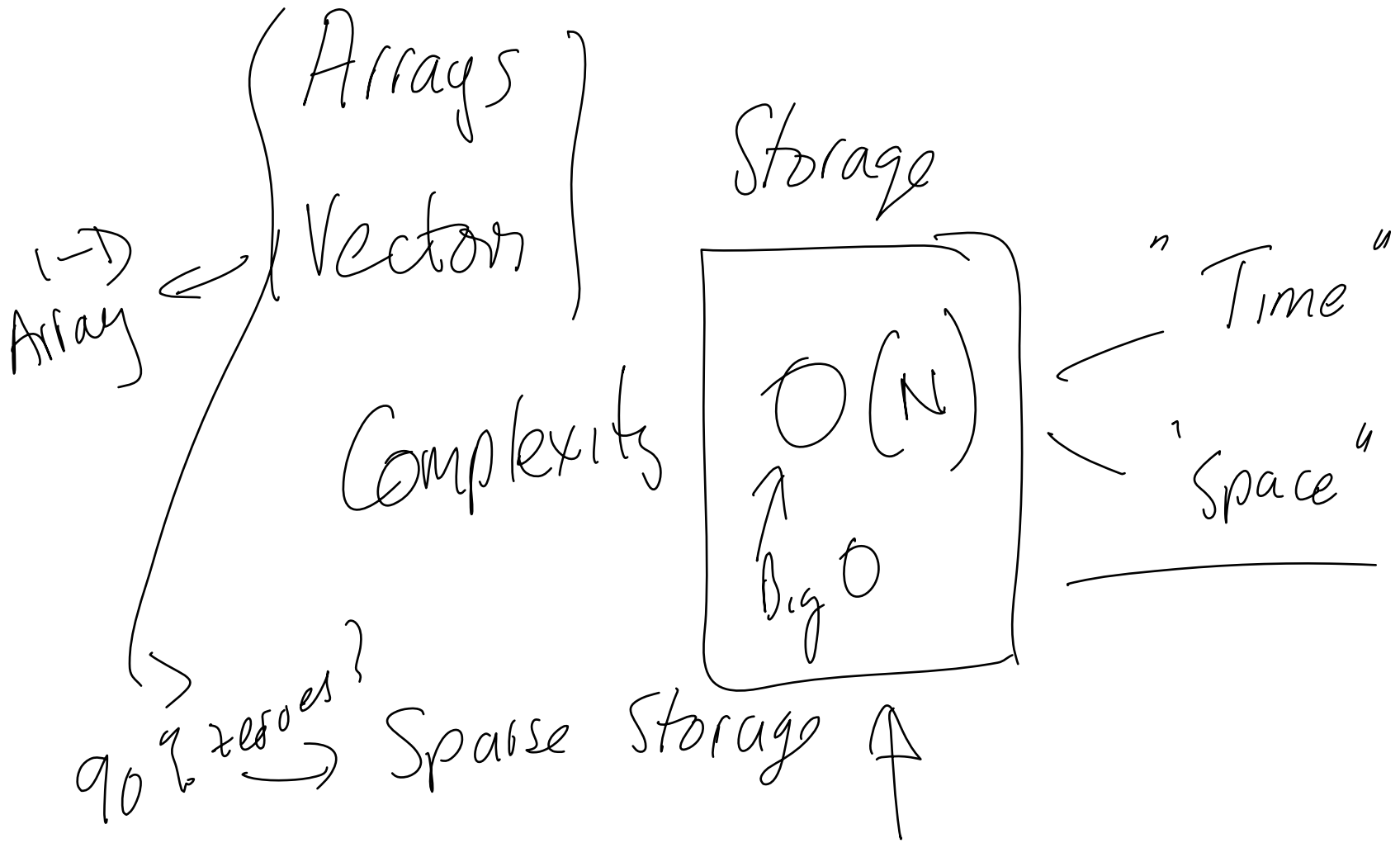


ECSE-322

16 January 2008

Lecture 6

Hashing and Searching



Hashing

- There is a need to store data which, for most of the domain, is zero.
- There is a requirement to minimize the space taken by the non-zero elements.
- There is a requirement to minimize the time to find a data item (if it exists) (see the previous algorithm)

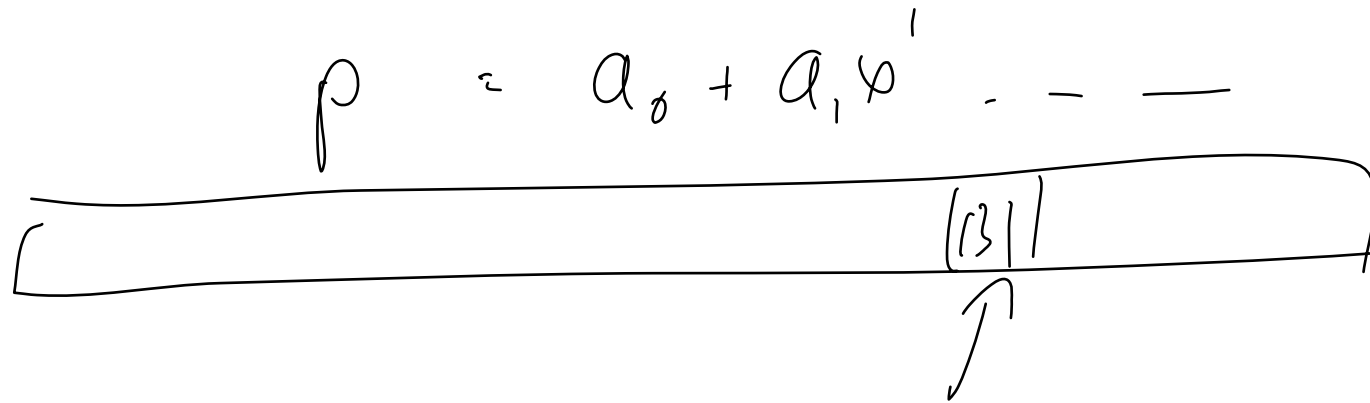
$O(N)$

Hashing

- With the previous structure how do you answer the question:

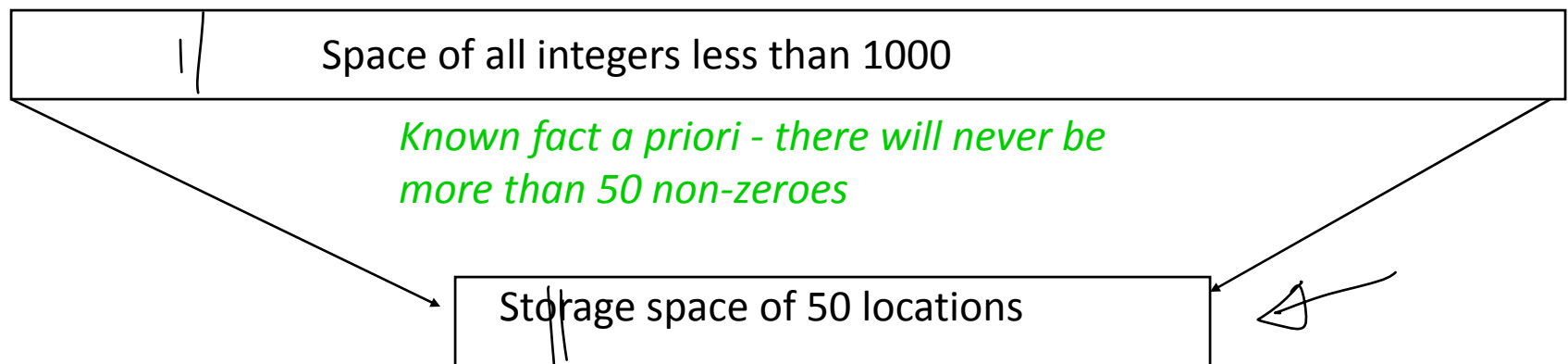
“Does the coefficient of x to the 131 exist?”

- We need a method of directly accessing the storage location for the coefficient of 131...



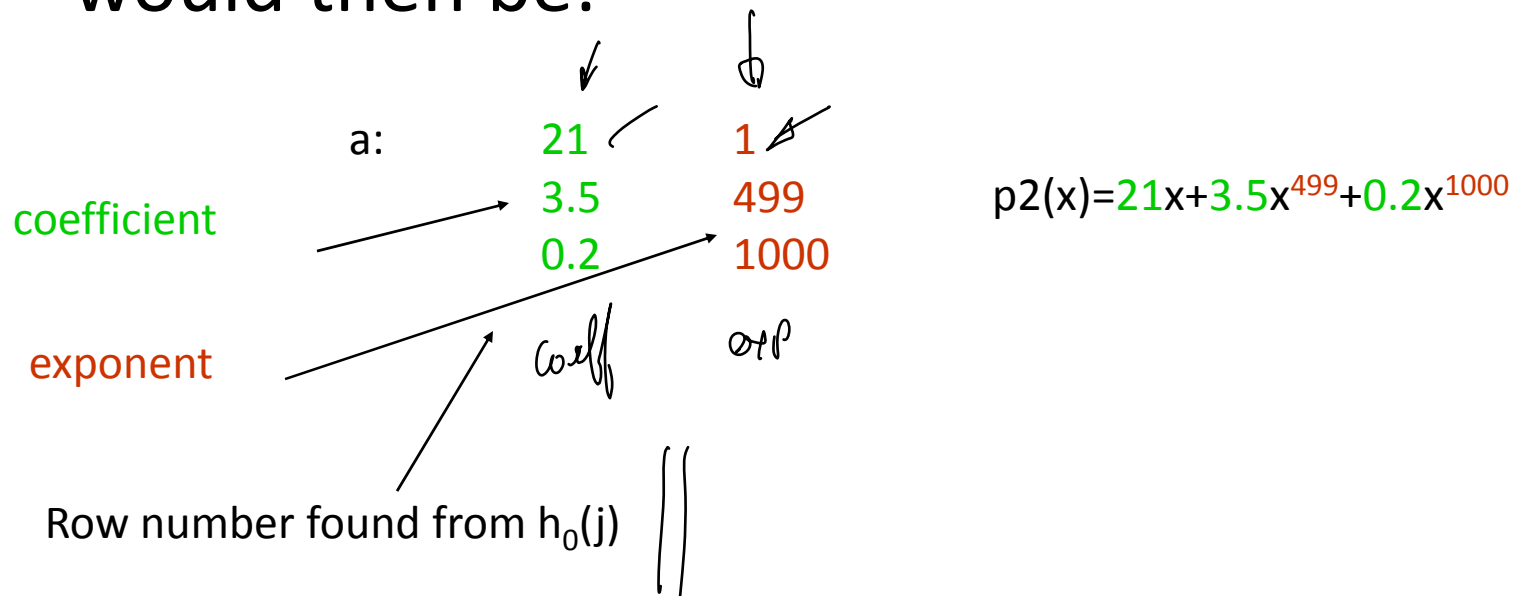
Hashing

- Idea:
 - Map the data domain into a smaller space such that each location in the original space has a defined (not unique) position in the new space..



Hashing

- The storage of the polynomial in an array would then be:



Hashing

- How is a coefficient retrieved in this system?

Step 1: compute the array index by using the function $h_0(j)$

Step 2: (compare the exponent in the array location to determine if it is the one wanted)

Step 3: extract the coefficient from the array.

|| $\frac{131}{499} + 1 = 1$

(31

Hashing

- What happens if we want the coefficient of x^{502} ?
 - *The process fails at step 2 because the coefficient ~~6~~ doesn't exist!*

$$\frac{502}{499} \approx 1 \quad \text{②}$$

Hashing

- How does this all work?
 - Assume that we have randomly arriving data but we know there is a maximum of M items...
 - Set up an array of length M (big enough to hold all the data)
 - Assume there is a key associated with each element (doesn't have to be a number - in the example it is the exponent)

Hashing

- Using the key, e , define a mapping function such that an index, I , in the range $0 \leq I \leq M$ is created...

– e.g.

$$- h_0(e) = e \bmod M + 1$$

$M+1$

$$\frac{M+1}{1}$$

$$I \rightarrow M$$

Example

Consider the polynomial:

$$p_2(x) = 3.576x^{131} - 0.106x^{337} + 1.03x^{858} - 5.664x^{945}$$

Store it as a linear array:

Coefficient	location in array (key)
0	1
0	2
...	...
3.576	131
0	132
...	...
-0.106	337
...	...
1.03	858
...	...
-5.664	945

Set $M = 6$ (size of available space)

Apply hashing function
 $h_0(e) = e \bmod M + 1$

Coeff.	Exponent
1.030	858
-0.106	337
0.000	0
-5.664	945
0.000	0
3.576	131

Example

M=6 gives:

Coeff.	Exponent
1.030	858
-0.106	337
0.000	0
-5.664	945
0.000	0
3.576	131

M=5 gives

Coeff.	Exponent
-5.664	945
3.576	131
-0.106	337
1.030	858
0.000	0

The order the elements appear in the array depends on the hashing function - *not their original order or the order in which they were received.*

Hashing

- What could go wrong?

Hashing

- What could go wrong?
 - More than one element could map to the same place

a COLLISION occurs

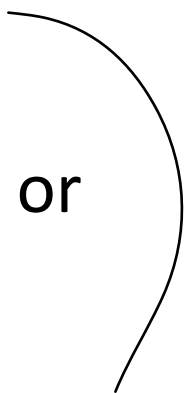
- How can this be solved?

Hashing - Resolving Collisions

- If a collision occurs - use a second hashing function.
- If another collision occurs - use a third
 - Generate a family of hashing functions!

$$h_k(e), k = 0, 1, \dots$$

Hashing - Resolving Collisions

- The process of storage becomes:
 - 1. Apply the hashing function ✓
 - 2. Check if the location computed is empty ✓
 - 3. If it is, store the data element in it ✓
 - 4. If it is not empty, apply the next hashing function and repeat from step 2 until success or there are no hashing functions left.
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Linear Hashing

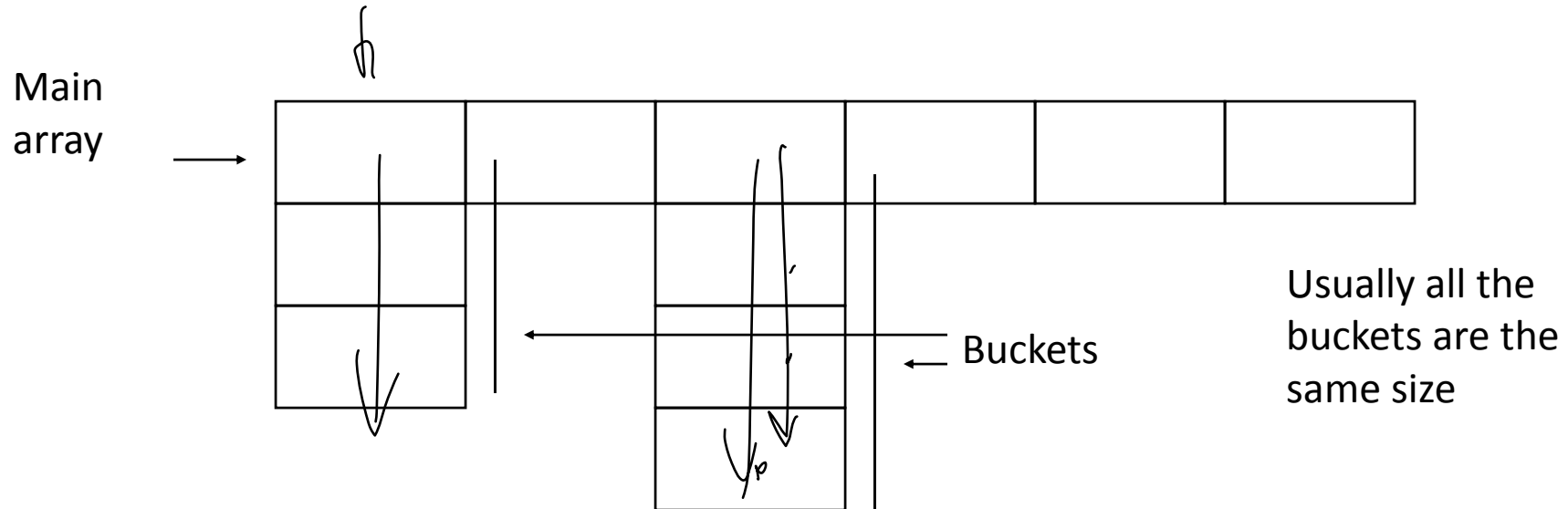
- A simple family of hashing functions

$$h_k(e) = (h_0(e) + k) \bmod M$$

- The implication is that, if the desired location is not empty, the next location is tried.
- This family of functions will wrap around in the storage space.
- Each attempt to store is known as a *probe*
 - Thus if the first function results in a collision and the second function is successful, there are 2 probes.

Bucket Hashing

- An alternate approach to resolving collisions is to add an array at each storage location (a *bucket*). In a collision, the next location in the bucket is used..



Retrieving Data

- Basically use the same process as storing data
 - use the hashing function..
- Problem:
 - If a collision occurred in storing data, then it may not be stored where you expect it.
 - Each retrieved item must be checked to see if it is the right one.

Retrieving Data

- E.g.
 - If we want X and the hashing function points to a_i , it should not be assumed that a_i contains X .
 - If a collision occurred in storing X , it will have been stored elsewhere.
 - Thus the keys of a_i and X must be checked to see if they match
 - If they do not match... *Rehash with the next function.*

Retrieving Data

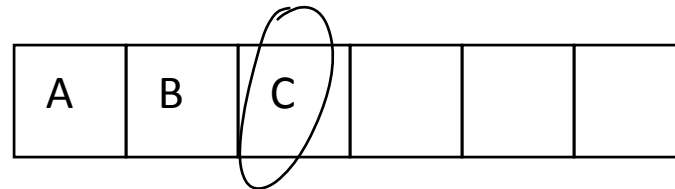
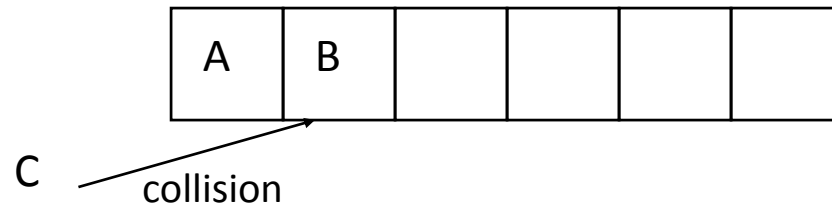
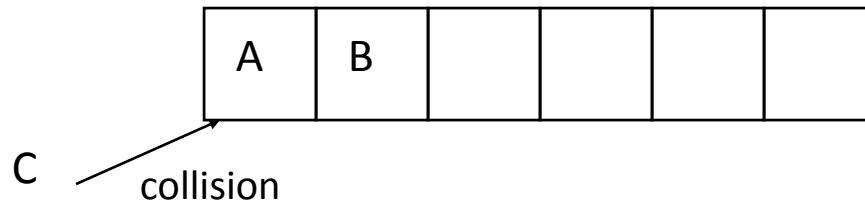
- How do we know if X exists?
- If a_i is not empty we cannot prove X does not exist until M attempts have been made.
- What happens if an item was deleted *after* X was stored?

|

Retrieving Data

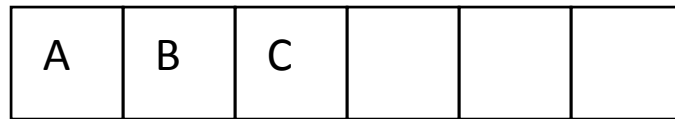
- Example

To store C:

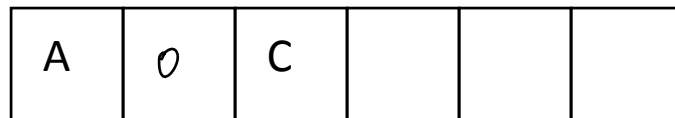


C stored after 2 collisions, i.e. 3 probes

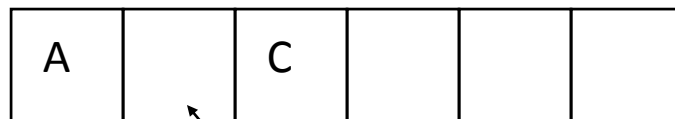
Retrieving Data



Now delete B..







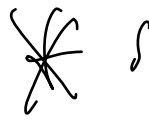
Retrieve C..



Algorithm fails when it reaches here..

How can C ever be found?

Performance of Hashing

- Rough calculations based on bounds..
 - Place N elements in a large array M ($N \ll M$) - assume few or no collisions 
 - One fetch-hash-store cycle per item 
 - $O(N)$  |
 - Place N elements in an array M ($N=M$) with maximum collisions 
 - Average element placed after $N/2$ attempts
 - $O(N^2)$ 

Searching

- Data is only stored so that it can be found.
- In a hashing system, data is retrieved by following the hashing function.
- What if the hashing functions are not known or the data was stored unhashed?